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SERVO DRIVES MINAS A6 SERIES

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Application areas:



Pick-and-place machines



Handling systems



Machine tools



Robots



Printing machines



Automated machines



Materials handling



Packaging machinery

Automation products from Panasonic Industry

With over 100 years of innovation and manufacturing expertise, Panasonic Industry Europe remains committed to its vision of creating "A Better Life, A Better World." Panasonic can look back on decades of experience in the electronics industry and, thanks to its dedicated customer orientation, is a competent and reliable partner for customers throughout Europe when it comes to technical expertise in combination with solution orientation. As a provider of tailor-made solutions, we focus on offering our customers products and services in the **Mobility**, **Living Space** and **Business** sectors that make a difference thanks to our proprietary innovations.

Smart automation technology

The factory of the future will achieve new levels of productivity, effectiveness and profitability through comprehensive networking. Equipment and components from Panasonic Industry Europe offer leading-edge **Industry 4.0** features, as connectivity, energy efficiency, reliability and sturdiness play a pivotal role in modern production environments.

The Panasonic Industry Europe portfolio not only offers key electronic components, devices, modules and software but also complete solutions for production lines in a wide variety of industries. Panasonic Industry's comprehensive know-how along the entire value chain, combined with a corporate culture geared to customer needs, enables it to offer customerspecific solutions.

Our experience as a manufacturer and a sales partner for components and products allows us to share our experience with our customers. Customer wishes are specifically integrated into the development of new products, so that we can surpass our role as a supplier and become a competent, long-term partner for our customers.

The most modern servo drives: the MINAS A6 series

With its MINAS A6 series,

Panasonic Industry offers a highly dynamic servo driver family with a wide power range from 50W to 5kW for many different areas of applications. The servo drivers and motors of the **MINAS A6 series** are characterized by a consistently compact and robust but also lightweight design. In addition, they have been equipped with innovative functions for damping resonance frequencies and to eliminate vibration tendencies.

Highly dynamic drive technology in a 400V network for maximum performance

With around 70% market share, 400V applications represent the largest segment in industrial automation. Take advantage of the 400V three-phase network by using the servo drives from Panasonic, which cover a power range from 0.4–5kW (in future up to 22kW).

Proven technology paired with innovative functions and versatile control features such as pulse, analog and network technology with real-time communication characterize our solutions.

Service

Panasonic Industry Europe's comprehensive service includes an expert hotline, workshops and on-site service to ensure the reliable and effective use of our servo drives. In addition to its wide-ranging product portfolio of programmable logic controllers, Panasonic Industry Europe also offers sensors, operating panels, drive technology, energy management systems, ionisers, automation components and many other products and complete solutions.





MINAS A6 Multi series: 400V servo drive system

Compact, modular design for maximum performance

400V servo drive system

- > Compact servo drive in book format: Only 25mm width per axis on the two-axis-unit
- > Modular design: One power supply unit supports several servo drivers
- > DC link bus system: Reliable connection without tools
- > **Quick servo control technology:** A frequency response of 3.2kHz enables high-speed operation for maximum productivity
- > Anti-vibration technology: Suitable for highly precise applications thanks to vibration damping.

- State-of-the-art network technology: High-speed communication via EtherCAT with up to 10Mbit/s
- > 18 advanced safety functions: MINAS A6 Multi achieves safety class SIL3
- > Setup via EtherCAT: Easy configuration and programming over EtherCAT (EoE) using the software tool PANATERM
- Robust connectors: Servo motors with round connectors according to IEC, CENELEC, and IEEE

Industries



Packaging industry



Plastics and metal processing



Presses

Quick-connect technology

The MINAS A6 Multi can be wired at the top and bottom. No tools are needed.

DC link bus

Beneath the front cover lies the DC link bus. Thanks to the screwless power bus system it allows quick and easy expansion of the servo drivers.

Modular construction

Several two-axis servo drivers (50mm) can be coupled to just one compact power supply unit (50mm or 100mm width). Thanks to the DC link bus, the expansion is fast and reliable.

Power supply units

Product no.	Size	Input voltage	Rated power
MADMPN14	А	3-phase 380–480V AC	15kW
MBDMPN24	В	3-phase 380–480V AC	30kW





Servo driver units

Product no.	Size	Number of axes	Rated power
MADM2A4KBX	А	2	For motors 0.4–0.75kW**
MADM2A6KBX	А	2	For motors 0.75–1.5kW**
MADM2AAKBX	А	2	For motors 1.5–3.0kW**
MBDM1ABKBX	В	1	For motors 3.0–5.0kW

The MINAS product family changes the world of industrial machine automation



Robots

A robot is required to operate stably independent of the constantly changing position, workload, or other condition affecting the robot arm. The MINAS A6 servo drive family guarantees stable operation by reducing the effects of loads to a minimum with the help of "adaptive load control".



Processing machines

With metal-processing machines, it is very difficult to manufacture polygonal bodies with a mirror-like finishing. The MINAS A6 servo drive family realizes a frequency response of 3.2kHz to improve the feedback and to enable a mirror-like finish without lines or streaks.



Pick-and-place machines

The MINAS A6 servo drive family shows its versatility especially when used with pick-and-place machines where speed and positional accuracy are a must.

In addition to the high-frequency response, the servo drives deal with random disturbances with the help of the built-in "adaptive load control", thus keeping productivity high.



CNC milling machine

Equipped with servo motors of the MINAS LIQI series for controlling 3 axes (X, Y, Z) and safety light curtains from Panasonic.



Packaging machine for hamburgers and minced meat

Equipped with MINAS A5 servo motors, FP7 programmable controllers, inverters, touch terminals and sensors from Panasonic.



Press brake for metal sheet

Machine system equipped with MINAS A5 motors with EtherCAT for moving back gauges.



Panasonic's MINAS A6 series follows in the footsteps of the highly successful predecessor, the MINAS A5 series. The A6 series has been improved further. At the same time, compatibility with the A5 series has been maintained.



		200/400V AC										
MINAS A6 series	A6SE	A6SG	A6SF	A6N/A6B	A6 Multi							
			1									
Rated power		400W-5kW										
Supply voltage		3-phase										
Bandwidth (velocity response)			3200Hz									
Rated rotational speed			2000-3000rpm									
Max. rotational speed		3000-6500r/	min (200V AC), 3000–5500rp	om (400V AC)								
Rated torque		0.16-26.3	Nm (200V AC), 3.18–23.9Nm	(400V AC)								
Peak torque		0.48-71.6	Nm (200V AC), 9.55–71.6Nm	(400V AC)								
Control functions	Position	Position control Position, velocity, torque control										
IP degree of protection (motor)			IP67									
Control input	Pu	lse	Pulse, analog	Network	Network							

Compatible with MINAS A5 series

Connections designed for compatibility

The A5 series connector cables and connectors can also be used for the A6 series (except for MHMF motors 50W–1000W).



