# Ultra High-speed Laser Displacement Sensor CCD Style

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This product is classified as a Class 2 / Class 3B Laser Product in IEC / JIS standards and a Class II / Class IIIb Laser product in FDA regulations 21 CFR 1040.10.

Never look at or touch the direct laser beam and its reflection.

# High speed of 100 µs, Ultra high-speed & stable measurement for a variety of measurement objects

#### 100 µs, fast sampling rate

Ultra high-speed sampling of 100 µs has now been achieved. Thus enabling ultra high-speed measurement of rotating, vibrating and moving objects.

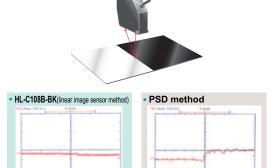
#### Resolution of 1 $\mu$ m 0.039 mil, linearity of ±0.1 % F.S.

Now available with ultra-precise 1 µm 0.039 mil resolution measurement capability (HL-C105□) and a linearity of ±0.1 % F.S. (for all models).

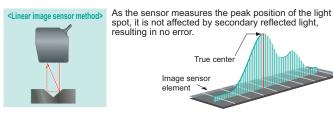
#### High precision measurement is now possible, unaffected by the surface condition of the detected object

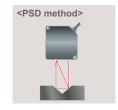
All deficiencies inherent in the conventional PSD sensing method have now been solved. Whereas the PSD method measures position information from the center of gravity of the total light quantity distribution of the light spots connected along each light element, the linear image sensor method measures the peak position values of the light spots themselves. This advancement now makes high-precision measurement possible, regardless of the surface condition of the object whether for metal hairline surface cracks or for non-reflective black rubber.

#### Change in measurement data due to color difference (White ceramic / Black rubber)

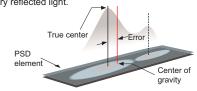


#### Principle For detection of a V-shaped groove





As the sensor measures the center of gravity of the entire light quantity distribution of the beam spot as position information, errors occur due to the presence of secondary reflected light.

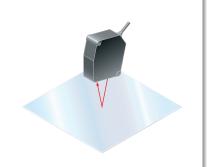


# FDA regulations conforming types are available

FDA regulations conforming types, most suitable for equipment used in the USA, are available.

#### APPLICATIONS

#### Measuring glass substrate thickness

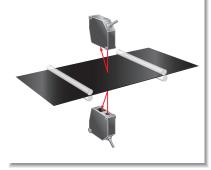


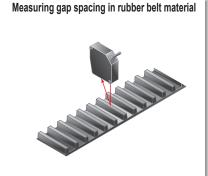






Measuring the thickness of rubber sheet





# Inspecting tire form



Sensor heads HL-C135C-BK10 Controller HL-C1C-M-WL

# The long and wide range

#### Measures wide changes over long ranges

The long and wide range capabilities over 350 mm ±200 mm 13.780 in ±7.874 in allow large changes to be measured. Even if the object position changes, there is no need to change the sensor head settings or position.

#### High speed and high precision even over long and wide ranges with an ultra-small type head

High-speed and high-precision performance has been achieved in an ultra-small head of W26.6 × H82 × D87 mm W1.047 × H3.228 × D3.425 in with high-speed sampling of 100 µs at a resolution of 10 µm 0.394 mil, and a linearity of ±0.1 % F.S.



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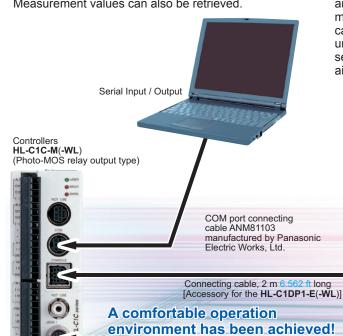
Selection Guide Magnetic Displacement Collimated Beam Digital Panel Controller Metal-sheet Double-feed Detection

HL-G1 HL-C2

HL-C1 LM10

# Equipped with serial input / output

An RS-232C interface for serial input and output is provided so that settings can be retrieved and saved. Measurement values can also be retrieved.



Sensor heads <IEC / JIS standards conforming type> HL-C135C-BK10 HL-C108B-BK

HL-C105B-BK HL-C108B HL-C105B

<FDA regulations conforming type>

HL-C135C-BK10 HL-C108F-BK HL-C105F-BK HL-C108F HL-C105F

## 2 sensor heads can be connected! Reduces costs and saves space

The controller, to which 2 sensor heads can be connected, incorporates 2 separate input / output

This feature saves the expense and space usually required by a second controller, whenever 2 sensor heads are used.

# Waterproof sensor head construction, compliant with IP67 rated protection

The HL-C1 series can withstand water splashes.

Extension cables HL-C1CCJ2 (2 m 6.562 ft) HL-C1CCJ5 (5 m 16.404 ft)

HL-C1CCJ10 (10 m 32.808 ft) HL-C1CCJ20 (20 m 65.617 ft)

HL-C1CCJ30 (30 m 98.425 ft)



Note: Accurate measurement cannot be performed if water is present on the sensing window of the sensor head

# A convenient intelligent monitor (HL-C1AiM) is available (Optional)

An intelligent monitor is provided capable of the waveform display of each measurement condition setting and of measurement values as well as monitoring of measurement data and received light intensity data. It can perform waveform monitoring that was only possible until now with a conventional oscilloscope and can easily set each measurement condition and function with the aid of a PC.

