







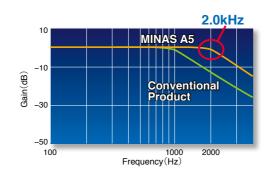


2.0 kHz frequency response

Example application Semiconductor production equipment, packaging, etc.

Achieves the industry's fastest frequency response of 2.0 kHz.

Operation speed up by new developed LSI and high responsible control. By the industry's fastest speed and positioning response, a highly advanced system can be created. What's more, the shorter response delay will realize an to extremely lower vibration.





20 bits/revolution, 1.04 million pulses

Example application Machine tools, textile machinery, etc.

Ensures smoother operation and reduced vibration at stopping.

Ensures accurate positioning in a short time.

New proprietary signal processing technology achieves 1.04 million pulses with a 20-bit encoder.

Conventional A4 Series 131,072 p/r 130,000 pulses





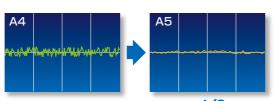
Low cogging torque (Excluding MSMD, MHMD type)

Example application Semiconductor production equipment, textile machinery, etc.

For the industry's most stable speed and lowest cogging

We've achieved the industry's lowest cogging by minimizing the pulse width by a new design incorporating a 10-pole rotor for the motor and a magnetic field parsing technique.

Positioning and stability are greatly improved by the minimal torque variation. This results to improved speed stability and positioning of motor rotation.



Vibration reduced to only 1/8



The input/output pulse 4 Mpps

Example application Semiconductor production equipment, machine tools, etc.

Accommodates the industry's leading positioning resolution commands (with pulse train commands).

The command input and feedback output operate at the high speed of 4 Mpps. Accommodates high-resolution and high-speed operation, including standard full closed operation.





2 Smart



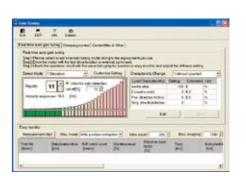
Highly Functional Real-time Auto-Gain Tuning

Example application Semiconductor production equipment, food processing machinery, etc.

Incorporates the industry's quickest high-performance real-time auto-gain tuning featuring simple setup.

After installation, tuning will be completed automatically after several operations. When the response is adjusted, **simple tuning** is supported with a change of one parameter value. Use of the gain adjustment mode in the setup support software contributes to optimum adjustment. The built-in auto vibration suppression function reduces equipment damage. Appropriate modes are provided for various machines such as vertical axis machines and high friction machines with belts.

This makes it possible to perform simple optimal adjustments simply by selecting the mode and stiffness.



Nocth filters

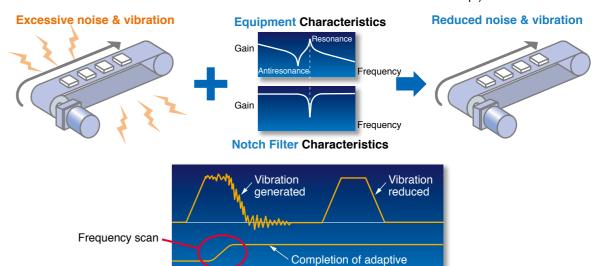
Manual/Auto Notch Filters

Example application Semiconductor production equipment, food processing machinery, etc.

Equipped with auto-setting notch filters for greater convenience.

Now there is no need to measure troublesome vibration frequencies. Our notch filters automatically detect vibration and provide simple auto-setting. These notch filters greatly reduce noise and vibration caused by equipment resonance and respond quickly

during operation. The A5 Series features an industry-largest total of four notch filters with setup frequencies of 50 to 5,000 Hz. This approach enables depth adjustment within this frequency range. (Two of the filters share the auto set-up.)





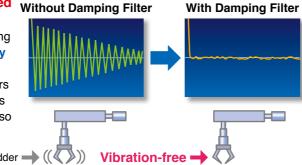
Manual/Auto Damping Filter

Example application

Chip mounters, food processing machinery, robots, general production machinery, etc.

Equipped with a damping filter featuring simplified Without Damping Filter automatic setup.

The setup software features automatic setup of the damping filter. This filter removes the natural vibration frequency component from the command input, greatly reducing vibration of the axis when stopping. The number of filters has been increased to four from the conventional two filters (two for simultaneous use). The adaptive frequency has also been significantly expanded from 1 to 200 Hz.





Motion Simulation

Example application General production machinery, etc.

Equipped with a simplified machine simulation function.

The setup software uses frequency response data acquired from the actual machine. In addition, it features a machine simulation function for performing simulated operation. This allows you to easily confirm the effects of gain and various filters without adjusting the actual equipment.







New Structure/ Innovative Core/ Innovative Encoder (Excluding MSMD, MHMD ty

Example application Robots, chip mounters, general production machinery, etc.



novative encode

Featuring significantly reduced weight and a more compact motor

We've developed new designs for both compact motors and large motors. The new design used for the core has succeeded in compact. The addition of an innovative compact encoder has contributed to a 10% to 25% (1 to 6 kg) reduction in motor weight in the 1 kW and larger class when compared with conventional motors.



	[Examples for MSM or MDM]						
		A4 Series	A5 Series	Weight Reduction			
V	MSM 1kW	4.5kg	3.5kg	▲ 1kç			
-	MSM 2kW	6.5kg	5.3kg	▲1.2kç			
	MDM 1kW	6.8kg	5.2kg	▲1.6kg			
	MDM 2kW	10.6kg	8.0kg	▲ 2.6k@			





Complies with European Safety Standards. A5E series doesn't correspon to the safety standard.

