Oriental motor

Brushless Motors **BLE2 Series**

All New.

An advanced Brushless DC package, which is both easy to use and feature rich.



Evolution in Brushless Motors

Introducing the **BLE2** Series

BLE Series models have been fully revamped. The motor, driver, and cable have been redesigned. While retaining the original advantages of the brushless DC motors. This makes the **BLE2** Series easy to use and highly functional. This advanced model reveals its excellence with every application.



Superb Performance and Features

- Speed Control Range 80~4000 r/min
- Speed Regulation Rate ±0.2% *In digital setting
- Torque Limiting Capability
- Multiple Speed-Change Operation Max. 16 Speeds
- Output Shaft Holding when Stopped (up to 50% of rated torque)
- Watertight and Dust-Resistant (degree of protection IP66) *0nly for motor
- High Rust-Proof and Anti-Corrosion Properties due to Stainless Steel Shaft
- Monitoring and Testing Features which are Useful for Setup and Trouble Shooting.

Easy to Use and Affordable Prices

- The Driver can be Digitally Set and Controlled via the Drivers Front Panel.
- Compact and Thin Drivers Allows for Side-by-Side Installation
- Speed Setting Via PC and External Signals
- Cables with Selectable Pull-out Directions
- A Max. Distance of 20 m between the Motor and the Driver is Possible, via Direct Connection.
- Product Line 30 W~300 W

Features of the Brushless Motor

Brushless DC motors are without brushes, which is a major drawback of brushed DC motors, this allows for quieter and maintenance free operation. Because the **BLE2** Series has a permanent magnet it allows for a compact design with high power and high efficiency.

Wide Speed Control Range

Brushless motors have a wider range of speed control than AC motors. Additionally they are ideal for applications that require a constant torque from low to high speed.

Product Group	Speed Control Range*	Speed Ratio
Brushless Motors BLE2 Series	80~4000 r/min	1:50
Inverter-Controlled Three-Phase Induction Motor	200~2400 r/min	1:12
AC Speed Control Motors	50 Hz : 90∼1400 r/min 60 Hz : 90∼1600 r/min	1:15 1:17

*Speed control range varies from model to model.

Stable Speed Control

Brushless motors constantly monitors feedback signals from the motor and adjusts the applied voltage by comparing them against the set speed. This allows the motor to rotate at a stable speed from low to high speeds even when the load fluctuates.

Comparison of Speed Variation (Reference value)



Slim, Light, High Power

Brushless motors are slim, light and high power because permanent magnets are used in the rotor portion. It contributes to the downsizing of equipment.

[Comparison Example at 200 W Output Power]



Saves Energy

Brushless motors significantly reduce power consumption as the use of permanent magnets in the rotor portion prevents secondary loss from the rotor. This helps the equipment to save energy.



In Pursuit of Easy Setting, Installation, and Wiring

Overhauling the motor structure has made it even more compact, as well as increasing the power and efficiency. The driver comes with a digital indication panel, that easily allows speed to be set via a single potentiometer. Additionally, connection cables now come with the option to choose the pull-out direction and a max. distance of 20 m can be secured via direct connection.

BLE2 Series epitomises what the customers find easy to use.



Effective Utilization of Installation Space

This new driver has a compact and slim body through optimal layout of its internal parts. Multiple drivers can now be installed in contact with each other, making it possible to reduce the amount of installation space or increase the number of axes within the same equipment space.

Compact, Slim-Body Driver



Side-by-Side Installation of Multiple Drivers



BLE2 Series Drivers



Condition for Contact Installation •Ambient temperature 0~+40 °C •Please install it on a heat sink (Material: Aluminum, equivalent to 350×350×2 mm).

Watertight and Dust-Resistant Performance (Degree of protection IP66)

A new type of connector has been designed, which includes a built-in Gasket and O-ring. This allows for the motor to achieve an IP66 degree of protection in both the motor and connector, enabling it to be used in an environment where high pressured water may be an issue. Additionally the connectors lock lever does not require a screw fitting, which allows for easy connection. *The driver portion is IP20.

Connector Structure





Insert the connector



Fold down the lock lever



Connected

Standardized Use of Stainless Steel Shaft

EURONORM X 10 CrNiS 18 9 stainless steel is used for the shaft, which has excellent anti-corrosive properties. Stainless steel is also used in parallel keys and installation screws.



Easy Assembly with a Combination Type

With cutting-processed boss section and installation surface, the installation precision between the device and gearhead has been improved. This improved machining as also resulted in a quiter product. Furthermore, as the combination type of the motor and gearhead comes pre-assembled, it is fast and simple to directly couple onto a device.