# Touch panel operation, easy and compact

Compact consoles HL-C1DP1-E(-WL)

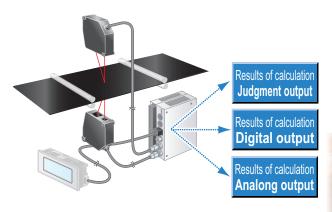
A variety of settings and measurement data can be displayed easily. (Optional)

# Easy maintenance with sensor head compatibility

Maintainability has been significantly improved. Compatibility has been achieved through the incorporation of correction data into the sensor heads themselves. This sensor series no longer needs the amount of maintenance usually required for conventional displacement sensors of this class.

#### Calculations can be performed when 2 sensor heads are used

The built-in calculation function allows measurement of gap and thicknesses without requiring a digital panel controller, thus saving further on costs and space.



#### Compact controller and front connection reduce setup space

The ultra-compact controller **HL-C1C-M** with dimensions of W40 × H120 × D74 mm W1.575 × H4.724 × D2.913 in requires much less space for installation. Tight installation is also possible. Furthermore, the cables can be connected directly or to a removable terminal block, so that all connections come from the same direction in order to further save space.



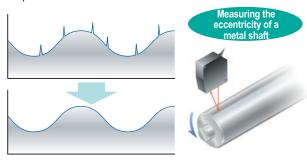
# **Enhanced functionality**

The **HL-C1** series incorporates a great number of useful function, including hold function, calculation function, filter function and a hysteresis-setting function, which facilitate convenient usage in a variety of diverse applications.

#### Low-pass / High-pass filter functions

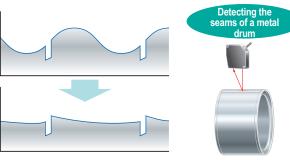
#### <Low-pass filter function>

For example, if the surface conditions of a metal object cause noise that interferes with accurate measurement, the use of the low-pass filter function will reduce the effects of noise and allow for the stable measurement of displacement.



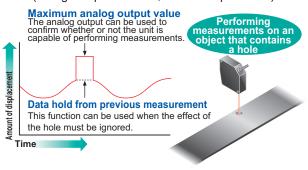
#### <High-pass filter function>

When measuring seams and gaps in objects that undergo large displacement changes due to vibration or tilting, such as measuring the eccentricity of a rotating object, this function will minimize the effects of these undulations and enable the accurate measurement of seams and gaps.



# Analog output switching function during alarm output

During measurement, if the unit becomes incapable of performing measurements due to excessive or insufficient incident light intensity (during alarm output), this function allows the analog output to be switched to either hold the data obtained just previously, or to output a fixed value. If the fixed value is selected, one of two options can be chosen for the analog output during alarm output: the output of the maximum value (voltage output: +10.9 V, current output: 29.5 mA) or the output of the minimum value (voltage output: -10.9 V, current output: 0 mA).



#### **Hold functions**

The **HL-C1** series incorporates 4 hold modes.

NORM (no hold)	This mode outputs the amount of displacement from the measurement center distance in real time. This mode is utilized for general-purpose operation.
P-P	This mode holds the output at the difference between the maximum and minimum measured values. This mode is utilized for vibration or eccentricity measurements.
PEAK	This mode holds the output at the maximum measured value.
VALLEY	This mode holds the output at the minimum measured value

## Data buffering function

It is possible to accumulate data up to 48,000 data into a controller temporarily in order to capture measurement data into a PC. All the accumulated data can be captured into the PC with **HL-C1AiM**. Used for reading and storing all data including the verification of measurement data when introduced as well as all post-measurement data.

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Digital Panel

### ORDER GUIDE

#### **Sensor heads**

Ту	pe	Appearance	Measurement center distance	Resolution (Note 1, 2)	Beam diameter	Model No.	Applicable controller	Applicable console	Conforming standards / regulations
e type	Wide range	*	350 mm 13.780 in (Measuring range ±200 mm 7.874 in)	10 µm 0.394 mil	400 × 200 μm 15.748 × 7.874 mil approx.	HL-C135C-BK10	HL-C1C-M-WL	HL-C1DP1-E-WL	IEC / JIS / FDA
Diffuse reflective type	General purpose			2 µm	100 × 140 µm 3.937 × 5.512 mil	HL-C108B-BK			IEC / JIS
fuse re			85 mm 3.346 in (Measuring range ±20 mm 0.787 in)	0.079 mil	approx.	HL-C108F-BK			FDA / IEC / JIS
Dif	ecision			1 µm	70 × 120 μm	HL-C105B-BK			IEC / JIS
	High precision		50 mm 1.969 in (Measuring range ±5 mm 0.197 in)	0.039 mil	2.756 × 4.724 mil approx.	HL-C105F-BK			FDA / IEC / JIS
ype	General purpose	*		2 µm	100 × 140 µm 3.937 × 5.512 mil	HL-C108B	HL-C1C-M	HL-C1DP1-E	IEC / JIS
flective t	General		81.4 mm 3.205 in (Measuring range ±16 mm 0.630 in)	0.079 mil	approx.	HL-C108F			FDA / IEC / JIS
Specular reflective type	High precision	****		1 µm	70 × 120 µm 2.756 × 4.724 mil	HL-C105B			IEC / JIS
Spe	High pr		46 mm 1.811 in (Measuring range ±4 mm 0.157 in)	0.039 mil	approx.	HL-C105F			FDA / IEC / JIS

Notes: 1) These values were obtained by converting P-P values into a distance. The P-P values indicate the distribution of measured values throughout the measurement center distance.