Example application Semiconductor and LCD production equipment, etc.

Complies with the latest European safety standards.

Features non-software-based (hardware-based?) independent redundant circuitry for motor power isolation. This obviates the need for magnetic contactors to isolate the required motor in order to

accommodate low-voltage machinery commands. (The final safety compliance must be applied as



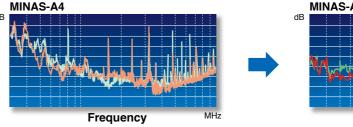
Low noise

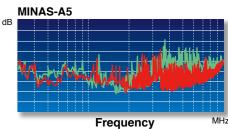
Example application

Semiconductor and LCD production equipment, etc. general production machinery for export to the European market

Complies with the European EMC Directive

By incorporating the latest circuit technology, A5 series achieves a further noise reduction of 3dB compared with the conventional A4 Series, which also features noise suppression. (The A4 Series also conforms to the EMC Directive.)





IP67 Enclosure Rating (Excluding MSMD, MHMD type

Example application Machine tools, robots, printing machines, etc.

IP67 enclosure rating for increased environmental resistance

Our improved motor seals and direct-mount connectors in the motor power supply and encoder input-output areas contribute to this unit's IP67 enclosure rating.



IP67

Protection against dust

· Protected against dust penetration when in full contact

Protection against water

 Protection against temporary immersion in water

IP65: MSMD, MHMD series

5 Easy







PANATERM Set-up Support Software

Introducing the new PANATERM Set-up Support Software, now with many added features.

Localized in 4 languages

Choose either English, Japanese, Chinese, or Korean*-language display.

* The Korean-language version is scheduled for release in December.

Service Life Prediction

The service life prediction function considers the internal temperature for main components such as the fan and condenser. If the rated value is exceeded, an alarm is displayed. This approach prevents unexpected suspension of operation and allows for planning of systemized maintenance.

Note: The life span prediction value should be considered as a guide only.

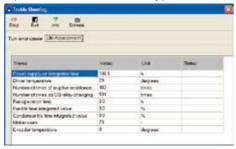
Encoder Temperature Monitor

The Encoder Temperature Monitor is a new function capable of real-time measurement of the interior temperature of the encoder, something that has been difficult to achieve in the past. It is valuable for monitoring the motor and can be used as a diagnostic in the event of a malfunction (provided with 20-bit encoder only).

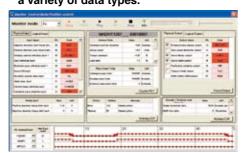
Other New Function

The software offers a wide range of convenient features including motor and driver data such as load factor, voltage, and driver temperature. Moreover, the logging function records the interface history. As well, the trial run function supports positioning with a Z-phase search and software limit as well as a non-rotating contributing factor display function.

• Service Life Prediction function (Screen shown for reference only.)



 The Data Logging function handles a variety of data types.



Other Functions

Command Control Mode (Excluding A5E Series)

- Command control mode is available for Position,
 Speed (including eight internal gears) and Torque.
- Using parameter settings, you can set up one optional command control mode or two command control modes by switching.
- With a suitable application utility, you can choose an optional command control mode.

Full closed Control (Excluding A5E Series)

You can use the AB-phase linear scale (for general all-purpose products) or the serial scale (for products with Panasonic1s exclusive format) for supported scales (see table below).

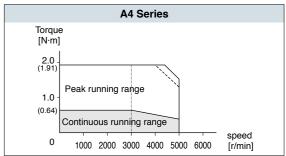
SEMI F47

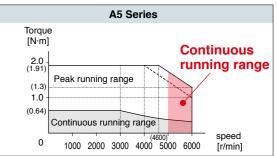
- Includes a function in compliance with the SEMI F47 standard for voltage sag immunity under no load or light load.
- Ideal for the semiconductor and LCD industries.
 Notes:
- 1) Excluding the single-phase 100-V type.
- Please verify the actual compliance of your machine with the F47 standard for voltage sag immunity.

6,000-rpm capability

The MSME motor (under 750 W) can accommodate a maximum speed of 6,000 r/min.

[Comparison of new and conventional 200 W]





Inrush Current Preventive Function

 This driver is equipped with a rush current preventive resistor to prevent the circuit breaker from shutting off the power supply as a result of inrush current occurring at power-on.

Table 1

Applicable Linear Scale	Manufacturer	Model No.	Resolution [µs]	Maximum Speed (m/s)*
Parallel Type (AB-phase)	General	_	Maximum speed after 4 × multiplication: 4 Mpps	
		SR75	0.01	3.3
Serial Type	Sony Manufacturing Systems Corporation	SR85	0.01	3.3
(Incremental)		SL700/PL101-RP	0.1	10
		SL710/PL101-RP	0.1	10
		AT573A	0.05	2
0 1 1 7	Mitutoyo Corporation	ST771A(L)	0.5	5
Serial Type (Absolute)		ST773A(L)	0.1	4
(riboolato)	Sany Manufacturing Systems Corneration	SR77	0.01	3.3
	Sony Manufacturing Systems Corporation	SR87	0.01	3.3

^{*} The maximum speed is a characteristic of the driver. It is limited by the configuration of the machine and the system.