MINAS A5



MINAS A6



Identical accessories

EMC filter and braking resistor can be used for both the MINAS A5 series and the MINAS A6 series.

Compatible flange dimensions

The motor can be exchanged 1:1 at the machine or gear flange.

Improvements and new features of the MINAS A6 series

Even more compact design

Thanks to the split core structure and a new housing, we have been able to reduce not only the length by 30%, but also the weight by up to 10%.

MHMF + MDMF models 10% lighter, 30% shorter



High-resolution 23-bit encoder – can be used as an absolute or incremental rotary encoder

The 20-bit encoder (1048576 pulses per revolution = ppr) has been upgraded to 23 bit (8388608ppr).

Improvements and new features of the MINAS A6 series

Advanced controller settings

3.2kHz frequency response



Numerous interference bands Hardly any interference bands

Available with two different seals

(single/triple lip)

An oil seal with triple lip has just been developed. It is ideally suited for protection against ingress of dust and oil in ambient environments with a high degree of pollution.

Improved suppression of vibrations

The tendency to vibrate when braking to a standstill is significantly reduced. This has shortened the transient recovery time.

Improved reaction and adjustment to load variations

Type 1: Single lip



Type 2: Triple lip



NEW!

Comparison of transient recovery curves



Elapsed time after command carried out [ms]

Elapsed time after command carried out [ms]



----- : without load

Max. torque

Up to 350% of the nominal torque (MHMF model)

Max. speed

Raised to max. 6500rpm (MHMF model)



Semi/fully enclosed position control loop

The A6 series enables a setting value of 8Mpps and a response with 4Mpps. This allows for high resolution as well as high-speed operation.

A5 Setting value 4Mpps

A6 Setting value 8Mpps

General features

External encoders for full-closed control

Using an external encoder or linear displacement measuring system ensures high-precision position control.

Feedback External encoder

Belt drive

Ball screw drive







Real-time auto-gain tuning

Automatic tuning after completion of multiple operations. The automatic vibration suppression function minimizes damage to the equipment. Additional mode and stiffness parameters enable easy response frequency-optimization for specific machine types such as high-friction, belt-driven machines or machines with low-friction ball screw drives.

Manual and automatic notch filters

Highly sensitive notch filters log resonance frequencies and adapt them automatically.

General features

Manual and automatic damping filters

Damping filters that can be set automatically suppress the equipment's resonance, which greatly reduces axis vibration at machine stoppage.



Integrated safety function STO (Safe Torque Off)

Safety functions based on safety standards: ISO13849-1(PL e, CAT3), EN61508(SIL3), EN62061(SILCL3), EN61800-5-2(SIL3, STO), IEC61326-3-1, IEC60240-1.



Dynamic brake

For dynamic braking that protects material.

Torque limit

Torque limit is an indispensable function for torque-controlled applications or generally for protection against mechanical damages.

3-step control setting

Control parameters are activated according to the operating condition (deceleration during operation, stopping during fast positioning, standstill). By controlling the motion it is possible to perform even faster positioning with a lower vibration tendency.

Software tool PANATERM with motion simulation

PANATERM reads response frequency data from the actual machine. A simplified simulation function allows you to check gain and filter effects without you having to adjust the actual parameter settings of the equipment.





Servo drivers and motors

				200/400V AC			400V AC
	Model	Standard	RS485 communication	Multifunction	Netv	work	400V AC compact
		A6SE	A6SG	A6SF	A6N	A6B	A6 Multi
					1		
/ers	RTEX	-	-	-	x	-	-
vo driv	EtherCAT	-	-	-	-	х	х
Ser	External encoder	-	-	х	х		х
	Safety function STO	-	-	х		x	x
	Advanced safety function	-	-	-		_	х
	RS232/485 (Modbus)	-	х	х		_	-
	Velocity control, torque control	-	-	х		х	
	Position control with dig. I/O (like MINAS A4P)	Х	X	X		-	-
	Position control	х	x	x		x	x

		Model MSMF				MD	MF	MHMF					
			Low inertia			Medium	inertia		High i	inertia			
		Rated power W	Flange Ø mm	Rated rota- tional speed (max.) rpm	Flange Ø mm	Rated rota- tional speed (max.) rpm	Flange Ø mm	Rated rota- tional speed (max.) rpm	Flange Ø mm	Rated rota- tional speed (max.) rpm	Flange Ø mm	Rated rota- tional speed (max.) rpm	
		50	38	3000 (6000)	-	-	-	-	40	3000 (6500)	-	-	
		100			-	-	-	-			-	-	
	5	200	60		-	-	-	-	60		-	-	
	00V A	400			-	-	-	-			-	-	
	2	750	80		-	-	-	-	80	3000 (6000)	-	-	
		1000			100	3000 (5000)	130	2000 (3000)			130	2000 (3000)	
s		1500	-	-	100	3000 (3000)	150	2000 (3000)	-	-	130	2000 (3000)	
Servo moto		1000	-	-	100					-	-	130	
		1500	-	-		2000 (5500)	130		-	-	130		
	V AC	2000	-	-			3000 (3300)	5000 (5500)	150	2000 (3500)	-	-	
	400	3000	-	-	120				-	-	17/		
		4000	-	-	120	2000 (5000)	174		-	-	170		
		5000	-	-	130	3000 (3000)	170	2000 (3000)	-	-		2000 (3000)	
		Features	Low power inertia, suit kinds of appl suitable for applic	range, low able for all ications, also high-speed ations	Medium power range, low inertia, suitable for machinery directly connected with a ball screw drive and with high machine rigidity and repetition rate		Medium power range, medium inertia, suitable for belt-driven machinery with low rigidity		Low power range, high inertia, suitable for belt- driven machinery with low rigidity		Medium power range, high inertia, suitable for belt-driven machinery with low rigidity		
		Applica- tions	Bonders, eq transistor p packaging m	uipment for production, achines, etc.	SMD ma machines production ar	achinery, s for food nd LCDs, etc.	Conveyor machinery, robots, textile machines, etc.		Conveyor machinery, robots, etc.		Conveyor machinery, robots, machines for LCD production, etc.		