2) These values were obtained with an average number of samples: 256, when using an object made of our company's standard white ceramic for measurement (an aluminum vapor deposition surface reflection mirror was used with specular reflective types).

#### **Controllers**

Туре	Appearance	Model No.	Judgment outputs
Standard		HL-C1C-M	Photo-MOS relay
For <b>HL-C135C-BK10</b>		HL-C1C-M-WL	

#### **Compact consoles**

Туре	Appearance	Model No.
Standard	The same time same	HL-C1DP1-E
For <b>HL-C1C-M-WL</b>		HL-C1DP1-E-WL

#### ORDER GUIDE

#### Sensor head extension cable

Appearance	Model No.	Description	
	HL-C1CCJ2	Length: 2 m 6.562 ft, Net weight: 160 g approx.	
	HL-C1CCJ5	Length: 5 m 16.404 ft, Net weight: 350 g approx.	Cabtyre cable with connector on both ends
	HL-C1CCJ10	Length: 10 m 32.808 ft, Net weight: 700 g approx.	Cable outer diameter: ø7 mm ø0.276 in Connector outer diameter: ø14.7 mm
	HL-C1CCJ20	Length: 20 m 65.617 ft, Net weight: 1,400 g approx.	ø0.579 in max.
	HL-C1CCJ30	Length: 30 m 98.425 ft, Net weight: 2,000 g approx.	

#### Intelligent monitor

Appearance	Model No.	Description
Intelligent Monitor HLC1AIM  Advanced  Affanber  Affanbe	HL-C1AiM	Enables the waveform display of each measurement condition setting and of measurement values as well as monitoring of measurement data and received light intensity data.  1pc. of COM port connection cable manufactured by Panasonic Electric Works, Ltd. is attached.

#### **SPECIFICATIONS**

#### Sensor heads

Ser	isor neads					
	_		Diffuse reflective type			
Тур		Wide range	General purpose	High precision		
\	\ 릴 IEC / JIS standards conforming type	III 04050 BK40	HL-C108B-BK	HL-C105B-BK		
Iter	m\ FDA regulations conforming type	HL-C135C-BK10	HL-C108F-BK	HL-C105F-BK		
Mea	asurement center distance	350 mm 13.780 in	85 mm 3.346 in	50 mm 1.969 in		
Mea	asuring range	±200 mm 7.874 in	±20 mm ±0.787 in	±5 mm ±0.197 in		
Res	solution (Note 2, 3)	10 μm 0.394 mil	2 μm 0.079 mil	1 µm 0.039 mil		
Line	earity (Note 4)		±0.1 % F.S.			
Temperature characteristics			0.02 % F.S./°C			
Laser emission indicator		Green LED (lights	up during laser emission or immediately bef	fore laser emission)		
Measuring range indicator		Yellow LED (blinks within the measuring range and lights up when near the measurement center distance)				
eou	Pollution degree		3 (Industrial environment)			
star	Protection	IP67 (IEC)(excluding the connector)				
resi	Ambient temperature	0 to +45 °C +32 to +113 °F (No dew condensation), Storage: -20 to +70 °C -4 to +158 °F				
ntal	Ambient humidity	35 to 85 % RH, Storage: 35 to 85 % RH				
ıme	Ambient illuminance	Incandescent light: 3,000 & at the light-receiving face				
Environmental resistance	Vibration resistance	10 to 55 Hz (period: 1 min.) frequ	uency, 1.5 mm 0.059 in amplitude in X,Y an	d Z directions for two hours each		
E	Shock resistance	196 m/s² accelerat	ion (20 G approx.) in X,Y and Z directions for	or three times each		
Emi	itting element	Red semiconductor laser, Class 3B (Class III b for FDA regulations) (Max. output: 10 mW, Peak emission wavelength: 658 nm 0.026 mil)	Red semiconductor laser, Class 2 (Class I (IEC / JIS standards conforming type: IEC FDA / IEC / JIS) (Max. output: 1 mW, Peal	/ JIS, FDA regulations conforming type:		
Bea	ım diameter (Note 5)	400 × 200 μm 15.748 × 7.874 mil approx.	100 × 140 μm 3.937 × 5.512 mil approx.	70 × 120 μm 2.756 × 4.724 mil approx.		
Red	ceiving element	Linear image sensor				
Enc	losure earthing	Floating				
Mat	erial	Enclosure: Die-cast aluminum, Case cover: Die-cast aluminum, Front cover: Glass				
Cab	ole	Cabtyre cable, 0.5 m 1.640 ft long with connector				
Cab	ole extension	Extension u	p to total 30 m 98.425 ft is possible, with op	tional cable.		
Wei	ght		Net weight: 300 g approx.			
Acc	essory	English warning label: 1 set [The FDA regulations conforming type includes a set of both the IEC label (written in English) and JIS label (written in Japanese)].				

Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were as follows: supply voltage 24 V DC, ambient temperature +20 °C +68 °F, sampling rate 100 µs, average number of samples: 256 (HL-C135C-BK10: 512), object measured at measurement center distance is made of white ceramic (an aluminum vapor deposition surface reflection mirror was used with specular reflective type). Linearity also depends upon the characteristics of the object being measured.

- aluminum vapor deposition surface reflection mirror was used with specular reflective type). Linearity also depends upon the characteristics of the object being measured.

  2) These values were obtained by converting P-P values into a distance. The P-P values indicate the distribution of measured values throughout the measurement center distance.
- 3) These values were obtained with an average number of samples: 256 (HL-C135C-BK10: 512), when using an object made of our company's standard white ceramic for measurement (an aluminum vapor deposition surface reflection mirror was used with specular reflective types).
- 4) This value indicates the range of errors for an ideal linear displacement output, when using an object made of our company's standard white ceramic for measurement (an aluminum vapor deposition surface reflection mirror was used with specular reflective types). This value may fluctuate depending on the characteristics of the object measured.
- 5) These values were defined by using  $1/e^2$  (13.5 %) of the center light intensity. If there is a slight leakage of light outside the normal spot diameter and if the periphery surrounding the sensing point has a higher reflectivity than the sensing point itself, then the results may be affected.

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#### SPECIFICATIONS

#### **Sensor heads**

		Time	Specular ref	flective type	
		Туре	General purpose	High precision	
`	\ :	IEC / JIS standards conforming type  FDA regulations	HL-C108B	HL-C105B	
Item	\ :	FDA regulations conforming type	HL-C108F	HL-C105F	
Mea	suremer	nt center distance	81.4 mm 3.205 in	46 mm 1.811 in	
Mea	suring ra	ange	±16 mm ±0.630 in	±4 mm ±0.157 in	
Resolution (Note 2, 3)		Note 2, 3)	2 μm 0.079 mil	1 μm 0.039 mil	
Line	arity (No	te 4)	±0.1 %	6 F.S.	
Tem	perature	characteristics	0.02 %	F.S./°C	
Lase	er emissi	on indicator	Green LED (lights up during laser emission	on or immediately before laser emission)	
Measuring range indicator		ange indicator	Yellow LED (blinks within the measuring range and lig	ghts up when near the measurement center distance)	
a)	Pollutio	n degree	3 (Industrial e	environment)	
tanc	Protect	ion	IP67 (IEC) (exclud	ing the connector)	
Environmental resistance	Ambier	nt temperature	0 to +45 °C +32 to +113 °F (No dew condens	eation), Storage: –20 to +70 °C –4 to +158 °F	
ıntal	Ambier	nt humidity	35 to 85 % RH, Stor	age: 35 to 85 % RH	
nme	Ambier	nt illuminance	Incandescent light: 3,000 &	x at the light-receiving face	
nviro	Vibratio	on resistance	10 to 55 Hz (period: 1 min.) frequency, 1.5 mm 0.059 in	n amplitude in X,Y and Z directions for two hours each	
Ш	Shock	resistance	196 m/s² acceleration (20 G approx.) in X	C,Y and Z directions for three times each	
Emit	tting eler	nent	Red semiconductor laser, Class 2 (Class II for FDA regulati FDA regulations conforming type: FDA / IEC / JIS) (Max. ou		
Bea	m diame	ter (Note 5)	100 × 140 μm 3.937 × 5.512 mil approx.	70 × 120 μm 2.756 × 4.724 mil approx.	
Rec	eiving el	ement	Linear ima	ge sensor	
Enclosure earthing		arthing	Floating		
Mate	erial		Enclosure: Die-cast aluminum, Case cove	er: Die-cast aluminum, Front cover: Glass	
Cab	le		Cabtyre cable, 0.5 m 1.6	40 ft long with connector	
Cab	le extens	sion	Extension up to total 30 m 98.425	ft is possible, with optional cable.	
Wei	ght		Net weight: 3	00 g approx.	
Acce	essory		English warning label: 1 set [The FDA regulations conforming type includes a set	et of both the IEC label (written in English) and JIS label (written in Japanese)].	

Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were as follows: supply voltage 24 V DC, ambient temperature +20 °C +68 °F, sampling rate 100 μs, average number of samples: 256, object measured at measurement center distance is made of white ceramic (an aluminum vapor deposition surface reflection mirror was used with specular reflective type). Linearity also depends upon the characteristics of the object being measured.

- 2) These values were obtained by converting P-P values into a distance. The P-P values indicate the distribution of measured values throughout the measurement center distance.
- 3) These values were obtained with an average number of samples: 256, when using an object made of our company's standard white ceramic for measurement (an aluminum vapor deposition surface reflection mirror was used with specular reflective types).
- 4) This value indicates the range of errors for an ideal linear displacement output, when using an object made of our company's standard white ceramic for measurement (an aluminum vapor deposition surface reflection mirror was used with specular reflective types). This value may fluctuate depending on the characteristics of the object measured.
- 5) These values were defined by using 1/e2 (13.5 %) of the center light intensity. If there is a slight leakage of light outside the normal spot diameter and if the periphery surrounding the sensing point has a higher reflectivity than the sensing point itself, then the results may be affected.