Regenerative Energy Discharge

- · A regenerative resistor is used to discharge regenerative energy, which is the energy generated when stopping a load with a large moment of inertia or when using this unit in vertical operation. This energy is returned to the driver from the motor.
- Frame A and Frame B model drivers do not contain a regenerative resistor. We recommend that you connect an optional regenerative resistor.
- Frame C to Frame F model drivers contain one regenerative resistor; however, adding an optional regenerative resistor provides additional regeneration capability.

Dynamic Braking

- With parameter settings, you can select dynamic braking, which shorts servomotor windings U, V and W at Servo-OFF, during positive direction/ negative direction over-travel inhibition, and during power shutdown and tripping of the circuit breaker.
- The desired action sequence can be set up to accommodate your machine requirements.

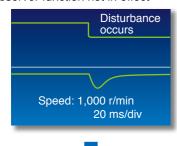
Parameter Initialization

Using the front panel or by connecting a PC, you can restore the parameters to the factory settings.

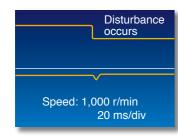
Disturbance Observer

By using a disturbance observer to add an estimated disturbance torque value to the torque canceling command, this function diminishes the impact of the disturbance torque, reduces vibration, and offsets any speed decline.

Disturbance observer function not in effect







Torque Feed Forward

The Torque Feed Forward function performs a comparison with feedback and calculates the amount of torque to add to the necessary torque command in the command for actuation.

Friction Torque Compensation

This function reduces the effect of machine-related friction and improves responsiveness. Two kinds of friction compensation can be set up: unbalanced load compensation, which compensates with a constant operational offset torque; and kinetic friction, which changes direction in response to the direction of movement.

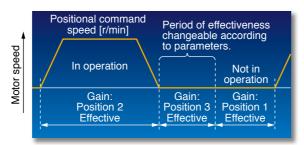
3-Step Gain

A 3-step gain switch is available in addition to the normal gain switch.

This chooses appropriate gain tunings at both stopping and running.

The 3-step gain switch gives you choices of 3 diffent tunings for normal running, stopping for faster positioning and at stopping.

The right gaing tunings achieve lower vibration and quicker positioning time of your application.



Inertia Ratio Conversion

You can adjust right inertia ratio by Inertia Ratio Conversion input(J-SEL).

When you have significant load inertia changes, it can adjust unbalanced speed and position gain turning conbination.

It ends up quicker response of your system.

Input/Output Signal Assignment

You can use the parameters to arbitrarily allocate the universal 10 inputs and 6 outputs. (Inputs can be selected as either A contacts or B contacts). The Panaterm setup software provides an exclusive screen for a more simplified setup.

Torque Limiter Switching

You can use the I/Os to set up torque limits. These can be used for applications such as simplified pressure, tension control, and sensor-less homing.

Applicable overseas safety standards









		Driver	Motor
	EMC Directives	EN55011 EN61000-6-2 IEC61800-3	_
	Low-Voltage Directives	EN61800-5-1	EN60034-1 EN60034-5
EC Directives	Functional safety	EN954-1(CAT3) ISO13849-1(PL-D) EN61508(SIL2) EN62061(SIL2) EN61800-5-2(STO) IEC61326-3-1	.1
UL Standards		UL508C (E164620)	UL1004-1 (E327868: Small type) UL1004 (E166557: Large type)
CSA Standards		C22.2 No.14	C22.2 No.100

IEC: International Electrotechnical Commission

EN: Europaischen Normen

EMC: Electromagnetic Compatibility UL: Underwriters Laboratories

CSA: Canadian Standards Association

Pursuant to the directive 2004/108/EC, article 9(2)

Panasonic Testing Centre

Panasonic Service Europe, a division of

Panasonic Marketing Europe GmbH

Winsbergring 15, 22525 Hamburg, F.R. Germany

* When export this product, follow statutory provisions of the destination country.

* A5E series doesn't correspond to the functional safety standard.

MEMO

Motor Line-up/ Driver and Motor Combination

Motor Line-up

	-		Low inertia		Middle	inertia	High inertia	
		MSMD (Small type)	MSME (Small type)	MSME (Large type)	MDME	MGME (Low speed/ (High torque type)	MHMD	мнме
M	lotor		9					
Rated or	utput (kW)	0.05 0.1 0.2 0.4 0.75	0.05 0.1 0.2 0.4 0.75	1.0 1.5 2.0 3.0 4.0 5.0	1.0 1.5 2.0 3.0 4.0 5.0	0.9 2.0 3.0	0.2 0.4 0.75	1.0 1.5 2.0 3.0 4.0 5.0
	otational Max. speed)	3000 (5000) For 750W 3000 (4500)	3000 (6000)	3000 (5000) For 4.0kW and 5.0kW 3000 (4500)	2000 (3000)	1000 (2000)	3000 (5000) For 750W 3000 (4500)	2000 (3000)
Rotary	20-bit incremental	0	0	0	0	0	0	0
encoder	17-bit absolute	0	0	0	0	0	0	0
Enclosu	re	IP65 (*)	IP67 (*)	IP67 (*)	IP67 (*)	IP67 (*)	IP65 (*)	IP67 (*)
Feature	s	Leadwire type Small capacity Suitable for high speed application Suitable for all applications	Small capacity Suitable for high speed application Suitable for all applications	Middle capacity Suitable for the machines directly coupled with ball screw and high stiffness and high repetitive application	Middle capacity Suitable for low stiffness machines with belt driven	Middle capacity Flat type and suitable for machines with space limitation	Leadwire type Small capacity Suitable for low stiffness machines with belt driven	Middle capacity Suitable for low stiffness machines with belt driven, and large load moment of inertia
Bonder Semiconductor production Food machines		Conveyors Robots Machine tool etc	Conveyors Robots Textile machines etc	Conveyors Robots	Conveyors Robots LCD manufacturing equipment etc			

^(*) Except for output shaft, and connector.