Selectable Pull-out Direction and Directly Connectable Cables

3 types of connection cables are available based on the desired pull-out direction. Since 1 connection cable can be used to connect the motor and the driver directly, with a max. distance of 20 m, there is no need for special connectors.

Selectable Cable Pull-out Direction

Pull-out on output shaft side Pull-out on rear of the motor Vertical Pull-out





*Only pull-out on the rear of the motor is available for round shaft type.

• Connection with 1 Connection Cable, No need for Relays



Meeting Customer Needs with Enhanced Functions

Features 4 data setting methods and various functions that are customisable. By using data setting software, equipment start-up and checking operating status is simple. Oriental Motors offers functions that meet the customers' needs and situations.

Operating Method

Local Control Operating: Set via the front control panel. It can be used for test operation.
 Remote Control Operation: Set via external signals and data setting software MEXEO2.



*When using data setting software **MEXEO2**, a commercially available USB cable can be used to connect the driver and PC.

Settable Contents

			Setting Method				
Setting Contents	Applications and Purposes	Setting Value	Control Panel	External Speed Potentiometer PAVR2-20K	External DC Voltage	Data Setting Software MEXEO2	
Speed	For operating at an arbitrary speed.	80~4000 r/min	•	•	•	•	
Torque Limiting	For suppressing the motor's max. output power for safety purpose or limiting it depending on the load.	0~300 %	•	•	•	•	
Acceleration/ Deceleration Time	For setting the acceleration time and deceleration time to prevent impact to the load when starting and stopping.	0~15.0 seconds	•	_	_	•	
Multistep Speed-Change Operation	For operating at more than 2 speeds.	Max. 16 speeds	•	-	-	•	
Parallel-Motor Operation	For operating multiple motors at the same speed.	20 units max. (When using a potentiometer)	-	•	•	_	

Main Software Functions

Below are the major functions that can be operated using the control panel and data setting software MEXEO2.

Applications and Purposes	Function	Description
Checking the Motor's Generated Torque.	Load Factor Indication	It displays the load factor with the motor's rated torque as 100 %. (Indication range: 0 \sim 300 %)
Displays the Output Shaft Speed after the Gearhead.	Gear Ratio	When the gear ratio is set, it displays the converted speed.
Operating at a Speed within the Set Speed Control Range.	Speed Limits Setting	It sets the upper and lower limit values of the speed.
Changing the Speed while the Motor is Rotating.	Speed Teaching	Speed can be changed in the monitor mode while the motor is rotating.
Holding the Load during Standstill.	Easy Holding Torque	An electrical holding torque can be generated while the motor is stopped. (Holding force up to 50 % of rated torque) Note Since the holding force is canceled when the power supply to the driver is turned OFF, it cannot be used to prevent falls during standstill.
Reducing Shock during Starting and Stopping.	Shock Alleviation Filter	This function softens acceleration and deceleration so that the load being transported does not experience sudden movement.
Checking the Reason for the Alarm Generation.	Alarm	Alarm outputs include overload, incorrect connection, over voltage etc and can be identified easily. This allows for ease of fault finding and swift corrective action.
Information Status of the Motor and Driver.	General Information	Before an alarm is output, an information output can be set to enable maintenance teams to be made aware of situations when the motor maybe running outside of its normal conditions before going into alarm.
Set Data is Protectable.	Edit Lock	Set data is protectable, which prevents users from deleting or making unnecessary changes to data & parameters, from either the control panel or the local PLC.



Data Setting Software MEXEO2 The data setting software can be downloaded from the website Oriental Motor also provides it on a CD-ROM free of charge.

When Operating

For Maintenance

Use ful Functions that Utilize Data Setting Software MEXE02

Monitoring Function

A variety of monitoring functions are built into the driver that helps with confirming the operating status of the motor, etc. By using these during application set-up, equipment can be configured and adjusted more quickly as well as making maintenance much more efficient.

Alarm Monitoring

Waveform Monitoring

The operating and output signal status of the motor can be monitored like an oscilloscope. This can be used for application set-up & configuration.





When an alarm occurs the details of the alarm are recorded as well as the operating status of the motor just before the alarm.

Test Functions

These functions allow for the motor to be operated, controlled and adjusted via Oriental Motors **MEXE02** Software. Additionally when directly connected to a PLC or controller the software can monitors the inputs and outputs sent to and from the **BLE2** drive. This helps to reduce set-up time.

• Teaching and Remote Operation



I/O Monitor

up When Operating

The "Teaching and Remote Operation" Function allows for the motion variables to be changed and saved during testing, such as speed. Allowing for the machine to be set up before connecting it to the PLC or controller. This helps to reduce set-up time.