Servo driver model codes 100/200/400V AC

	MAD	L	N	1	5	S	E	
Frame: MAD: A MBD: B MCD: C MDD: D MED: E MFD: F L: A6 series								Type: Pulse/analog type: SE: Standard (pulse) SF: Multifunction (pulse, analog) SG:RS485 (pulse) Network type: NE: Without STO (RTEX) NF: With STO (RTEX)
								BE: Without STO (EtherCAT) BF: With STO (EtherCAT)
Safety function: N: Without STO T: With STO								Supply voltage: 1: 1-phase, 100V AC 3: 3-phase, 200V AC 5: 1-/3-phase, 200V AC 4: 3-phase, 400V AC
Maximum rated current: 0: 6A 1: 8A 2: 12A 3: 22A 4: 24A	5: 40A 8: 60A A: 100A B: 120A	A A						

Servo motor model codes 100/200V AC

	MSM	F	5A	Z	L	1	A1	
Motor model MSM: Low inertia MDM: Medium inertia MHM: High inertia								Motor specifications: (shaft type, holding brake, oil seal, encoder clamp): A-D,G,H,S-V; 1-8
F: A6 series								1: Standard
Rated power: 5A: 50W 01: 100W 02: 200W 04: 400W	08: 750W 09: 1kW 10: 1kW 15: 1.5kV	(Ø 80mm) (Ø 100/130 V	lmm)					L: 23 bit absolute, 8388608ppr
Supply voltage: 1: 100V 2: 200V Z: 100V/200V								

Servo motor model codes 400V AC

	MSM	F	10	4	A1	G	9
Motor model MSM: Low inertia MDM: Medium inertia MHM: High inertia							0il seal: 9: Single lip A: Triple lip
F: A6 series							Shaft type: G: Without key way shaft, without holding brake H: With key way shaft, with holding brake
Rated power:							
10: 1kW 15: 1.5kW 20: 2kW 30: 3kW 40: 4kW 50: 5kW							Encoder type: L1: Standard A1: Encoder without battery
Supply voltage: 4: 400V AC							

Power supply model codes A6 Multi

MAD M P N 1 4

A	Supply voltage:
B	4: 3-phase, 400V AC
A6 Multi series	Rated power: 1: 15kW 2: 30kW
e type:	Safety function:
ower supply	N: Without safety function

Servo driver model codes A6 Multi 400V AC

	MAD	М	2	А	4	К	В	X
Frame: MAD: A MBD: B								Other Features: X: Advanced safety function
M: A6 Multi series								Network type: B: EtherCAT
Axis unit type 1: 1-axis unit 2: 2-axis unit								Supply voltage: K: 560V DC
Safety function: A: With STO								Rated power: 4: 750W 6: 1.5kW A: 3kW B: 5kW

Connections and interfaces

Connector type (200V DC: frame A - F)



PRODUCT FINDER: FOR SERVO DRIVES



Find the best servo drive within seconds!

Overview of MINAS A6 motors, servo drivers and accessories 200V AC

	Servo motor										
	Rated power W	Flange Ø mm	Max. torque Nm	Max. nom. rotation speed rpm	Motor	Holding brake	Degree of protection IP67	Key shaft	Encoder		
Low inertia 200V AC class											
	50		0.16		MSMF5AZL1U1		х	х	_		
		38	(0.48)		MSMF5AZL1V1	Х	х	х			
	100	00	0.32		MSMF012L1U1		х	х	-		
			(0.95)	_	MSMF012L1V1	Х	х	х			
	200		0.64		MSMF022L1U1		х	Х	_		
		60	(1.91)	3000	MSMF022L1V1	Х	х	х	_		
c,	400		1.27	(6000)	MSMF042L1U1		х	х			
inerti	400		(3.82)		MSMF042L1V1	Х	х	х	23 bit abso- lute encoder		
Low	750		2.39		MSMF082L1U1		Х	х	8388608ppr		
		80	[7.16]	_	MSMF082L1V1	Х	Х	х	-		
			3.18		MSMF092L1U1		Х	х	-		
	1000		(9.55)		MSMF092L1V1	Х	Х	х	-		
	1000		3.18		MSMF102L1G5		х	х			
		100	(9.55)	3000	MSMF102L1H5	Х	Х	х	-		
	1500		4.77	(5000)	MSMF152L1G5		Х	х	-		
			[14.3]		MSMF152L1H5	Х	Х	Х			
					Medium inertia 20	IOV AC class					
tia	1000 130		4.77 (14.3)		MDMF102L1G5		Х	Х			
mine		130		2000	MDMF102L1H5	Х	Х	X	23 bit abso- lute encoder		
Mediu		7.16	(3000)	MDMF152L1G5		X	X	8388608ppr			
					MDMF152L1H5	Х	Х	Х			
					High inertia 200	V AC class					
	50		0.16		MHMF5AZL1U1		Х	Х			
		40	(U.36)	_	MHMF5AZL1V1	Х	Х	Х			
	100		0.32		MHMF012L1U1		Х	Х	-		
			(1.11)	3000	MHMF012L1V1	Х	X	X	-		
	200		0.64	(0500)	MHMF022L1U1		X	X	-		
		60	(2.23)	_	MHMF022L1V1	Х	X	X	-		
tia	400		1.27		MHMF042L1U1		Х	X	22 hit ohao		
h inert			(4.40)		MHMF042L1V1	Х	X	X	lute encoder		
Higl	750		2.39		MHMF082L101		X	X	8388608ppr		
		80	(0.50)	3000	MHMF082L1V1	Х	X	X	-		
			3.18	(0000)			X	X	-		
	1000		(11.1)			Х	X	X	-		
			4.77				X	X	-		
		130	130 7.16 (21.5) 7.16	2000 (3000)		Х	X	X	-		
	1500						X	X			
					MHMF152L1H5	Х	Х	Х			