Driver and Motor Combination

	Driver	Motor								
Frame	Part No.	MSMD	MSME	N	MSME	MDME	МСМЕ		MHMD	МНМЕ
	MADHT1105	MSMD5AZ***	MSME5AZ***							
	MADHT1107	MSMD011 ***	MSME011 ***		Motor (S	cheduled to be i	released.)			
A -Frame	MADHT1505	MSMD5AZ***	MSME5AZ***		• MDME	7.5kW, 11kW, 15	kW			
	WADII 1505	MSMD012***	MSME012***		• MHME	7.5kW				
	MADHT1507	MSMD022***	MSME022***		l	4.5kW, 6.0kW			MHMD022***	
B -Frame	MBDHT2110	MSMD021 ***	MSME021***		l	1.5kW, 2.5kW, 4.			MHMD021 ***	
D -Frame	MBDHT2510	MSMD042***	MSME042***			vith Gear Reduce			MHMD042***	
0.5	MCDHT3120	MSMD041 ***	MSME041 ***		100W, 200W, 400W, 750W		50W		MHMD041 ***	
C-Frame	MCDHT3520	MSMD082***	MSME082***						MHMD082***	
	MDDHT3530					MDME102***				MHME102***
	MDDHT2412					MDME104***				MHME104***
D.	MDDHT5540			MSMI	E102***	MDME152***	MGME092	***		MHME152***
D-Frame	MDDH 13540			MSM	E152***					
	MDDHT3420			MSMI	E104***	MDME154***	MGME094	***		MHME154***
	MDDH 13420			MSM	E154***					
E-Frame	MEDHT7364			MSMI	E202***	MDME202***				MHME202 ***
E-Frame	MEDHT4430			MSMI	E204***	MDME204***				MHME204 ***
	MFDHTA390			MSMI	E302***	MDME302***	MGME202	***		MHME302***
	MFDHT5440			MSMI	ME304 *** MDME304 ***		MGME204	***		MHME304***
- -	MFDHTB3A2			MSMI	E402*** MDME402***		MGME302	***		MHME402***
rrame	WIFUTI DOAZ			MSM	E502***	MDME502***				MHME502***
	MEDUTAAGA			MSMI	E404***	MDME404***	MGME304	***		MHME404***
	MFDHTA464			MSM	E504***	MDME504***				MHME504 ***

^{*} A5E series (dedicated for position control) drivers are also used in combination with motors show above.

MINAS A5

Model Designation

Servo Motor



Motor rated output

	-		
Symbol	Rated output	Symbol	Rated output
5A	50W	10	1.0kW
01	100W	15	1.5kW
02	200W	20	2.0kW
04	400W	30	3.0kW
08	750W	40	4.0kW
09	0.9kW	50	5.0kW

Voltage specifications

Symbol	Specifications		
1	100V		
2	200V		
4	400V		
Z	100V/200V common (50W only)		

Rotary encoder specifications

•				
Symbol	Format	Pulse counts	Resolution	Wires
G	Incremental	20-bit	1,048,576	5
S	Absolute	17-bit	131,072	7

Special specifications

Motor specifications

MSME(50W to 750W), MSMD, MHMD

Design order 1 : Standard

(
	S	haft	Holding	j brake	Oil seal		
Symbol	Round	Key-way, center tap	without	with	without	with	
Α							
В							
С							
D							
S							
Т							
U							
V							

MSME(1.0kW to 5.0kW), MDME, MGME, MHME

Symbol	Shaft		Holding	brake	Oil seal	
	Round	Key-way	without	with	without	with
С						
D						
G						
Н						

Motor with reduction gear

M S M E 0 1 1 G 3 1 N Motor rated output

			Motor	rated outp
Symbol	Тур	е	Symbol	Rated output
MSME	Low inertia (50W to 750W)		01	100W
IVISIVIE			02	200W
			04	400W
			08	750W

Voltage specifications

_	
Symbol	Specifications
1	100V
2	200V

Rotary encoder specifications

Symbol	Format	Pulse counts	Resolution	Wires
G	Incremental	20-bit	1,048,576	5
S	Absolute	17-bit	131,072	7
* S: car	n be used in in	cremental.		

Gear ratio, gear type

ا م ما محدد د	Gear	Mo	otor ou	ıtput (N)	Gear
Symbol	reduction ratio	100	200	400	750	type
1N	1/5					
2N	1/9					For high
3N	1/15					accuracy
4N	1/25					

Motor structure

Symbol	Shaft	Holding	brake
Syllibol	Key-way	without	with
3			
4			

Servo Driver

Positioning type	M	Α	D	Н	T	1	5	0	5	E	*	*		Special specifications
		Dowo	r dos	vice N	lov					L	Only	posit	ion control	Current detector
		Powe			ıax	•								current rating

Frame symbol

Symbol	Frame
MADH	Frame A
MBDH	Frame B
MCDH	Frame C
MDDH	Frame D
MEDH	Frame E
MFDH	Frame F

current rating

Frame	Symbol	Current ratin
Frame A	T1	10A
Frame B	T2	15A
Frame C	T3	30A
Frame D	T4	35A
Frame E	T5	50A
Frame F	T7	75A
	TA	100A
	TB	150A

Symbol	Current rating
T1	10A
T2	15A
T3	30A
T4	35A
T5	50A
T7	75A
TA	100A
TB	150A

Supply voltage specifications

-	
Symbol	Specifications
1	Single phase, 100V
3	3-phase, 200V
4	3-phase, 400V
5	Single/3-phase, 200V

05	5A
07	7.5A
10	10A
12	12A
20	20A
30	30A
40	40A
64	64A
90	90A
A2	120A

Symbol | Current rating

Special specifications

^{*} S: can be used in incremental.