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Detail the C-los monitor Detail 10 liquit □ DiC FWD □ Di REV □ Di REV □ Di SPDF-MODE □ Di MU □ Di MI □ Di SLARM RESET □ Dis MB-FREE	Ouput	
External analog voltage External DC voltage	0.0 IVec	

This function allows us to monitor the digital I/O of the BLE2 driver

as well as any external DC voltage. Additionally Inputs & Outputs

can be forced. This function is useful for confirming that wiring is

Compact, High Power, and High Efficiency Motors

Uses the New Brushless Motor NexBL.

Increase in Unit Efficiency by Up to 7% (Compared against the BLE Series)

Optimal magnetic design and high-performance materials allow for a stator thickness of only 11.2 mm. It is a high-efficiency power unit that can output 120 W with this thickness.



Series Name	BLE2 Series	Conventional BLE Series
Motor Weight	1.6 kg	1.9 kg
Motor L Dimensions	45 mm	50 mm
Speed Control Range	16~800 r/min	20~800 r/min
Permissible Torque	0.9 Nm	0.9 Nm

Compared when a combination type motor (output 60 W, gear ratio 5), driver, and 1 m connection cable are used in combination

Product Line

For the **BLE2** series the motor, driver and connection cables are sold separately. They can be purchased in combinations.

Motor	Output Power [W]	Frame Size	Gearhead Gear Ratio (Combination type)	Driver	Power Supply Voltage	Connection Cable
	30	Combination Type Round Shaft Type 60 mm		4858		BLE2 Series 0.5~20 m
Combination Type	60	Combination Type 80 mm Round Shaft Type 60 mm	5, 10, 15, 20,		Single-Phase 100-120 VAC Single-Phase 200-240 VAC Three-Phase 200-240 VAC	Pull-out on output shaft side/ Pull-out on rear of the motor
	120	Combination Type Round Shaft Type 90 mm	200			
	200	Combination Type 110 mm			Single-Phase 200-240 VAC	Vertical Pull-out
Round Shaft Type*	300	Round Shaft Type 90 mm	5, 10, 15, 20, 30, 50, 100	34 ABS	Three-Phase 200-240 VAC	

*For round shaft motors only connection cables facing away from the motors mounting face can be used. *Round shaft type with flat is available.

For Controlling with Network

BLE Series RS-485 Communication Type

In addition to I/O control, FA network control is now possible using Modbus (RTU) or other network converters.



System Configuration

Motors, drivers and connection cables are sold separately.



*3 An external speed potentiometer (PAVR2-20K) and general-purpose cable for I/O signals cannot be used together.

•Example of System Configuration

BLE2 Series				Ac	cessories (Sold separatel	y)
Combination Type with a Parallel Shaft	Driver	Connection Cable (3 m)	+	Mounting Bracket for Motor and Gearhead	Flexible Coupling	DIN Rail Mounting Bracket
BLM230HP-10S	BLE2D30-A	CC030KHBLF		SOL2M4F	MCL301010	MADP02
213.00 €	194.00 €	56.00 €]	26.00 €	39.00 €	21.00 €

The system configuration shown above is an example. Other combinations are also available.

Product Number

 Moto 	or (Com	binatic	on Ty	pe/F	loun	d S	haft Ty	rpe)
BLA	۸4	60	S	Η	Ρ	-	50	S
1	2	3	4	5	6		7	8
Drive	ars							
BLE	2D	60	-	С				
 (1		0		3				
• Conr	rection	Cable		e				
CC (010	KH	B	LF				
1	2	3	(4) (5)			

1	Motor Type	BLM: Brushles	ss motor		
2	Frame Size	2 : 60 mm 4 : 8 6 : 104 mm (Ge	2 : 60 mm 4 : 80 mm 5 : 90 mm 6 : 104 mm (Gearhead is 110 mm)		
3	Output Power	30 : 30 W 60 : 60 W 120 : 120 W 200 : 200 W 300 : 300 W			
4	Identification Number	S			
5	Motor Connection Method	H: Connector t	уре		
6	Degree of Motor Protection	P: IP66 rating			
1	Gear Ratio and Motor Shaft Type	Number: Gear ratio for combination types A: Round shaft type AC: Round shaft type (with shaft flat)			
8	Output Shaft Material	S: Stainless steel			
1	Driver Type	BLE2D: BLE2	2 Series driver		
2	Output Power	30: 30 W 60 200: 200 W 3	: 60 W 120 : 12 300 : 300 W	0 W	
3	Power Supply Voltage	A: Single-phas C: Single-phas	e 100-120 VAC e, three-phase 20	00-240 VAC*	
1	Cable Type	CC: Connection	n cable		
2	Length	005 : 0.5 m 020 : 2 m 040 : 4 m 100 : 10 m	010: 1 m 025: 2.5 m 050: 5 m 150: 15 m	015 : 1.5 m 030 : 3 m 070 : 7 m 200 : 20 m	
3	Motor Connection Method	KH: Metal connector type			
4	Applicable Model	BL: Brushless	motors		
5	Cable Pull-out Direction	 F: Pull-out on output shaft side B: Pull-out on rear of the motor V: Vertical direction 			

*WARNING: Connecting the **BLE2** to three-phase 400 VAC will damage the product.