### SPECIFICATIONS

#### **Controllers**

	_	Photo-MOS	relay output		
	Туре	Stardard	For <b>HL-C135C-BK10</b>		
ltem	Model No.	HL-C1C-M	HL-C1C-M-WL		
Coni	nection sensor heads	Maximum 2	sensor heads		
Supp	ly voltage	24 V DC ±10 % inclu	iding ripple 0.5 V (P-P)		
Curr	ent consumption	When 1 sensor is connected: 430 mA approx.,	When 2 sensors are connected: 550 mA approx.		
Sam	pling rate	Selectable from 100 μs / 144 μs / 200	µs / 255 µs / 332 µs / 498 µs / 1,000 µs		
em	perature characteristics	±0.01 %	6 F.S./°C		
Analog output	Voltage	Output voltage: $\pm 5$ V/F.S. [default setting when diffuse reflective mode is selected (Note 2)] Output range: $-10.9$ to $+10.9$ V Output current: Max. 2 mA, Output impedance: $50$ $\Omega$			
Analo	Current (Note 3)	Output current: 4 to 20 mA/F.S. [default setting v Output range: 0 to 29.5 mA (maximum of 25 mA Load impedance: 250 Ω or less	when diffuse reflective mode is selected (Note 4)] at max. load impedance)		
Alarr	n output	Photo-MOS relay  • Maximum load current: 50 mA  • Applied voltage: 30 V DC or less  • ON impedance: 35 Ω or less  • Operation time: Max. 2 ms	s (between alarm output and COM)		
	Output operation	Opened when the amount of I	ight is excessive or insufficient.		
	Short-circuit protection	Incorp	porated		
Photo-MOS relay  • Maximum load current: 50 mA  • Applied voltage: 30 V DC or less (between judgment output and COM)  • ON impedance: 35 Ω or less  • Operation time: Max. 2 ms			(between judgment output and COM)		
	Utilization category	DC-12 (	or DC-13		
	Output operation	Opened or closed when the threshold value is reached. Determined based on judg	ment output mode selection. (The threshold value varies with the hysteresis setting		
	Short-circuit protection	Incorp	orporated		
Seria	Il input / output	RS-	232C		
	ng input er emission)	Laser emission stops or continues when voltage (using input voltage: 12 to 24 V DC, maximum input voltage: 30 V DC) is input or there is an open circuit: determined based on input mode selection.			
Rem	ote interlock input	<del></del>	Laser emission stop when open circuit		
Zero	set ON input	Zero set: ON when voltage (using input voltage: 12 to	24 V DC, maximum input voltage: 30 V DC) is input		
'ero	set OFF input	Zero set: OFF when voltage (using input voltage: 12 to 24 V DC, maximum input voltage: 30 V DC) is input			
ors	Laser emission	Green LED (lights up during laser emission from sensor hea	ad 1 or sensor head 2, or immediately before laser emission)		
Indicators	BRIGHT	Red LED (lights up upon disabled measureme	ent due to excessive light at sensor head 1 or 2)		
	DARK	Red LED (lights up upon disabled measureme	ent due to insufficient light at sensor head 1 or 2)		
	ng / Data display	Compact con	sole (optional)		
(Note 5)	Shift	±20.0000 mm ±0.787 in	±200.0000 mm ±7.874 in		
(Note	Span	0.9000 t	to 1.1000		
vera	ge number of samples (Note 5)	OFF, 2 to 32,768	8 times (16 steps)		
Digit	al filters (Note 5)	High pass: OFF, 10 to 2,000 Hz (9 steps)	), Low pass: OFF, 10 to 2,000 Hz (9 steps)		
	ulation functions (Note 5)	A, B: Sensor head 1, Sensor head 2 measureme	3, L ±K (A ±B) ent values, L = ±999.9999, K = 0.0001 to 99.9999		
Hold functions (Note 5) Selectable from NORMAL / P-P / PEAK / VALLEY					
stance	Pollution degree 3 (Industrial environment)				
resis	Ambient temperature  Ambient humidity	`	sation), Storage: –20 to +70 °C –4 to +158 °F		
nental	rage: 35 to 85 % RH				
Pollution degree  3 (Industrial environment)  Ambient temperature  0 to +50 °C +32 to +122 °F (No dew condensation), Storage: -20 to +70 °C -4 to +158 °F  Ambient humidity  35 to 85 % RH, Storage: 35 to 85 % RH  Vibration resistance  10 to 55 Hz frequency (period: 1 min.) 0.75 mm 0.030 in amplitude in X,Y and Z directions for 30 min. ea  Shock resistance  196 m/s² (20 G approx.) in X, Y and Z directions for 3 times each					
Ē	Shock resistance		and Z directions for 3 times each		
	e length		, Signal line: Less than 30 m 98.425 ft		
Neig		Net weight: 3	300 g approx.		
Acce	ssory	<del></del>	Key: 2 pcs.		

Notes: 1) Where measurement conditions have not been specified precisely, the conditions used were as follows: supply voltage 24 V DC, ambient temperature +20 °C +68 °F, sampling rate 100 µs, average number of samples: 256 (HL-C1C-M-WL: 512), and measurement center distance.