Servo drivers			Filter	Brake resistor			
		Motor	cable	Encode	Encoder cable		
Model	Frame	For motors without holding brake	For motors with holding brake	23 bit incremental	23 bit absolute	EMC filter	Model
			Low in	ertia 200V AC class			
		MFMCA0==0WJD					
MADI -05			MFMCA0==0WJD*				DWD250100
MADELUJIL	^	MFMCA0==0WJD					BWD250100
	A		MFMCA0000WJD*			FN2080-6-06	
MADI -15		MFMCA0==0WJD					
MADEUTSUU			MFMCA000WJD*		MFECA0000GJE	FS21238607	
	D	MFMCA0==0WJD		MFECAULLOWJD	(with battery box)		DWD250072
MRDF07200	В		MFMCA000WJD*	_			BWD250072
	2	MFMCA0==0WJD		_			
MCDL03500	C		MFMCA000WJD*			FN2090-10-06	
		MFMCA0000WJD					
MDDLo45oo			MFMCA000WJD*	-			
	5	MFMCD0==2GCD			MFECA0□□0GTE (with battery box)		DUUDEOOOOE
	D		MFMCA0002HCD				BWD500035
MDDLo55oo		MFMCD0==2GCD					
			MFMCA0002HCD	-			
		1	Medium	inertia 200V AC class	1		
	D	MFMCD0==2GCD		MFECA0nn0GTD			
MDDL04500			MFMCA0002HCD		MFECA0==0GTE (with battery box)		BWD500035
		MFMCD0==2GCD				FIN2090-10-06	
MDDLo55oo			MFMCA0002HCD	_			
			High in	ertia 200V AC class			
		MFMCA0007WFD					
			MFMCA0007XFD	-			
MADLo05oo		MFMCA0007WFD		-			BWD250100
	A		MFMCA0007XFD	-			
		MFMCA0000WFD		-		FN2080-6-06	
MADLo15oo			MFMCA000XFD		MFECA0	or FS21238607	
		MFMCA0000WFD		MFECA0000WJD	(with battery box)		
MBDLo25oo	В		MFMCA000XFD				BWD250072
	-	MFMCA0000WFD		-			
MCDLo35oo	С		MFMCA0==0XFD	-			
		MFMCA0000WFD		-			
MDDL=55==			MFMCA0==0XFD	-			
		MFMCD0==2GCD					
MDDLo45oo	D		MFMCE0002HCD	MFECA0==0GTD	MFFCA0nn0GTF	FN2090-10-06	BWD500035
		MFMCD0==2GCD			MFECA0==0GTE (with battery box)		
MUULo55oo			MFMCE0002HCD	1			
□ □□ Servo driver ty see Page 16	ype,	* For MSMF motors with a h	□□ = Cable len olding brake < 1.5kW, an ad for the motor	igth (m) Iditional brake cable MFM(cable.	CB0==0PJT is required		

Overview of MINAS A6 motors, servo drivers and accessories 400V AC

	Servo motor										
	Rated power W	Flange Ø mm	Max. torque Nm	Rated rota- tional speed (max.) rpm	Motor	Holding brake	Degree of protec- tion IP67	Key shaft	Encoder		
				Low	inertia 400V AC class						
	1000		3.18		MSMF104DG9		х	Х			
	1000		(9.55)		MSMF104DH9	х	х	х	_		
	1500	100	4.77		MSMF154DG9		х	х			
	1000	100	(14.3)	3000	MSMF154DH9	х	х	Х			
	2000		6.37	(5500)	MSMF204DG9		х	Х			
ertia	2000		(19.1)		MSMF204DH9	х	х	Х	23-bit encoder		
ow in	2000	100	9.55		MSMF304DG9		х	Х	8388608ppr		
_	3000	120	(28.7)		MSMF304DH9	х	х	Х			
	(000		12.7		MSMF404DG9		х	Х			
	4000		(38.2)	3000	MSMF4040H9	х	х	Х			
		130	15.9	(5000)	MSMF504DG9		х	Х			
	5000		(47.8)		MSMF504DH9	х	х	х			
				Medium inertia 40	OV AC class	<u> </u>	11				
			4.77		MDMF104DG9		x	x			
	1000	1000	(14.3)		MDMF104DH9	х	х	Х			
	1500		7.16		MDMF154DG9		х	Х	_		
	1500	100	(21.5)		MDMF154DH9	х	х	Х	_		
e.	2000	9.55 2 (28.7) (3 14.3 (43.0) 19.1	9.55	2000	MDMF204DG9		х	Х			
inerti	2000		(28.7)	(3500)	MDMF204DH9	х	х	Х	23-bit encoder		
edium	2000		14	14.3		MDMF304DG9		х	Х	8388608ppr	
Ň	3000		(43.0)	(43.0)	MDMF304DH9	х	х	Х			
	4000		19.1		MDMF404DG9		х	Х			
	4000	174	(57.3)		MDMF404DH9	х	х	Х			
	5000	170	23.87	2000	MDMF504DG9		х	Х			
	5000	(71.6)		(3000)	MDMF504DH9	х	x	Х			
				High inertia 400V	/ AC class						
	1000		4.77		MHMF104DG9		X	Х	_		
		130	[14.3]		MHMF104DH9	х	х	Х	_		
	1500		7.16		MHMF154DG9		х	Х	_		
			[21.5]		MHMF154DH9	х	х	Х	_		
a.	2000		9.55	2000	MHMF204DG9		х	Х	_		
inerti			[28.7]	(3500)	MHMF204DH9	х	х	Х	23-bit encoder		
High	3000		14.3		MHMF304□G9		х	Х	8388608-ppr		
		176	[43.UJ		MHMF304□H9	Х	х	Х			
	4000		19.1		MHMF404□G9		Х	Х			
			[5./6]		MHMF404□H9	Х	Х	Х	X		
	5000		23.9	2000	MHMF504□G9		Х	Х			
			[/1.0]	(3000)	MHMF504DH9	X	X	Х			
					□ Motor type (L1 = st	andard, A1 = encoder	without battery]				

	Servo	drivers	Cables				Brake resistor
			Motor	cable	Encoder cable	EMC filter	Model
	Model	Frame	For motors without holding brake	For motors with holding brake	23 bit, standard encoder/ encoder without battery	See page 32/33	
	Low inertia 400V AC class						
			MFMCA0001YUD				
	MDDL=64==	_		MFMCA0001ZUD			
		D	MFMCA0001YUD			Understing	BWD300130
				MFMCA0001ZUD			
	MEDL -9/25	E	MFMCA0==2YUD				
	MEDLU64UU	E		MFMCA0002ZUD			DAAD200100
			MFMCA0==2YUD		MFECA000YYE	tests	
	MFULUA4UU			MFMCA0==2ZUD			
			MFMCA0002YUD				
		F		MFMCA0002ZUD			BWD600047
	MFDLoB4oo		MFMCA0002YUD				
				MFMCA0==2ZUD	_		
				Medium inertia 400V AC	class		
	MDDLo54oo		MFMCA0==1YUD				
		_		MFMCA0001ZUD			
		D	MFMCA0=1ZUD MFMCA0=1YUD MFMCA0=1ZUD			BWD500150	
				MFMCA0001ZUD	MFECA0aa0YYE		
		E	MFMCA0002YUD				DWD500100
	MEDL08400			MFMCA0002ZUD		Undergoing tests	RMD200100
		F	MFMCA0002YUD				
	MFULUA4UU			MFMCA0002ZUD			
			MFMCA0002YUD				
				MFMCA0002ZUD			BVVD600047
	MFULUB4UU		MFMCA0==2YUD				
				MFMCA0002ZUD			
				High inertia 400V AC c	lass		
			MFMCA0001YUD				
	MDDLU34UU	D		MFMCA0001ZUD			BWD500150
		-	MFMCA0==1YUD				
				MFMCA0001ZUD			
	MEDLa84aa	Е	MFMCA0002YUD				BWD500100
				MFMCA0002ZUD	MFECA000YYE	Undergoing	
	MFDLoA4oo		MFMCA0002YUD			tests	
				MFMCA0002ZUD			
		F	MFMCA0002YUD				BWD600047
	MFDLoB4oo			MFMCA0002ZUD			
			MFMCA0002YUD				
				MFMCA0==2ZUD			
	□,□□ Servo driver type, see	Page 16		$\Box \Box = Cable$	length (m)		