Product Line

Please purchase a motor, a driver, and a connection cable.

Combination Type with a Parallel Shaft Gearhead

Combination
TypeMotor and gearhead are delivered pre-assembled.The combination of motors and gearheads can be changed, and they are also available separately.
In addition, the gearhead can be removed and the assembly position can be changed in 90° increments.



♦Motor			
Output Power [W]	Product Name	Gear Ratio	List Price
		5, 10, 15, 20	213.00 €
30	BLM230HP-	30, 50, 100	218.00 €
		200	225.00 €
		5, 10, 15, 20	231.00 €
60	BLM460SHP-□S	30, 50, 100	238.00 €
		200	244.00 €
		5, 10, 15, 20	281.00 €
120	BLM5120HP-	30, 50, 100	290.00 €
		200	299.00 €
		5, 10, 15, 20	345.00 €
200	BLM6200SHP-□S	30, 50	356.00 €
		100, 200	367.00 €
		5, 10, 15, 20	383.00 €
300	BLM6300SHP-□S	30, 50	393.00 €
		100	404.00 €
- The follow	ing items are included with each	product.	

Motor, Gearhead, Installation Screws, Parallel Key, Operating Manual

 \bullet A number indicating the gear ratio is specified where the box \Box is located in the product name.

♦ Connection Cables

	*				
	Length [m]	Product Name	List Price	Length [m]	I
	0.5	CC005KHBL	32.00€	4	C
	1	CC010KHBL	32.00€	5	С
	1.5	CC015KHBL	36.00€	7	С
	2	CC020KHBL	39.00€	10	С
	2.5	CC025KHBL	47.00€	15	C
	3	CC030KHBL	56.00€	20	С
1					

~	Y .	
.ength [m]	Product Name	List Price
4	CC040KHBL	65.00 €
5	CC050KHBL	75.00€
7	CC070KHBL	92.00 €
10	CC100KHBL	117.00€
15	CC150KHBL	164.00 €
20	CC200KHBL	208.00 €

~ =							
Output Power [W]	Power Supply Voltage	Product Name	List Price				
20	Single-Phase 100-120 VAC	BLE2D30-A	194.00€				
30	Single-Phase, Three-Phase 200-240 VAC	BLE2D30-C	194.00€				
60	Single-Phase 100-120 VAC	BLE2D60-A	194.00€				
00	Single-Phase, Three-Phase 200-240 VAC	BLE2D60-C	194.00€				
100	Single-Phase 100-120 VAC	BLE2D120-A	198.00€				
120	Single-Phase, Three-Phase 200-240 VAC	BLE2D120-C	198.00€				
200	Single-Phase, Three-Phase 200-240 VAC	BLE2D200-C	221.00€				
300	Single-Phase, Three-Phase 200-240 VAC	BLE2D300-C	252.00€				
- The follow	The following items are included with each product.						
Driver, O	Driver, Operating Manual, Start-up Guide						

3 types of connection cables with different cable pull-out direction are available.

F: Pull-out on output shaft side

B: Pull-out on rear V: Vertical Pull-out of the motor





• An F, B or V indicating the cable pull-out direction is specified where the box 🔳 is located in the product name.

Round Shaft Type

⇔Motors						
Output Power [W]	Product Name	List Price				
30	BLM230HP-AS	116.00€				
60	BLM260HP-AS	126.00€				
120	BLM5120HP-AS	151.00€				
200	BLM5200HP-AS	180.00€				
300	BLM5300HP-AS	220.00€				
The following items are included with each product. Motor, Operating Manual						

Output Power [W]	Power Supply Voltage	Product Name	List Price
20	Single-Phase 100-120 VAC	BLE2D30-A	194.00€
30	Single-Phase, Three-Phase 200-240 VAC	BLE2D30-C	194.00€
60	Single-Phase 100-120 VAC	BLE2D60-A	194.00€
60	Single-Phase, Three-Phase 200-240 VAC	BLE2D60-C	194.00€
100	Single-Phase 100-120 VAC	BLE2D120-A	198.00€
120	Single-Phase, Three-Phase 200-240 VAC	BLE2D120-C	198.00€
200	Single-Phase, Three-Phase 200-240 VAC	BLE2D200-C	221.00€
300	Single-Phase, Three-Phase 200-240 VAC	BLE2D300-C	252.00€