Table of Part Numbers and Options

	Motor				Driver		Power	Fncor	der cable	Motor	r cable	nal parts			
lotor series	Power supply	Output (W)	Part No. Note) 1	Part No. (Standard type)	Part No. (Positioning	Frame	canacity	20-bit	17-bit	without	with brake	Brake cable	Regenerative resistor	Reactor	Noise filter
		(,	14010) 1	(Otandard typo)	type)		(diratod lodd)	Note) 2		Note) 2	Note) 2	Note) 2	10010101		11101
		50	MSMD5AZ 1 *	MADHT1105	MADHT1105E	A-frame	Approx. 0.4kVA						DV0P4280	DV0P227	D1/0D//
	Single phase 100V	100	MSMD011 1 * MSMD021 1 *	MADHT1107 MBDHT2110	MADHT1107E	D from a	Approx. 0.4kVA						DV0P4283		DV0P4170
MSMD		200 400	MSMD041 1 *	MCDHT3120	MBDHT2110E MCDHT3120E								DV0P4283 DV0P4282	DV0P228	DV0PM20042
(Leadwire)		50	MSMD5AZ_1*	MADHT1505	MADHT1505E	O-lianie	Approx. 0.5kVA		MFECA	MFMCA	_	MFMCB			D V UF IVIZUU4Z
type /		100	MSMD012_1*	MADHT1505	MADHT1505E	A-frame		0^*0EA	И 0**0EAE	0**0EED		0**0GET	DV0P4281	DV0P220	
3000r/min	Single phase/ 3-phase 200V	200	MSMD022□1*	MADHT1507	MADHT1507E		Approx. 0.5kVA								DV0PM20042
	2001	400	MSMD042□1 *	MBDHT2510	MBDHT2510E								DV0P4283	DV0P221	
		750	MSMD082_1 *	MCDHT3520	MCDHT3520E	C-frame								DVOIZZI	
		50	MSME5AZ 1 *	MADHT1105	MADUT1105E	A-frame	Approx. 0.4kVA						DV0P4280	DV0P227	DV0D4470
	Single phase 100V	100 200	MSME011 1 * MSME021 1 *	MADHT1107 MBDHT2110	MADHT1107E MBDHT2110E	R framo	Approx. 0.4kVA Approx. 0.5kVA						DV0P4283		DV0P4170
моме		400	MSME041 1 *	MCDHT3120	MCDHT3120E								DV0P4283	DV0P228	DV0PM20042
MSME		50	MSME5AZ_1*	MADHT1505	MADHT1505E	O mame	Approx. 0.5kVA	MFECA		MFMCA	_	MFMCB			D V OI IVIZOU-IZ
3000r/min		100	MSME012_1 *	MADHT1505	MADHT1505E	A-frame		U^*OMJI	0**0MJE	0**0NJD		0**0PJT	DV0P4281	DV0P220	
	Single phase/ 3-phase 200V	200	MSME022□1 *	MADHT1507	MADHT1507E		Approx. 0.5kVA								DV0PM20042
	2001	400	MSME042□1 *	MBDHT2510	MBDHT2510E								DV0P4283	DV0P221	
		750	MSME082 1 *	MCDHT3520	MCDHT3520E	C-frame								DVOI ZZI	
	Single phase/ 3-phase	1000	MSME102 1 *	MDDHT5540	MDDHT5540E	D-frame	Approx. 1.8kVA			MFMCD	MFMCA		DV0P4284	DV0P222	DV0P4220
	200V	1500	MSME152_1 * MSME202_1 *	MDDHT5540 MEDHT7364	MDDHT5540E		Approx. 2.3KVA			0**2ECD	0**2FCD				
		2000 3000	MSME302 1 *	MFDHTA390	MEDHT7364E MFDHTA390E	E-Trame	Approx. 3.3KVA Approx. 4.5kVA					-	DV0P4285	DV0P223 DV0P224	DV0PM20043
	3-phase 200V	4000	MSME402_1 *	MFDHTB3A2	MFDHTB3A2E	F-frame	Approx. 6.0kVA			MFMCA	MFMCA		DV0P4285	DV0P224	DV0P3410
MSME		5000	MSME502 1 *	MFDHTB3A2	MFDHTB3A2E	1 -mame	Approx. 7.5kVA	MEECA	MFECA	0**3ECT	0**3FCT		× 2 in parallel	_	D V 01 0 4 10
3000r/min		1000	MSME104_1 *	MDDHT3420	MDDHT3420E	D.	Approx. 1.8kVA		0**0ETE			-	DV0DM00040		
000017111111		1500	MSME154□1*	MDDHT3420	MDDHT3420E	D-frame	Approx. 2.3kVA			MFMCD 0**2ECD	MFMCE 0**2FCD		DV0PM20048		
	3-phase 400V	2000	MSME204□1 *	MEDHT4430	MEDHT4430E	E-frame	Approx. 3.3kVA			0 ZLOD	0 21 00		DV0PM20049	_	_
	3-pnase 400 v	3000	MSME304□1 *	MFDHT5440	MFDHT5440E		Approx. 4.5kVA			MFMCA	MFMCA		DV0PM20049	_	
		4000	MSME404 1 *	MFDHTA464	MFDHTA464E	F-frame				0**3ECT	0**3FCT		× 2 in parallel		
	0	5000	MSME504 1 *	MFDHTA464	MFDHTA464E		Approx. 7.5kVA						·		
	Single phase/ 3-phase 200V	1000	MDME102_1 * MDME152_1 *	MDDHT3530 MDDHT5540	MDDHT3530E	D-frame	Approx. 1.8kVA Approx. 2.3kVA			MFMCD	MFMCA		DV0P4284	DV0P222	DV0P4220