MINAS A6 motors, MINAS A6 Multi servo drivers and accessories 400V AC

Servo motor					Servo motor			Servo drivers			Cables		Filter	Brake resistor
	,		E			e IP67				Motor	cable	Encoder cable		
	Rated power W	Flange Ø mm	Max. torque N	Rated rotation speed (max.	Motor	Holding brak Degree of protection Key shaft	Encoder	Model	Frame	For motors with- out holding brake	For motors with holding brake	23-bit	EMC filter	Model
							Low	inertia MINAS A6 Mu	lti 4	OOV AC class				
	750			* under	development			MADM2A4KBX		MFMCA0001YUD	 MFMCA0001ZUD			_
	1000		3.18		MSMF104DG9M	x x				MFMCA0001YUD				atio
	1000		(9.55)		MSMF104DH9M	x x x	_				MFMCA0001ZUD			plic
	1500	100	4.77		MSMF154DG9M	x x		MADMZA6KBX		MFMCA0001YUD			ENI3288-90-34	de u
e	1200	100	(14.3)	3000	MSMF154DH9M	x x x					MFMCA0001ZUD		1110200 70 04	g of
inerti	2000		6.37	(5500)	MSMF204DG9M	x x	23 bit en-			MFMCA0001YUD				ndin
Low	2000		(19.1)		MSMF204DH9M	x x x	8388608ppr				MFMCA0001ZUD			epe
	3000	120	9.55		MSMF304DG9M	x x				MFMCA0001YUD				b ng
	5000	120	(28.7)		MSMF304DH9M	x x x	MBDM1A9KBX B			MFMCA0001ZUD			lesi	
	4000		12.7		MSMF404DG9M	X X			MFMCA0002YUD				oro	
		130	[38.2]	3000	MSMF404DH9M	X X X				MFMCA0002ZUD	-	FN3288-160-40	Mot	
	5000		15.9	(5000)	MSMF504DG9M	X X	MF	MFMCA0002YUD						
			[47.8]		MSMF504DH9M	x x x					MFMCA0002ZUD			
							Mediu	m inertia MINAS A6 M	lult	400V AC class				1
	750			* under	development			MADM2A4KBX		MFMCAUDDIYUD				
-			4 77		MDME104DG9M	x x								tion
	1000		(14.3)		MDMF104DH9M	x x x					MFMCA0001ZUD			olica
	1500		7.16		MDMF154DG9M	x x	_	MADM2A6KBX		MFMCA0001YUD				app
tia	1500	100	(21.5)		MDMF154DH9M	x x x			A		MFMCA0001ZUD		FN3288-90-34	d on
iner	2000	130	9.55	2000	MDMF204 G9M	x x	23 bit en-			MFMCA0001YUD				din
dium	2000		(28.7)	(3500)	MDMF204 H9M	x x x	8388608ppr				MFMCA0001ZUD	MFECAULLUTTE		ber
Me	3000		14.3		MDMF304DG9M	x x				MFMCA0001YUD				n de
			[43.0]		MDMF304DH9M	x x x					MFMCA0001ZUD			esig
	4000		19.1		MDMF404DG9M	X X				MFMCA0002YUD				or de
		176	(57.3)		MDMF4040H9M	X X X	_	MBDM1A9KBX	В		MFMCA00022UD		FN3288-160-40	Moto
	5000		23.87	2000			_							-
			((,	10101011 3040117101	^ ^ ^	Hiah	inertia MINAS A6 Mu	lti /	ANNY AC class				
	750			* undor	dovelopment					MFMCA0001YUD				
-	1 00			unuer			_				MFMCA0001ZUD			_
	1000		4.77		MHMF104DG9M	XX	_			MFMCAUDD1YUD				atio
		130	(14.3)			X X X	_	MADM2A6KBX			MFMCAUDD1ZUD			plic
	1500		7.16			X X			Δ	MFMCAUDDIYUD			FN3288-90-34	n ap
ia			0.55	0000		X X X					MFMCAULLIZUD		1110200 /0 01	o br
inert	2000		9.55 (28.7)	(3500)			coder					MFECA0DDVYE		ndir
High			1/ 0	(0000)			8388608ppr	MADM2AAKBX						lepe
	3000		(43.0)			x x v	_							gn a
		176	10 1		MHMF404nG9M	XX	-			ΜΕΜΟΑΩΠΠ2ΥΙΙΠ				Jesi
	4000		(57.3)		MHMF404nH9M	x x x	-							tor
			23.9	2000	MHMF504DG9M	x x	-	MBDM1A9KBX	В	MFMCA0002YUD			FN3288-160-40	Mo.
	5000		(71.6)	(3000)	MHMF504DH9M	x x x	-				MFMCA0002ZUD			
					□ Motor type A1 = encoder	e (L1 = s withou	standard, it battery)				ı = Cable length (m)		

MINAS A6N with RTEX protocol

RTEX (Realtime Express)

Thanks to its high transmission speed and sampling rate, this fast, real-time Ethernet bus for automation is particularly well suited for highly dynamic single and multiple axes position control tasks. The communication between master and slaves happens in real time.

Easy mounting and reliable connections thanks to ring topology



MINAS A6B with EtherCAT protocol

EtherCAT (Ethernet for Control Automation Technology)

This Ethernet-based field bus system offers similiarly outstanding features like RTEX. However, unlike RTEX, EtherCAT is an open, standardized field bus. This has the advantage that data can be exchanged with other servo drivers if they have an EtherCAT port.





For more data about MINAS A6 servo controllers and motors such as technical data, dimensional diagrams, and torque characteristics, please use this download link:



Examples of servo motor torque characteristics



Examples of servo motor dimension diagrams

MSMF - low inertia (50-1500W, 200V AC)





MINAS A6V servo drives (24/48V DC)

Low voltage, high performance

Features:

- > Servo drives and servo motors
- > 24/48V DC input voltage
- > 200W or 400W
- > 23-bit absolute encoder
- > Modbus RTU communication
- > Position, rotational speed, and torque control
- > Pulse train with up to 500kpps (kpps = thousand pulses/second)
- > Rated rotational speed 3000rpm

Battery-driven DC drives are very common in drive technology for applications where there is no AC or three-phase current network available. Especially in the area of drive technology for vehicles and the medical field there is a need for motors with battery voltages. These motors round off Panasonic's portfolio of drive technology products.