.... r of the motor V: Vertical Pull-out



♦Connection Cables

Length [m]	Product Name	List Price	Length [m]	Product Name	List Price	B : Pull-out on rear				
0.5	CC005KHBLB	32.00 €	4	CC040KHBLB	65.00 €	<u>.</u>				
1	CC010KHBLB	32.00 €	5	CC050KHBLB	75.00 €					
1.5	CC015KHBLB	36.00 €	7	CC070KHBLB	92.00 €					
2	CC020KHBLB	39.00 €	10	CC100KHBLB	117.00€					
2.5	CC025KHBLB	47.00 €	15	CC150KHBLB	164.00 €					
3	CC030KHBLB	56.00 €	20	CC200KHBLB	208.00 €	-				
Note						-				
The only cable	The only cable pull-out direction of the round shaft type is the rear of the motor.									

Other Product Lineup

Round Shaft Type Shaft Flat on Output Shaft

•For detailed information on products with shaft flat, please see the Oriental Motor website.

Specifications

• 30 W

Product Name	Motor	Combination Type with a Parallel Shaft Gearhead	BLM230HP-	□S	
		Round Shaft Type	BLM230HP-	AS	
	Driver		BLE2D30-A	BLE2D30-C	
Rated Output I	Power (Continuous)	W	3	0	
	Rated Voltage	VAC	Single-Phase 100-120	Single-Phase 200-240/Three-Phase 200-240	
	Permissible Voltage Range		-15~	+10 %	
Power	Frequency	Hz	50/	/60	
Supply Input Pe Ra Bated Speed	Permissible Frequency Range		±5 %		
	Rated Input Current	А	1.1	Single-Phase: 0.67/Three-Phase: 0.39	
	Max. Input Current	А	3.3	Single-Phase: 2.2/Three-Phase: 1.2	
Rated Speed		r/min	30	00	
Rated Torque		Nm	0.0	96	
Max. Instantar	neous Torque	Nm	0.	2	
Rotor Inertia J		×10 ⁻⁴ kgm ²	0.0	42	
Round Shaft Type Permissible Inertia J		$ imes 10^{-4}\mathrm{kgm^2}$	1.8		
Speed Control	Range		80~4000	r/min (Speed ratio 1:50)	
		Load	Max. ± 0.2 % (± 0.5 %): Conditions $~0{\sim}$ rated torque, rated	d speed, rated voltage, normal ambient temperature	
Speed Regulat	tion*	Voltage	Max. ± 0.2 % (± 0.5 %): Conditions Rated voltage $-15{\sim}$	+10 %, rated speed, no load, normal ambient temperature	
		Temperature	Max. ± 0.2 % (± 0.5 %): Conditions Operating ambient ten	nperature 0 \sim +50 °C, rated speed, no load, rated voltage	

*The value inside parentheses is the specification for analog setting.

The values correspond to each specification and characteristics of a stand-alone motor.
 A number indicating the gear ratio is specified where the box
 is located in the product name.

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Product Name	Motor	Combination Type with a Parallel Shaft Gearhead	BLM460SH	IPS	
		Round Shaft Type	BLM260HF	P-AS	
	Driver		BLE2D60-A	BLE2D60-C	
Rated Output F	Power (Continuous)	W	6	60	
	Rated Voltage	VAC	Single-Phase 100-120	Single-Phase 200-240/Three-Phase 200-240	
	Permissible Voltage Range		-15~	+10 %	
Power	Frequency	Hz	50	/60	
Power Fre Supply Input Per Rat Rated Speed	Permissible Frequency Range		±5%		
	Rated Input Current	А	1.7	Single-Phase: 1.0/Three-Phase: 0.61	
	Max. Input Current	Α	5.4	Single-Phase: 3.5/Three-Phase: 2.0	
Rated Speed		r/min	30	000	
Rated Torque		Nm	0.1	191	
Max. Instantan	eous Torque	Nm	0	.4	
Rotor Inertia J		imes10 ⁻⁴ kgm ²	0.0	082	
Round Shaft Ty	ype Permissible Inertia J	$ imes 10^{-4}~{ m kgm^2}$	3.	75	
Speed Control	Range		80~4000	r/min (Speed ratio 1:50)	
		Load	Max. \pm 0.2 % (\pm 0.5 %): Conditions 0 \sim rated torque, rate	d speed, rated voltage, normal ambient temperature	
Speed Regulat	ion*	Voltage	Max. ± 0.2 % (± 0.5 %): Conditions Rated voltage $-15 \sim$	+10 %, rated speed, no load, normal ambient temperature	
		Temperature	Max. ± 0.2 % (± 0.5 %): Conditions $$ Operating ambient te	mperature 0 \sim + 50 °C, rated speed, no load, rated voltage	