- 2) If specular reflective mode is selected, then the default setting is ±4 V/F.S.
- 3) The maximum analog output current will vary with load impedance.
- 4) If specular reflective mode is selected, then the default setting is 5.6 to 18.4 mA/F.S.
- 5) These values can be set using the command input from external equipment via the compact console and RS-232C interface.

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LASER

PHOTO-ELECTRIC SENSORS MICRO PHOTO-ELECTRIC SENSORS

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V URING YSTEMS

Selection Guide Laser Displacement Magnetic Displacement

Digital Panel
Controller

Metal-sheet
Double-feed

HL-G1

HL-C2

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MACHINE VISION SYSTEMS

CURING SYSTEMS

Metal-sheet Double-feed Detection

HL-G1 HL-C2 HL-C1

LM10

# **SPECIFICATIONS**

#### **Compact consoles**

		Туре	Standard	For <b>HL-C1C-M-WL</b>			
Item	1	Model No.	HL-C1DP1-E	HL-C1DP1-E-WL			
Supp	oly voltage		24 V DC ±10 % includ	ding ripple 0.5 V (P-P)			
Current consumption		otion	200 mA	or less			
	Display ele	ment	STN monoc	hrome LCD			
Display	Back light		White	LED			
Disp	Display ran	ge	-999.9999 t	0 999.9999			
	Language		Eng	lish			
Touch	Operation f	orce	0.5 N or less				
Tot	Lifetime		1,000,000 times or more (Note 1)				
Environmental resistance	Protection   IP65 (IEC) (at initial status) (Note 2)   Dust prevention and drip-proof at the front panel (waterproof packing is used at the contact surface)						
esist	Ambient ter	mperature	0 to +50 °C +32 to +122 °F (No dew condensation), Storage: -20 to +60 °C -4 to +140 °F				
ıtal	Ambient hu	ımidity	20 to 85 % RH, Storage: 10 to 85 % RH				
ımer	Electrostatic	noise resistance	5,000 V or more	(panel surface)			
viro	Vibration re	esistance	10 to 55 Hz frequency, 0.75 mm 0.030 in ampl	itude in X, Y and Z directions for 10 min. each			
ш	Shock resistance 98 m/s² or more acceleration (10 G approx.) in X, Y and Z directions for four times each						
Material			Case: PPE, Front protective sheet: Polyester				
Weig	ght		Net weight: 230 g approx.				
Acce	essories		Connection cable for connecting the controller	to the console: 1 pc., Mounting bracket: 1 set			

Notes: 1) This value indicates the average lifetime of the unit when used under a normal temperature of +25 °C +77 °F.

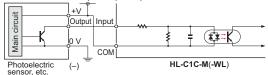
2) When reinstalling the console, replace the waterproof packing. (Part No: AIGT181, 10 packs included)

#### I/O CIRCUIT AND WIRING DIAGRAMS

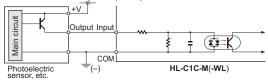
HL-C1C-M(-WL)

#### Input circuit diagram

Connection example 1 (NPN)

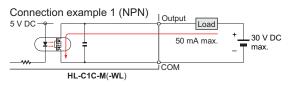


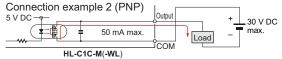
#### Connection example 2 (PNP)



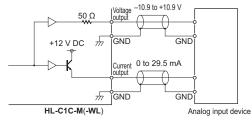
#### **Output circuit diagram**

#### Alarm output, Judgment output





#### Analog output diagram



Notes: 1) Do not short-circuit analog output terminals or apply vottage to them.

#### 2) Use shielded wires for analog outputs.

# **Terminal arrangement** I

nput te	erminals
TM1   111   112   COM   TM2   121   122   COM	

HL-C135C-BK10

Symbol	Description		
TM1 (Note 1)	Timing input (sensor head 1) (Note 1)		
l11	Zero set ON input (sensor head 1)		
l12	Zero set OFF input (sensor head 1)		
COM	Input common		
TM2 (Note 2)	Timing input (sensor head 2) (Note 2)		
121	Zero set ON input (sensor head 2)		
122	Zero set OFF input (sensor head 2)		
COM	Input common		
•	Not used		
+	24 V DC input for power supply		
- 1	Power supply ground		
4	Function ground		

Symbol	Description
AL1	Alarm output (sensor head 1)
O11	Judgment output 1 (sensor head 1)
O12	Judgment output 2 (sensor head 1)
COM	Output common
AL2	Alarm output (sensor head 2)
O21	Judgment output 1 (sensor head 2)
O22	Judgment output 2 (sensor head 2)
COM	Output common
•	Not used
•	Not used
V1	Analog voltage output (sensor head 1)
I1	Analog current output (sensor head 1)
GND	Analog output ground
V2	Analog voltage output (sensor head 2)
12	Analog current output (sensor head 2)
GND	Analog output ground
	AL1 O11 O12 COM AL2 O21 O22 COM · · V1 I1 GND V2 I2

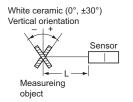
Notes: 1) In the case of HL-C1C-M-WL, "IL1: Remote interlock input (sensor head 1)"

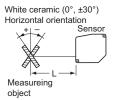
2) In the case of **HL-C1C-M-WL**, "IL2: Remote interlock input (sensor head 2)"

3) Terminals marked with "•" are not used. Some are connected to internal circuitry and cannot be used as relay terminals in wiring, etc.