Μ

Servo driver specifications:

Туре		Ać	V	
Supply voltage		24/48V DC	48V DC	
Rated current		8.0	бА	
Max. rated current		24.	3A	
Rated power		200W	400W	
Control mode		Position control, velocity control, t	orque control, full-closed control	
Positioning with digital I/Os (block operation t	table)	Yes		
Control input		Pulse, analog		
Encodor foodbook	Rotating	23-bit abso	lute, serial	
	Linear	-		
External encoder		Yes		
Communication		USB, RS232, R	S485, Modbus	
Inputs		5 multifunction inputs, 2 pulse	inputs, 1 analog input, Modbus	
Outputs		3 multifunction outputs, A	VB/Z-phase pulse output	
Weight		0.35kg approx.		
Dimensions (W x H x D in mm)		90 x 30	0 x 180	

Servo motor specifications:

Туре		Ad	5V		
Rated power		200W	400W		
Flange diameter		60mm			
Supply voltage		24/48V DC	48V DC		
Rated rotational speed		3000	rpm		
Max. rotational speed		3000rpm			
Motor length (without shaft)		79.5mm	99mm		
External encoder		Yes			
Encodor	Resolution	23 bit absolute			
Elicouel	Multi turn	23 bit	23 bit		
IP degree of protection (motor)		IP65			
Rated torque		0.64-1.27Nm/0.64-1.91Nm	1.27-2.54Nm		
Peak torque		1.27-2.54Nm			

Types:

MINAS A6V	Rated power	Supply voltage	Туре
Canva drivara	2001/// 001//	24V DC	MVDLN5CSF
Servo arivers	200040000	48V DC	MVDLN5BSF
		20100	MSMD02CL1S
	20014/	24V DC	MSMD02CL1T
Conversion market	20077		MSMD02BL1S
			MSMD02BL1T
	(00)4/	48V DC	MSMD04BL1S
	40000		MSMD04BL1T

Applications:





Robots

Medical technology, laboratories



AGVs (automated guided vehicles in households and warehouses, lawnmowers, etc.)

All dimensions are in mm

Cables

Cable (servo	motor – servo driver), 200V DC		
	MSMF motors 50W–1kW	MFMCA0==0WJD	
t holding brake	MHMF motors 50W/100W	MFMCA0==7WFD	(25.9) (20) (20) (20) (20) (20) (3) (50)
For motors witho	MHMF motors 200W–1kW	MFMCA0==0WFD	(20, 6) (20) (20) (20) (20) (20) (20) (3) (50)
	MSMF motors 1–2kW MDMF motors 1–2kW MHMF motors 1–1.5kW	MFMCD0==2GCD	
Brake cables	MSMF motors 50W–1kW	MFMCB0==0PJT	
	MHMF motors 50W/100W	MFMCA0007XFD	xx represents the cable length in meters: e.g. 10 + 10m x + 0 These facting block Cable outriseonting to DEBNA remark.
For motors with holding brake	MHMF motors 200W–1kW	MFMCA0==0XFD	xx represents the cable length in materix. e.g. 10 = 10m v =
	MSMF motors 1–2kW 200V MDMF motors 1–2kW 200V	MFMCA000 2HCD	20 mm 150 mm 150 mm 150 mm 100 mm 100 mm 30 mm
		$\Box \Box = Cable length (m)$	

All dimensions are in mm



Cable	Cable (servo motor – servo driver), 400V DC and MINAS A6 Multi series								
ut holding brake	Motors 200W–1.5kW	MFMCA0==1YUD							
For motors withou	Motors 2kW–5kW	MFMCA0==2YUD	E CITOR SCARET						
h holding brake	Motors 200W–1.5kW	MFMCA0==1ZUD							
For motors wit	Motors 2kW–5kW	MFMCA0==2ZUD	60 = 0.5 collo data diameter collo data diameter di monto PROT di monto Proto Proto Proto Proto Proto Proto Proto Proto di monto Proto Proto Proto Proto Proto Proto Proto Proto di monto Proto						

Encoder cable (se	ncoder cable (servo motor – servo driver), 400V DC and MINAS A6 Multi series							
For motors with 23-bit encoder	Motors 200W–5kW	MFECA0000YYE	S 15.000 CARLE 50.00 3- - 35.001 N - 20.0					
		$\Box \Box = Cable \ length \ (m)$						

All dimensions are in mm



Other accessories:

	Product no.	Details/Comment	s/Dimensions						
	Control cable 200/400V AC								
	DV0P4360	50W-5kW	50-pin	I/O cable X4, loose wire:	s, 2m				
	DVOP4360P	50W-5kW	50-pin	I/O cable X4, loose wire:	s, 2m, position control				
les	DVOP4360V	50W-5kW	50-pin	I/O cable X4, loose wire	s, 2m, velocity control				
Cat	DV0PM20024CAB020	50W-5kW	8-pin	Communication cable X2, RS485, RS232, loose wires, 2m					
	DV0PM20025CAB020	50W-5kW	8-pin	Safety function cable X3	Safety function cable X3, loose wires, 2m				
	DV0P0800-EU	50W-5kW	26-pin	I/O cable X4, loose wire:	s, 2m				
	Programming cable 200/400V AC								
	CABMINIUSB5D	50W-5kW	USB						
	Connector act for corve driver 200V A	<u> </u>							
			50 pip	1/0c X/					
	DV0P4330-E0	50W-5kW	26-pin	1/US, X4					
		50W_5kW	20-piii	Fytorpal opcodor coppo	ictor Y5				
	Connector set encoder servo motor v	vithout holding brake	2007 80	Externat encoder conne					
	DV0PM24581-FU	50/100W	_						
÷	DV0PM24582-EU	200W-1kW	_						
or se	DV0PM20035-FU	50W-1kW	_	MINAS A6 MSME, IP67					
nect	DV0PM20036-EU	1kW-2kW	_	MINAS A6 MSME, MDME: MHME 1–1.5kW					
Con	DV0PM20036A	1kW-2kW	_	Angled type: MINAS A6 MSMF, MDMF; MHMF 1–1,5kW					
	Connector set encoder, servo motor v	vith holding brake 20	OV AC						
	DV0PM20040-EU	50W-1kW	_	MINAS A6 MSMF, IP67					
	DV0PM20038-EU	1kW-2kW	-	MINAS A6 MSMF, MDMF; MHMF 1–1,5kW					
	DV0PM20038A	1kW-2kW	-	Angled type; MINAS A6	MSMF, MDMF; MHMF 1–1,5kW				
	Connector set for servo drives 400V AC								
	DV0PM14576-EU	1kW-5kW	-	For mounting motor an	d encoder cables				
	FMC (14 2001/ AC								
			1	2501/40					
	FIN2080-0-00	5000-75000	I-phase	25UV AC					
	FN2090-10-06	1kW-1.5kW	1-/3-phase	250V AC					
	FS21238607	50W-750W	1-phase	Footprint filter, 250VAC					
	FN3268-7-44	1kW-3kW	3-phase	400V AC					
	FN3268-16-44	4kW-5kW	3-phase	400V AC					
	DVUP1460	JUVV-ZZKVV	I-pnase	Ferrite core, noise litter					
	PWD250100	50\// 100\//	1 phace		110 x 90 x 15 (L x W x D in mm)				
	BWD250072	200\/_750\/	1-phase	720 100W 400V AC					
	BWD500035	1kW_15kW	1-phase	350, 200W, 600V AC	216 x 80 x 15 (L x W x D in mm)				
SIII	EMC filter 400V AC (undergoing to		i pilase	5512, 20011, 0001 AC					
lanec	EN3258-16-44	1kW-2kW	3-phase	400V AC					
scel	EN12250 20 22		2 phase						
Σ	110220-30-33	JKW-JKW	5-pilase	400V AC					
	Braking resistors 400V AC			4500 40004 40004 40					
	BWD500150	IKW-1.5KW	3-phase	1500, 100W, 600V AC	216 x 80 x 15 (L x W x D in mm)				
	BWD500100		3-phase	1000, 10000, 6000 AC	216 X 80 X 15 (L X W X D In mm)				
	EMC filter MINAS A6 Multi (00V AC	SKVV-SKVV	o-phase	4711, 240(400)W, 600W AC					
	ENI3288_80_3/	1kW_3kW	3-phace		ti power supply 15kW				
	EN3288-140-40	(kW-5kW	3-phase	530V AC, MINAS A6 Mul					
	Braking resistors MINAS A6 Multi And		l o buase	500 AO, MINAS AO MUI	a power supply solver				
	Motor design depending on	application							
	Miscellaneous MINAS A6 Multi 400V	AC							
	DV0PM24621-EU	USB license o	longle "PANATF	ERM for Safetv"					
			<u> </u>						

EMC filter

200V AC:

FN2080-6-06 for servo driver MINAS A6 50-750W, 1-phase / FN2090-10-06 for servo driver MINAS A6 1-1.5kW, 1-phase





Dimensions (mm)	FN2080-6-06	FN2080-10-06
A	113.5	156
В	57.5	57.5
С	45.4	45.4
D	94	130.5
E	56	56
F	103	143
G	25	25
Н	12.4	12.4
1	32.4	32.4
J	15.5	15.5
K	4.4	5.3
L	6	6
М	1	1
Ν	6.3 x 0.8	6.3 x 0.8

FS21238607 for servo driver MINAS A6 50-750W, 1-phase



DV0P1460 with ferrite core



400V AC (filters are undergoing tests):

FN3258-16-44 for servo driver MINAS A6 1-2kW, 3-phase / FN3258-30-33 for servo driver MINAS A6 3-5kW, 3-phase





Dimensions (mm)	FN3258-16-44	FN3258-30-33
A	190	270
В	40	50
С	70	85
D	160	240
E	180	255
F	20	30
G	4.5	5.4
Н	1	1
	22	25
J	M5	M5
K	20	25
L	29.5	39.5

MINAS A6 Multi 400V AC:

FN3288-80-34 for servo driver MINAS A6 Multi 1–3kW / FN3288-160-40 for servo driver MINAS A6 4–5kW





Dimensions (mm)	FN3288-80-34	FN3288-160-40
A	175	4.5
В	180	5.4
С	195	5.4
D	220	5.4
E	240	5.4
F	270	6.5
G	280	6.5
Н	290	6.5
	220	4.5
J	215	5.4
K	230	5.4
L	250	5.4
М	250	5.4
Ν	290	6.5
0	300	6.5
Р	310	6.5
Q	170	4.5
R	185	5.4
S	190	5.4
Т	200	5.4

RTEX - the multiaxis Ethernet servo system

The RTEX positioning units support MINAS A6N network servo drives. A mutually optimized system consisting of PLC and servo driver greatly simplifies installation and reduces time needed for design.

Commercially available Ethernet cable (shielded, category 5e)



FPWIN Pro

The main advantages of the RTEX positioning units:

- > Unique: Allows easy control of network servos with an ultracompact PLC.
- > Allows highly accurate control of multi-axis position control using high-speed 100Mbit/s communication.
- > Minimization of wiring costs by using commercially available Ethernet cables.
- > **Position control** of 4 or 8 axes for servo drivers with Ethernet (RTEX) interface.
- **Easy** configuration with the software Control Configurator PM instead of complex programming.
- > Includes manual pulser input allowing support for **precision teaching**.

System configuration

Panasonic's compact PLC FP0H can be easily expanded with up to 2 RTEX positioning units (max. 2 x 8 axes + 4 axes (CPU)).

Product		Number of axes	Output type		Product no.
		4	RTEX Ethernet	Electronic gear, electronic clutch, electronic cam control	AFP0HM4N
Positioning units FPUH		8			AFP0HM8N
Control Configurator PM For all RTEX units			AFPS66510		

Motion control libraries for Control FPWIN Pro (PLC)

The motion control library contains the most important function blocks, e.g.

- > for relative or absolute position control
- > and for home returns with linear axes.

Panasonic offers libraries for all motion control tasks.

CPU Motion Control Library

PP Motion Control Library

- Position control with FP series control units (FPOR, FP-X, FPXH, FP0H, FP7)
- > Positioning with PP motion control unit FP0H
- > FP7: Library is included in the PLC programming software Control FPWIN Pro.