•120 W

Product Name	Motor	Combination Type with a Parallel Shaft Gearhead	BLM5120	HPS
		Round Shaft Type	BLM5120	HP-AS
	Driver		BLE2D120-A	BLE2D120-C
Rated Output F	Power (Continuous)	W		120
	Rated Voltage	VAC	Single-Phase 100-120	Single-Phase 200-240/Three-Phase 200-240
	Permissible Voltage Range		-15	~+10 %
Power	Frequency	Hz	5	50/60
Supply Input	Permissible Frequency Range		=	±5 %
	Rated Input Current	А	2.7	Single-Phase: 1.7/Three-Phase: 1.02
Rate Max. Rated Speed	Max. Input Current	А	7.4	Single-Phase: 4.8/Three-Phase: 3.3
Rated Speed		r/min		3000
Rated Torque		Nm	C	0.382
Max. Instantan	neous Torque	Nm		0.8
Rotor Inertia J		imes10 ⁻⁴ kgm ²		0.23
Round Shaft Ty	ype Permissible Inertia J	$ imes 10^{-4} \mathrm{kgm^2}$	5.6	
Speed Control Range		80~4000 r/min (Speed ratio 1:50)		
		Load	Max. ± 0.2 % (± 0.5 %): Conditions 0 ~rated torque, rate	ed speed, rated voltage, normal ambient temperature
Speed Regulat	tion*	Voltage	Max. ± 0.2 % (± 0.5 %): Conditions Rated voltage -15	\sim +10 %, rated speed, no load, normal ambient temperature
		Temperature	Max. ± 0.2 % (± 0.5 %): Conditions Operating ambient	temperature 0 \sim +50 °C, rated speed, no load, rated voltage

• 200 W

•200 W			
Product Name	Motor	Combination Type with a Parallel Shaft Gearhead	BLM6200SHP-□S
		Round Shaft Type	BLM5200HP-AS
	Driver		BLE2D200-C
Rated Output	Power (Continuous)	W	200
	Rated Voltage	VAC	Single-Phase 200-240/Three-Phase 200-240
	Permissible Voltage Range		-15~+10 %
Power	Frequency	Hz	50/60
Supply Input	Permissible Frequency Range		±5 %
	Rated Input Current	A	Single Phase: 2.4/Three-Phase: 1.4
	Max. Input Current	A	Single-Phase: 6.5/Three-Phase: 4.3
Rated Speed		r/min	3000
Rated Torque		Nm	0.637
Max. Instantar	neous Torque	Nm	1.15
Rotor Inertia J		imes10 ⁻⁴ kgm ²	0.454
Round Shaft T	ype Permissible Inertia J	imes10 ⁻⁴ kgm ²	8.75
Speed Control	Range		80~4000 r/min (Speed ratio 1:50)
		Load	Max. ±0.2% (±0. 5%): Conditions 0~rated torque, rated speed, rated voltage, normal ambient temperature
Speed Regula	tion*	Voltage	Max. ±0.2% (±0.5 %): Conditions Rated voltage -15~+10 %, rated speed, no load, normal ambient temperature
		Temperature	Max. $\pm 0.2\%$ ($\pm 0.5\%$): Conditions Operating ambient temperature $0 \sim +50$ °C, rated speed, no load, rated voltage

*The value inside parentheses is the specification for analog setting. The values correspond to each specification and characteristics of a stand-alone motor.

ullet A number indicating the gear ratio is specified where the box \Box is located in the product name.

Product Name	Motor	Combination Type with a Parallel Shaft Gearhead	BLM6300SHP-⊡S
		Round Shaft Type	BLM5300HP-AS
	Driver		BLE2D300-C
Rated Output Po	ower (Continuous)	W	300
	Rated Voltage	VAC	Single-Phase 200-240/Three-Phase 200-240
	Permissible Voltage Range		-15~+10%
Power Supply	Frequency	Hz	50/60
Input	Permissible Frequency Range		$\pm 5\%$
	Rated Input Current	А	Single-Phase: 3.2/Three-Phase: 1.8
	Max. Input Current	А	Single-Phase: 8.5/Three-Phase: 6.0
Rated Speed		r/min	3000
Rated Torque		Nm	0.955
Max. Instantane	ous Torque	Nm	1.72
Rotor Inertia J		imes10 ⁻⁴ kgm ²	0.67
Round Shaft Typ	oe Permissible Inertia J	imes10 ⁻⁴ kgm ²	12
Speed Control F	lange		80~4000 r/min (Speed ratio 1:50)
		Load	Max. \pm 0.2% (\pm 0.5%): Conditions 0~rated torque, rated speed, rated voltage, normal ambient temperature
Speed Regulation	on*	Voltage	Max. $\pm 0.2\%$ ($\pm 0.5\%$): Conditions Rated voltage $-15 \sim +10\%$, rated speed, no load, normal ambient temperature
		Temperature	Max. \pm 0.2% (\pm 0.5%): Conditions Operating ambient temperature 0~+50°C, rated speed, no load, rated voltage