	2007	1500 2000	MDME202_1*	MEDHT7364	MDDHT5540E MEDHT7364E	F_framo				0**2ECD	0**2FCD		DV0P4285	DI/UD333	DV0PM20043
		3000	MDME302 1 *	MFDHTA390	MFDHTA390E	L-liaille	Approx. 4.5kVA					-		DV0P224	D V 01 1V120043
	3-phase 200V	4000	MDME402_1 *	MFDHTB3A2	MFDHTB3A2E	F-frame				MFMCA	MFMCA		DV0P4285	DV0P225	DV0P3410
MDME		5000	MDME502□1 *	MFDHTB3A2	MFDHTB3A2E		Approx. 7.5kVA	MFECA	MFECA	0**3ECT	0**3FCT		× 2 in parallel	_	
2000r/min		1000	MDME104□1*	MDDHT2412	MDDHT2412E	D-frame	Approx. 1.8kVA		0**0ETE		MEMOE	_	DV0PM20048		
		1500	MDME154□1*	MDDHT3420	MDDHT3420E		Approx. 2.3kVA			MFMCD 0**2ECD	MFMCE 0**2FCD		D V 0F IVI20040		
	3-phase 400V	2000	MDME204 1 *	MEDHT4430	MEDHT4430E	E-frame					·		DV0PM20049	_	_
	P 3333	3000	MDME304 1 *	MFDHT5440	MFDHT5440E	F.	Approx. 4.5kVA			MFMCA	MFMCA		DV0PM20049		
		4000 5000	MDME404_1 * MDME504_1 *	MFDHTA464 MFDHTA464	MFDHTA464E MFDHTA464E	F-frame	Approx. 6.0kVA Approx. 7.5kVA			0**3ECT	0**3FCT		× 2 in parallel		
	Single phase/ 3-phase 200V	900	MGME092 1 *	MDDHT5540	MDDHT5540E	D-frame	- 11			MFMCD0**2ECD	MFMCA0**2FCD		DV0P4284	DV/0P222	DV0P4220
		2000	MGME202_1*	MFDHTA390	MFDHTA390E		Annroy 3 8k\/A			MFMCA	MFMCA	-		DV0P223	
MGME	3-phase 200V	3000	MGME302_1 *		MFDHTB3A2E	F-frame	Approx. 4.5kVA	MFECA	MFECA	0**3ECT	0**3FCT			DV0P224	DV0P3410
1000r/min		900	MGME094_1 *	MDDHT3420	MDDHT3420E	D-frame	Approx. 1.8kVA			MFMCD0**2ECD	MFMCE0**2FCD] -	DV0PM20048		
	3-phase 400V	2000	MGME204_1 *	MFDHT5440	MFDHT5440E	F-frame	Approx. 3.8kVA			MFMCA	MFMCA		DV0PM20049	_	_
		3000	MGME304_1 *	MFDHTA464	MFDHTA464E		Approx. 4.5kVA			0**3ECT	0**3FCT		× 2 in parallel		
MHMD	Single phase 100V	200	MHMD021 1 *	MBDHT2110	MBDHT2110E								DV0P4283	DV0P228	DV0P4170
(Leadwire)	3 .	400	MHMD041_1 * MHMD022_1 *	MCDHT3120 MADHT1507	MCDHT3120E MADHT1507E			MFECA	MFECA	MFMCA		MFMCB	DV0P4282	DV0P220	DV0PM20042
type /	Single phase/ 3-phase	200 400	MHMD042_1 *	MBDHT2510	MBDHT2510E			0**0EAN	И 0**0EAE	0**0EED	_	0**0GET	DV0P4283		DV0PM20042
3000r/min	200V	750	MHMD082 1 *	MCDHT3520	MCDHT3520E								D V 01 4200	DV0P221	D V OI IVIZOUTZ
	Single phase/ 3-phase	1000	MHME102_1 *	MDDHT3530	MDDHT3530E		Approx. 1.8kVA			MFMCD	MFMCA		D)/2D/20/	D) /2D222	D1/2D /222
	200V	1500	MHME152_1 *	MDDHT5540	MDDHT5540E	D-frame	Approx. 2.3kVA			0**2ECD	0**2FCD		DV0P4284	DV0P222	DV0P4220
		2000	MHME202_1 *	MEDHT7364	MEDHT7364E	E-frame	Approx. 3.3kVA			MFMCE0**2ECD	MFMCE0**2FCD]	DV0P4285	DV0P223	DV0PM20043
	3-phase 200V	3000	MHME302 1 *	MFDHTA390	MFDHTA390E		Approx. 4.5kVA			MFMCA	MFMCA		DV0P4285	DV0P224	
NALIBAT.	ο μπασο 200 ν	4000	MHME402 1 *	MFDHTB3A2	MFDHTB3A2E	F-frame				0**3ECT	0**3FCT		x 2 in parallel	DV0P225	DV0P3410
MHME		5000	MHME502 1 *	MFDHTB3A2	MFDHTB3A2E		Approx. 7.5kVA		MFECA			_	,	_	
2000r/min		1000	MHME104 1 *	MDDHT2412	MDDHT2412E	D-frame	Approx. 1.8kVA	0^^0E11	0**0ETE	MFMCD 0**2ECD	MFMCE		DV0PM20048		
		1500	MHME154_1 * MHME204_1 *	MDDHT3420 MEDHT4430	MDDHT3420E MEDHT4430E		Approx. 2.3kVA Approx. 3.3kVA			MFMCE0**2ECD	0**2FCD		DV0PM20048		
	3-phase 400V	2000 3000	MHME304_1*	MFDHT5440	MFDHT5440E	L-irame	Approx. 3.3KVA Approx. 4.5kVA			IVII IVIOEU ZEOD		1	D V UF IVI 20048	_	_
			MHME404 1 *	MFDHTA464	MFDHTA464E	E frama				MFMCA	MFMCA		DV0PM20049		
		4000	NULINE 404 1 ×	MILDULIAANA	IVII DITTAGOGO	F-IIIAME	Approx. 6.0kVA			0**3ECT	0**3FCT		× 2 in parallel		

