

- Note 1. The example shows a three-phase, 200-V AC input to the Servo Driver for the main circuit power supply. Be sure to provide a power supply and wiring conforming to the power supply specifications for the Servo Driver in use.
- Note 2. Incorrect signal wiring can cause damage to Units and the Servo Driver.
- **Note** 3. Leave unused signal lines open and do not wire them.
- Note 4. Connect terminals and wiring marked with an asterisk (\*) when using an Absolute Encoder.
- **Note** 5. This wiring diagram is an example of X-axis wiring only. For two-axis control, the external input and Driver wiring must be connected for the Y axis in the same way.
- **Note 6.** Always short NC I/O terminals that are not used among the Motion Control Unit's I/O connectors.
- Note 7. Make the setting so that the Servo can be turned ON and OFF with the RUN signal.