 $\ensuremath{\boldsymbol{\ast}}\xspace$ The value inside parentheses is the specification for analog setting.

• The values correspond to each specification and characteristics of a stand-alone motor.

 \bullet A number indicating the gear ratio is specified where the box \Box is located in the product name.

Speed – Torque Characteristics

Continuous Duty Region: Continuous operation is possible in this region. Limited Duty Region: This region is used primarily when accelerating.



• The values correspond to each specification and characteristics of a stand-alone motor. The speed - torque characteristics show the values when rated voltage is applied.

Common Specifications

Item		Specifications					
Croad Catting Mathada	Digital Setting	-Control Panel -Data Setting Software MEXEO2					
Speed Setting Methods Acceleration/ Deceleration Time Torque Limiting*1 Operating Data Setting N Input Signals Output Signal Protective Function General Information	Analog Setting	-Set using an External Speed Potentiometer PAVR2-20K (Sold separately): $0 \sim 20 \text{ k}\Omega$, 0.05 W min. -Set using External DC Voltage: $0 \sim 10 \text{ VDC}$, 1 mA min. (Factory setting: $0 \sim 5 \text{ VDC}$)					
Acceleration/	Setting Range	Setting ·Control Panel -Data Setting Software MEXEO2 Setting ·Set using an External Speed Potentiometer PAVR2-20K (Sold separately): 020 kΩ, 0.05 W min. Set using External DC Voltage: 0-10 VDC, 1 mA min. (Factory setting: 05 VDC) Range 0.0~15.0 s (Factory setting: 0.5 s) Control Panel -Data Setting Software MEXEO2 Setting ·Control Panel -Data Setting Software MEXEO2 Setting ·Control Panel -Data Setting Software MEXEO2 Setting ·Control Panel -Data Setting Software MEXEO2 Setting ·Set with an External Speed Potentiometer PAVR2-20K (Sold separately): 0~20 kΩ, 0.05 W min. -Set suing External DC Voltage: 0-10 VDC, 1 mA min. (Factory setting: 0~5 VDC) Max. 16 points (Factory setting: 4 points) Photocoupler Input Input Resistance: 6 kΩ Connectable External DC Volver Supply: 24 VDC -15~+20 % Current 100 mA or more. Sink Input/Source Input Supports External Wring Arbitrary signal assignment to INO~INN input (7 points) is possible []: Initial Setting [FWD], REV], [STOP-MODE], [M0], [M1], [ALARM-RESET], M2, M3, H-FREE, TL, HMI, EXT-ERROR START/STOP ²⁴ , RUWBRAKE ⁴² , CW/CCW ⁴² Photocoupler and Open-Collector Output (0 No max, (5 ma min. for SPEED-OUT output power) Sink Output/Source output Supported through external wring Arbitrary signal assignment to OUT0, OUT1 (2 points) is possible. []: Initial setting [SFEED-OUT1, [ALARM-OUT], MOVE, INFO, TLC, VA, DIR When the following protective functions are actrixted, the output from ALARM-OUT will turn OFF and					
Deceleration Time	Setting Method	Control Panel Data Setting Software MEXEO2					
	Setting Range	0~300% (Factory setting: 300 %)					
Torque Limiting ^{*1}	Digital Setting	-Control Panel -Data Setting Software MEXEO2					
	Analog Setting	et with an External Speed Potentiometer PAVR2-2OK (Sold separately): $0 \sim 20 \text{ k}\Omega$, 0.05 W min. et using External DC Voltage: $0 \sim 10 \text{ VDC}$, 1 mA min. (Factory setting: $0 \sim 5 \text{ VDC}$)					
Operating Data Setting Nu	mber	Max. 16 points (Factory setting: 4 points)					
Input Signals		Photocoupler Input Input Resistance: 6.6 kΩ Connectable External DC Power Supply: 24 VDC -15~+20 % Current 100 mA or more. Sink Input/Source Input Supports External Wiring Arbitrary signal assignment to INO~IN6 input (7 points) is possible []: Initial Setting [FWD], [REV], [STOP-MODE], [M0], [M1], [ALARM-RESET], M2, M3, H-FREE, TL, HMI, EXT-ERROR					
		START/STOP ^{#2} , RUN/BRAKE ^{#2} , CW/CCW#2					
Output Signal		Photocoupler and Open-Collector Output (ON Power supply: 1.6 V max.) External Power Supply: 4.5~30 VDC 100 mA max. (5 mA min. for SPEED-OUT output power) Sink Output/Source Output Supported through external wiring Arbitrary sional assignment to OUT0. OUT1 (2 points) is possible. [1: Initial setting					
		[SPEED-OUT], [ALARM-OUT], MOVE, INFO, TLC, VA, DIR					
Protective Function		When the following protective functions are activated, the output from ALARM-OUT will turn OFF and the motor will preform a coasting stop. At the same time, the alarm code will be displayed and the ALARM LED will blink. Overcurrent, main circuit overheat, overvoltage, undervoltage, sensor error, main circuit output error, overload, over-speed, EEPROM error, initial sensor error, initial operation prohibited, external stop					
General Information		When general information is generated, the INFO output will turn ON. The motor will continue to operate. Overvoltage, undervoltage, overload, operation start restriction mode, I/O test mode, configuration request, power on request, operation prohibited					
Max. Extension Length		Motor and driver distance: 20.5 m [when an accessory connection cable (for relaying) is used]					
Time Rating		Continuous					