# SENSING CHARACTERISTICS (TYPICAL)

#### Correlation between measuring distance and error characteristics





· Horizontal positioning · Vertical positioning Sampling rate: 100 µs Sampling rate: 100 µs 0 Average number - 0° Average number of samples: 512 -30 of samples: 512 0.2 0.2 Error (%F.S.) (%F.S.) -0.4 -0.4 150 350 450 550 150 250 350 450 550 (Center) (Center)

-Measuring distance L (mm in) →

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HL-G1

Diffuse reflective type

-Measuring distancé L (mm in) →

HL-C2

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PRESSURE / FLOW SENSORS

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Magnetic
Displacement
Collimated
Beam
Digital Panel
Controller

HL-G1 HL-C2 HL-C1

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# SENSING CHARACTERISTICS (TYPICAL)

# Correlation between measuring distance and error characteristics

White ceramic (0°, ±10°)
Vertical orientation

Sensor head

Measureing
object

White ceramic (0°, ±10°)
Horizontal orientation

Sensor head

Measureing
object

· Vertical positioning 0.4 +10° Sampling rate: 100 µs Average number of samples: 256 0.2 . (%F.S.) Error (%F.S.) Error ( -0.4 -0.4 75 2.953 65 85 95 105 4,134 65 (Center)
Measuring distance L (mm in)

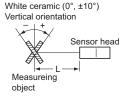
Diffuse reflective type

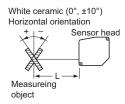
Diffuse reflective type

#### HL-C105□-BK

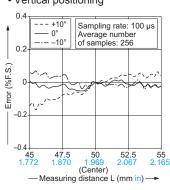
HL-C108□-BK

#### Correlation between measuring distance and error characteristics

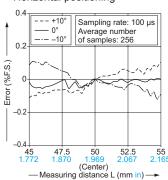




#### Vertical positioning



#### · Horizontal positioning



#### HL-C108B HL-C108F

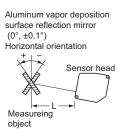
#### Correlation between measuring distance and error characteristics

surface reflection mirror (0°, ±0.2°)
Vertical orientation

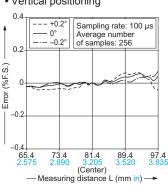
Sensor head

Measureing
object

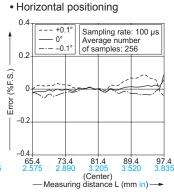
Aluminum vapor deposition



#### Vertical positioning



Specular reflective type



#### HL-C105B HL-C105F

#### Correlation between measuring distance and error characteristics

surface reflection mirror (0°, ±0.5°)
Vertical orientation

Sensor head

Measureing
object

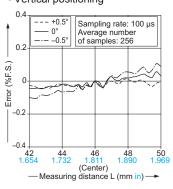
Aluminum vapor deposition



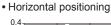
Measureing

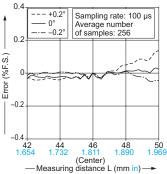
object

# Vertical positioning



#### Specular reflective type





#### PRECAUTIONS FOR PROPER USE

Refer to General precautions and About laser beam.

· This catalog is a guide to select a suitable product. Be sure to read instruction manual attached to the product prior to its use.

> · Never use this product as a sensing device for personnel protection.



In case of using sensing devices for personnel protection, use products which meet laws and standards, such as OSHA, ANSI or IEC etc., for personnel protection applicable in each region or country.

HL-C108 HL-C105□

- This product is classified as a Class 2 Laser Product in IEC / JIS standards and a Class II Laser Product in FDA regulations 21 CFR 1040.10. Do not look at the laser beam directly or through optical system such as a
- · The following label is attached to the product. Handle the product according to the instruction given on the warning label.



The English warning label based on \ FDA regulations is pasted on the FDA regulations conforming type.

HL-C135C-BK10

- This product is classified as a Class 3B Laser Product in IEC / JIS standards and a Class IIIb Laser Product in FDA regulations 21 CFR 1040.10. Never look at or touch the direct laser beam and its reflection.
- The following label is attached to the product. Handle the product according to the instruction given on the warning label.



The English warning label based on\ FDA regulations is pasted on the FDA regulations conforming type.

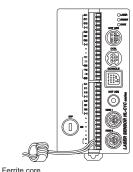
#### To comply with the European EMC Directive (HL-C1C-M-WL)

 To comply with the European EMC Directive, install a ferrite core on wires to the terminal block as shown below.

Recommended ferrite core:

E04RC281613 manufactured by Seiwa Electric Mfg. Co., Ltd. or equivalent

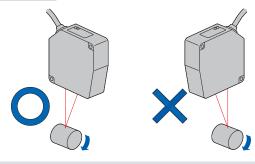
TFT-152613 manufactured by Takeuchi Industry Co.,Ltd. or equivalent



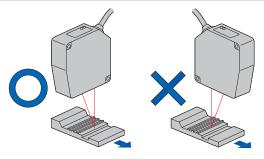
#### Sensor head mounting direction

• To obtain the greatest precision, the sensor head should be oriented facing the direction of movement of the object's surface, as shown in the figure below.