RTEX Motion Control Library

Positioning with RTEX positioning unit FPOH

Time chart

Simply download the software from the Panasonic website: <u>https://industry.panasonic.eu/downloads</u> Downloads -> Programmable controllers -> PLC software -> Software -> Library

Advantages of PLC programs using the Motion Control Library

- > Free just download it from Panasonic's website
- > Simple easy programming and installation
- > Efficient ready-made function blocks, set parameters instead of writing complex programs
- > Compliant compliant with IEC 61131-3
- Universal hardware-independent (works for every Pana-> sonic PLC)

Function block from the MC_CPU_Library Motion library used for an application

- > Flexible expandable for up to 256 axes
- > Fast fast and easy commissioning (ready-to-use example programs)



Drilling setup







Modbus RTU protocol

Advantages



Field Bus

Improved performance Improved functions > No position deviation caused by lost > Editing parameters (moment of pulse signals (considerably inertia, damping frequency) improved reliability) > Servo data logging (collection of

machines)

data related to the utilization factor and torque for remote monitoring of

Reduced cost

- > Easy adding and removing of axes (simplified wiring thanks to bus system)
- > Less time needed for commissioning, e.g. thanks to instantaneous registration of the axis position

Features

- > MINAS A6 series field bus
- > Modbus RTU is an open, serial (RS232 or RS485) protocol based on a master/slave or client/server architecture.
- > Widely used protocol due to its ease of operation and reliability
- > Cost-effective solution for programmable controllers based on RS485
- > Controlling a servo drive system based on the CANopen motion control profile CiA is possible

Simple complete motion control solution with one Panasonic compact PLC

Modbus RTU library for Motion Control



Direct access to servo drive parameters from the PLC

Libraries

The libraries enable serial communication (RS232, RS485) between the FP series PLCs and servo drivers of the MINAS A6 series.

- > The communication protocols for the drivers are also included in the libraries.
- > The libraries allow full read and write access to the parameters.
- > They also record the status and position data of the axes.
- > The RS232 interface (optional RS485) is already included with the FP series.

Panasonic Control FPWIN Pro

> With RS232 connections, the first driver can be used as a gateway to downstream drivers so that all drivers can communicate with the PLC.

Communication via RS232

Communication software

FP series PLCs



Communication via RS485

Communication software

FP series PLCs





Software Configurator PM for RTEX

User-friendly, user-friendly commissioning

The Configurator PM offers numerous configuration options

- > Axis and parameter settings
- > Data table creation
- > JOG operations

Panasonic Control Configurator PM water

- > Home return
- > Data monitor settings
- > and other settings for easy test operation

Parameter settings

The details of the settings can be displayed in a table. Details on how to create settings for each category are explained in the box below. Parameters can be copied between axes.

Advantage: In instances where many settings are shared among the axes, this can reduce the number of repeat inputs.

Data table creation

- > User-friendly data entry similar to an Excel sheet
- > Data tables are displayed in an easy-to-understand manner
- Export of data tables to CSV format for document management systems, etc.
- > Data ranges of a CSV file can be added to a table quickly with cut and paste
- > A separate table for each axis (or each set of interpolation axes)

Advantage: Data is clearly arranged for fast easy handling

Tool operations

Each axis can be operated by test sequences independently of the operation modes (PROG and RUN) of the RTEX unit (or the programmable controllers).

JOG operation and teaching can be carried out easily to index positioning points. Test operation is possible without having to create a rudder program.

Advantage: Trial operation in advance saves time

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art Letter	Pailet	Paula	Paslee .	Paulos	Paulue
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to a next sinkar per central					
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Configuring servo drivers

PANATERM configuration software

For MINAS AC servo motors & drive amplifiers

PANATERM assists users in making parameter and control settings as well as creating and analyzing data tables during operation. The software can be installed on any commercially available personal computer. The connection to the MINAS series is established via the USB port.

Setup and basic functions

- > Auto-tuning
- > Gain adjustment and inertia ratio measurement
- Line graph display The line graph diagram shows command and current velocity, torque, and the tracking error.
- > Display of the absolute encoder settings
- > Parameter setting

After a parameter has been defined on the screen, it will immediately be sent to the driver. Frequently used parameters can be listed separately in a second display.

Monitoring function

Parameters and status can be monitored, e.g. operation mode, speed, torque, error and warning. overview of command/feedback pulses, load ratio, regenerative resistive load ratio and many more.

Analysis of mechanical operation data (frequency analysis)

Frequency characteristics of a machine can be measured for display in a Bode diagram.







Line graph display









Software for designing drives

M-SELECT software

40

M-SELECT is a software program to help you select the correct motor capacity and servo driver from Panasonic's MINAS series. Find the optimal type of motor with regards to the mechanical layout and the dynamic requirements. It is a very valuable tool for mechanical engineering as it also provides CAD data in 2D and 3D. The software offers a complete analysis and detailed usage instructions for the MINAS series in all sizes.



Selecting the motor capacity in just four steps:

1. Select mechanical parts and input their parameters (figure 1)

The user can select parts from a database with all mechanical standard parts (gears, coupling, spindle axis, etc.).

2. Determine the motion profile (figure 2)

Display and determine speed, position and ramps, etc.

3. Select the correct motor series (figure 3)

- > 1- or 3-phase
- > Input voltage
- > Specify torque, etc.

The software calculates the parameters for the selected series. The various criteria are evaluated with OK or NG (not good).

4. Result (figure 4) Check and print result







Quick start guides

The Quick start guides are intended to help you set up a MINAS servo drive system.

They are based on information from the MINAS series manuals and the practical experience of our engineers. Step-by-step instructions will guide you through connecting a PLC to a MINAS servo driver and setting the most important parameters in the PC configuration software PANATERM.



More Quick start guides for the MINAS series are being prepared.

MINAS A6 series servo drives

Highly dynamic servo drives with state-of-the-art technology. Large power range (50W to 5kW) combined with a light-weight and compact design. Innovative functions for damping resonance frequencies and to eliminate vibration tendencies. Multiple control features such as pulse, analog, and network technology in real-time communication (100Mbit/s). (See page 10)

B M

Motion control libraries, configuration and programming software

The PLC programming software Control FPWIN Pro (compliant with IEC 61131-3) and the free configuration software PANATERM and M-SELECT shorten the time required for commissioning In addition, you can download motion control libraries for free. By using the function blocks integrated in the freely available motion control libraries, complex positioning tasks can be solved quickly and efficiently. (See Page 35)

MOTION CONTROL COMPREHENSIVE SOLUTIONS

HM and GT series touch terminals

Touch terminals allow humans and machines to interact with each other. The machine's role therein is to display data, results, messages, etc. and to receive instructions and execute tasks assigned by operators. Panasonic's innovative touch terminals are ideally suited for these tasks. They are optimally suited both for factory and building automation. Panasonic HMIs cover a wide spectrum, ranging in size from a compact 3" touch terminal to a color 21" display for sophisticated applications.



С

FP series PLCs

The PLC comes already equipped with the functionality required for position control tasks. FPOR and FP-X are capable of controlling up to 4 axes independently. The FP-XH has an integrated Ethernet-based communication bus (RTEX), and the CPU of the FPOH can be expanded with modular positioning units to control up to 20 axes. The modular FP7 series can control 64 axes independently or synchronously in the network.



MINAS A6 SERIES: COMPACT, LIGHT AND POWERFUL

As fast as our large motors!



Global Network



Panasonic Electric Works

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