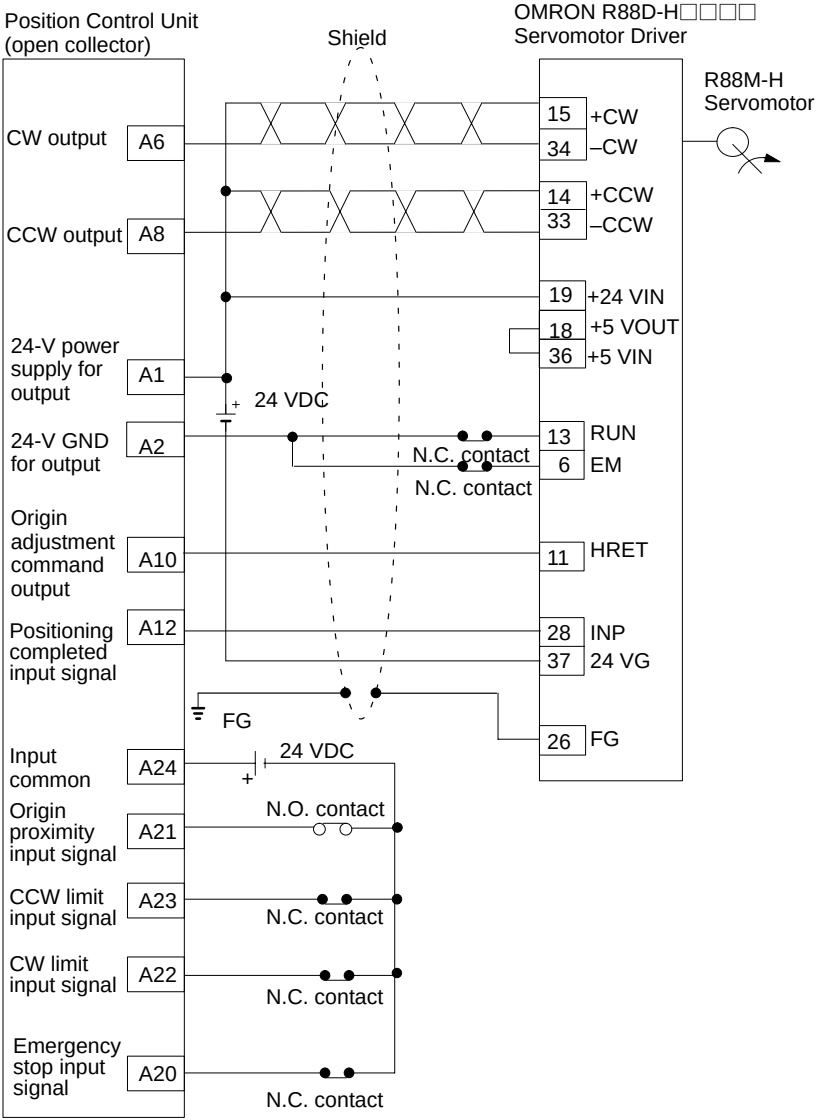
Position Control Unit
(open collector)
Shield
OMRON R88D-H□□□□
Servomotor Driver
R88M-H
Servomotor
CW output
A6
CCW output
A8
24-V power supply for output
A1
24-V GND for output
A2
Origin adjustment command output
A10
Positioning completed input signal
A12
Input common
A24
Origin proximity input signal
A21
CCW limit input signal
A23
CW limit input signal
A22
Emergency stop input signal
A20
15 +CW
34 –CW
14 +CCW
33 –CCW
19 +24 VIN
18 +5 VOUT
36 +5 VIN
24 VDC
13 RUN
6 EM
N.C. contact
N.C. contact
11 HRET
28 INP
37 24 VG
FG
26 FG
24 VDC
N.O. contact
N.C. contact
N.C. contact
N.C. contact