#### Rotating object



### Object that has large differences in gaps, grooves and colors



#### Safety standards for laser beam products

 A laser beam can harm human being's eyes, skin, etc., because of its high energy density. IEC and JIS have classified laser products according to the degree of hazard and the stipulated safety requirements. HL-C108□ and HL-C105□: Classified as Class 2 laser

products HL-C135C-BK10: Classified as a Class 3B laser products

(Refer to About laser beam.)

#### Safe use of laser products

· For the purpose of preventing users from suffering injuries by laser products, IEC 60825-1(Safety of laser products). Kindly check the standards before use. (Refer to About laser beam.)

FIBER SENSORS

LASER SENSORS

PHOTO-ELECTRIC SENSORS MICRO PHOTO-ELECTRIC SENSORS

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LIGHT CURTAINS

PRESSURE / FLOW SENSORS

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HL-C2

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HL-C108□-BK

HL-C105<sub>□</sub>-BK

emitting axis

COMPONENTS MACHINE VISION SYSTEMS

Magnetic Digital Panel Controller

HL-G1 HL-C2 HL-C1

LM10

#### PRECAUTIONS FOR PROPER USE

Refer to General precautions and About laser beam.

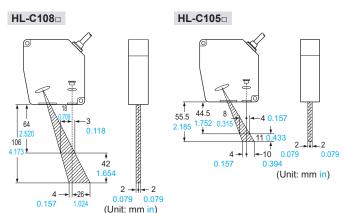
#### **Mutual interference**

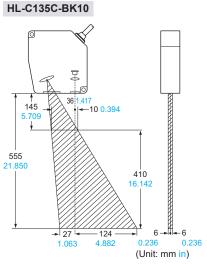
· When installing 2 or more sensor heads side by side, mutual interference will not occur if the laser spots from other sensor heads do not fall within the shaded areas of the sensor head in the figure below. Multiple sensor heads must be installed in a manner such that laser spots from other sensor heads will be prevented from falling within these shaded areas. When two sensor heads are connected to a controller and used, the measures described below are not required since the mutual interference prevention function can be used.

Sensor head

Sensor head

HL-C108B



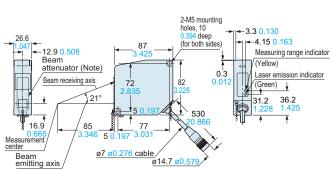


HL-C108F

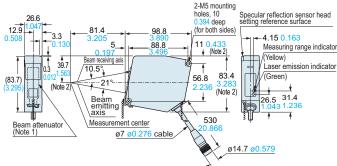
# **DIMENSIONS (Unit: mm in)**

The CAD data in the dimensions can be downloaded from our website.

Sensor head

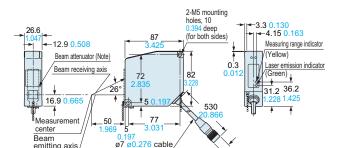


Note: There is not beam attenuator on IEC / JIS standards conforming type.



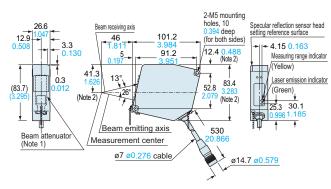
Notes: 1) There is not beam attenuator on IEC / JIS standards conforming

2) Figure shows standard installation level dimensions.



Note: There is not beam attenuator on IEC / JIS standards conforming type

# HL-C105B HL-C105F

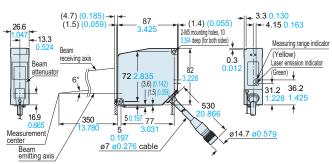


Notes: 1) There is not beam attenuator on IEC / JIS standards conforming type. 2) Figure shows standard installation level dimensions.

# DIMENSIONS (Unit: mm in)

The CAD data in the dimensions can be downloaded from our website.

HL-C135C-BK10 Sensor head

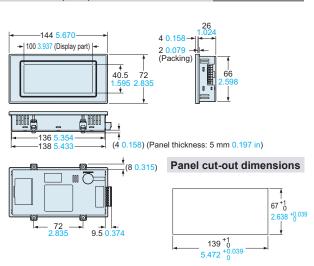


HL-C1C-M-WL Controller

4-M3, 1.5 0.059 deep (0.217) (0.217) (0.217) (0.319) (0.319) (0.319) (0.319) (0.319) 3 0.118 (13.2) 15 (10) 74 (10) 4.724 (10) 4.724 (10) 4.724 (10) 4.724 (10) 6.50 (10) 6

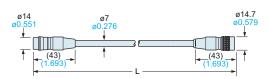
HL-C1DP1-E(-WL) Compact console

HL-C1C-M



Note: The panel thickness should be 1 to 5 mm 0.039 to 0.197 in.

**HL-C1CCJ**□ Extention cable



#### • Length L

Model No.	Length L
HL-C1CCJ2	2,000 78.740
HL-C1CCJ5	5,000 196.850
HL-C1CCJ10	10,000 393.700
HL-C1CCJ20	20,000 787.400
HL-C1CCJ30	30,000 1181.100

FIBER SENSORS

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PRESSURE / FLOW SENSORS

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SIMPLE

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FA COMPONENTS

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> UV CURING SYSTEMS

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Displacement
Magnetic
Displacement
Collimated
Beam
Digital Panel
Controller

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