 Options 							
Title	Title 構成品名						
Interface cable			DV0P4360				
Interface Conne	ctor		DV0P4350				
		Single row type	DV0PM20032				
Connector for Power	(100V/) 200V	Double row type	DV0PM20033				
Supply Input Connection	E-frame	(200V)	DV0PM20044				
Connection	D-frame		DV0PM20051				
	E-frame		DV0PM20052				
Connector for Control Power Supply Input Connection	D, E-fra (400V)	me	DV0PM20053				
Connector	A to D-f	rame	DV0PM20034				
for Motor	E-frame		DV0PM20046				
Connection	D-frame		DV0PM20054				
Connector for	E-frame)	DV0PM20045				
Regenerative Resistor	D-frame	(400V)	DV0PM20055				
			DV0P4290				
			DV0P4380				
Connector Kit fo	r		DV0PM20035				
Motor/Encoder (Connection	on	DV0PM20036 DV0PM20037				
			DV0PM20037 DV0PM20038				
			DV0PM20036 DV0PM20039				
Connector Kit fo	r		DV0PM20040				
Motor/Brake Co		DCOOO	DV0FM20040				
	RS485, Safety	H5232	DV0PM20024 DV0PM20025				
	Externa	Scale	DV0PM20026				
Connector	Encode		DV0PM20010				
	Analog Signal	Monitor	DV0PM20031				
Battery For Abso		oder	DV0P2990				
Battery Box			DV0P4430				
	A-frame)	DV0PM20027				
Mounting	B-frame	•	DV0PM20028				
bracket	C-frame		DV0PM20029				
	D-frame)	DV0PM20030				
	without		MFECA0**0EAM				
Junction Cable	Buttery	Box	MFECA0**0MJD MFECA0**0ETD				
for Encoder			MFECA0**0EAE				
TOT ETIOOGOT	with	_	MFECA0**0MJE				
	Buttery	Box	MFECA0**0ETE				
			MFMCA0**0EED				
			MFMCA0**0NJD				
	without	Brake	MFMCD0**2ECD				
Junction Cable			MFMCE0**2ECD				
for Motor			MFMCA0**3ECT				
	with Bra	ıko	MFMCA0**2FCD				
	WILLI DIE	ike	MFMCE0**2FCD MFMCA0**3FCT				
	I		MFMCB0**0GET				
Junction Cable f	or Brake		MFMCB0**0PJT				
	50Ω 25	W	DV0P4280				
	100Ω 2		DV0P4281				
			DV0P4281 DV0P4282				
Eutoroal	25Ω 50	W					
External Regenerative			DV0P4282 DV0P4283				
External Regenerative Resistor	25Ω 50° 50Ω 50° 30Ω 10°	W OW	DV0P4283 DV0P4284				
Regenerative	25Ω 50° 50Ω 50° 30Ω 10° 20Ω 13°	W DW DW	DV0P4283 DV0P4284 DV0P4285				
Regenerative	25Ω 50' 50Ω 50' 30Ω 100 20Ω 130 120Ω 80	W DW DW	DV0P4283 DV0P4284 DV0P4285 DV0PM20048				
Regenerative	25Ω 50' 50Ω 50' 30Ω 100 20Ω 130 120Ω 80 80Ω 190	W DW DW DW	DV0P4283 DV0P4284 DV0P4285 DV0PM20048 DV0PM20049				
Regenerative	25Ω 50' 50Ω 50' 30Ω 10' 20Ω 13' 120Ω 8' 80Ω 19' DV0P22	W DW DW DW DW DW	DV0P4283 DV0P4284 DV0P4285 DV0PM20048 DV0PM20049 221, DV0P222,				
Regenerative Resistor	25Ω 50' 50Ω 50' 30Ω 10' 20Ω 13' 120Ω 8' 80Ω 19' DV0P22 DV0P22	W DW DW DW DW DW	DV0P4283 DV0P4284 DV0P4285 DV0PM20048 DV0PM20049 221, DV0P222, 224, DV0P225,				
Regenerative Resistor	25Ω 50 ⁰ 50Ω 50 ⁰ 30Ω 10 ⁰ 20Ω 13 ⁰ 120Ω 8 ⁰ 80Ω 19 ⁰ DV0P22 DV0P22 DV0P4 ²	W DW DW DW DW 20, DV0P 23, DV0P 27, DV0P	DV0P4283 DV0P4284 DV0P4285 DV0PM20048 DV0PM20049 221, DV0P222, 224, DV0P225, 228 PM20042				
Regenerative Resistor	25Ω 50 ⁰ 50Ω 50 ⁰ 30Ω 100 20Ω 130 120Ω 80 80Ω 190 DV0P22 DV0P22 DV0P42 DV0P44 DV0P42	W DW DW DW DW 20, DV0P 23, DV0P 27, DV0P 170, DV0P	DV0P4283 DV0P4284 DV0P4285 DV0PM20048 DV0PM20049 221, DV0P222, 224, DV0P225, 228				
Regenerative Resistor	25Ω 500 50Ω 500 30Ω 100 20Ω 130 120Ω 80 80Ω 190 DV0P22 DV0P22 DV0P42 DV0P44 DV0P42 DV0P42	W DW DW DW DW 20, DV0P 23, DV0P 27, DV0P 170, DV0 220, DV0	DV0P4283 DV0P4284 DV0P4285 DV0PM20048 DV0PM20049 221, DV0P222, 224, DV0P225, 228 PM20042 PM20043				
Regenerative Resistor	25Ω 50' 50Ω 50' 30Ω 10' 20Ω 13' 120Ω 8' 80Ω 19' DV0P22 DV0P22 DV0P4' DV0P4' DV0P3' Single p	W DW DW DW DW 20, DV0P 23, DV0P 170, DV0P 170, DV0I 220, DV0I	DV0P4283 DV0P4284 DV0P4285 DV0PM20048 DV0PM20049 221, DV0P222, 224, DV0P225, 228 PM20042				
Regenerative Resistor Reactor Noise Filter	25Ω 50' 50Ω 50' 30Ω 10' 20Ω 13' 120Ω 8' 80Ω 19' DV0P22' DV0P22' DV0P4' DV0P4' DV0P3- Single p	W DW	DV0P4283 DV0P4284 DV0P4285 DV0PM20048 DV0PM20049 221, DV0P222, 224, DV0P225, 228 PM20042 PM20043 DV0P4190				

Cautions for Proper Use

- This product is intended to be used with a general industrial product, but not designed or manufactured to be used in a machine or system that may cause personal death when it is failed.
- Installation, wiring, operation, maintenance, etc., of the equipment should be done by qualified and experienced personnel.
- Apply adequate tightening torque to the product mounting screw by taking into consideration strength of the screw and the characteristics of material to which the product is installed. Overtightening can damage the screw and/or material; undertightening can result in loosening.
 - Example) Steel screw (M5) into steel section: 2.7 to 3.3 N·m.
- Install a safety equipments or apparatus in your application, when a serious accident or loss of property is expected due to the failure of this product.
- Consult us if the application of this product is under such special conditions and environments as nuclear energy control, aerospace, transportation, medical equipment, various safety equipments or equipments which require a lesser air contamination.
- We have been making the best effort to ensure the highest quality of the products, however, application of exceptionally larger external noise disturbance and static electricity, or failure in input power, wiring and components may result in unexpected action. It is highly recommended that you make a fail-safe design and secure the safety in the operative range.
- If the motor shaft is not electrically grounded, it may cause an electrolytic corrosion to the bearing, depending on the condition of the machine and its mounting environment, and may result in the bearing noise. Checking and verification by customer is required.
- Failure of this product depending on its content, may generate smoke of about one cigarette. Take this into consideration when the application of the machine is clean room related.
- Please be careful when using in an environment with high concentrations of sulfur or sulfric gases, as sulfuration can lead to disconnection from the chip resistor or a poor contact connection.
- Take care to avoid inputting a supply voltage which significantly exceeds the rated range to the power supply of this product. Failure to heed this caution may result in damage to the internal parts, causing smoking and/or a fire and other trouble.
- The user is responsible for matching between machine and components in terms of configuration, dimensions, life expectancy, characteristics, when installing the machine or changing specification of the machine. The user is also responsible for complying with applicable laws and regulations.
- Read and observe the instruction manual without fail for proper usage of the products.

Repair

Consult to the dealer from whom you have purchased this product for details of repair work.

When the product is incorporated to the machine you have purchased, consult to the machine manufacturer or its dealer.

URL

Electric data of this product (Instruction Manual, CAD data) can be download from the following web site; http://industrial.panasonic.com/ww/i_e/25000/motor_fa_e/motor_fa_e.html

Contact to :

Motor Company, Panasonic Corporation

1-1 Morofuku 7-chome, Daito, Osaka 574-0044, Japar Tel : +81-72-871-1212 Fax: +81-72-870-3151





ISO14001 Certificate division
CERTIFICATE OF APPROVAL ISO14001





ISO9001 Certificate division

The contents of this catalog apply to the products as of Oct. 1, 2009.

- Printed colors may be slightly different from the actual products.
- Specifications and design of the products are subject to change without notice for the product improvement.