*1 For the torque limit, an error up to a max. of approximately ±10 % (at rated torque and rated speed) may occur between the setting value and generated torque due to the setting speed, power supply voltage and motor cable extension length.
 *2 Can be used when 3 wire input method is selected.

General Specifications

Iter	m	Motor	Driver				
Insulation Resistance100 MΩ or more when 500 VDC megger is applied between the windings and the case after continuous operation under normal ambient temperature and humidity.The measured value is 100 MΩ or more when a 500 VD between the power supply terminal and the protective of and between the power supply terminal and the signal continuous operation under normal ambient temperature		The measured value is 100 M Ω or more when a 500 VDC megger is applied between the power supply terminal and the protective earth terminal and between the power supply terminal and the signal I/O terminal after continuous operation under normal ambient temperature and humidity.					
Sufficient to withstand 1.5 kVAC at 50 Hz applied betwe and the case for 1 minute after continuous operation un temperature and humidity.		Sufficient to withstand 1.5 kVAC at 50 Hz applied between the windings and the case for 1 minute after continuous operation under normal ambient temperature and humidity.	Sufficient to withstand the application of 1.5 kVAC at 50 Hz between the power supply terminal and the protective earth terminal for 1 minute, and with application of 1.5 kVAC at 50 Hz between the power supply terminal and the signal I/O terminal for 1 minute after continuous operation under normal ambient temperature and humidity.				
Temperature Rise Surface is 40 continuous of		The temperature rise of the windings is 50 °C max. and that of the case surface is 40 °C max.*1, measured by the thermocouple method after rated continuous operation under normal ambient temperature and humidity.	The temperature rise of the heat sink is 50 °C max., measured by the thermocouple method after rated continuous operation under normal ambient temperature and humidity.				
Operating Environment*2	Ambient Temperature	$0 \sim +40$ °C (Non-freezing)	$0 \sim +50^\circ C^{*3}$ (Non-freezing)				
	Ambient Humidity	85 % max. (Non-condensing)					
	Altitude	Max. of 1000 m above sea level					
	Atmosphere	No corrosive gases or dust. No oil splashing. Cannot be used in a radioactive area, magnetic field, vacuum, or other special environments.					
	Vibration	Not subject to continuous vibration or excessive shock. Con Frequency Range: $10{\sim}55$ Hz, Half Amplitude: 0.15 mm Sweet	forms to IEC 60068-2-6, "Sine-wave vibration test method" ap Direction: 3 directions (X, Y, Z) Number of Sweeps: 20 times				
	Ambient Temperature	$-20\!\sim\!+70~^\circ$ C (Non-freezing)	$-25{\sim}+70~^\circ\text{C}$ (Non-freezing)				
Storage Conditions ^{*4}	Ambient Humidity	85 % max. (Non-condensing)					
	Altitude	Max. of 3000 m	n above sea level				
	Atmosphere	No corrosive gases or dust. No oil splashing. Cannot be used in a rad	lioactive area, magnetic field, vacuum, or other special environments.				
Heat-Resistant C	lass	EN Standard: 120 (E)	-				
Degree of Protec	tion* ⁵	When connected to a cable: IP66 (Excluding the installation surface of the round shaft type and connectors on the driver side)	IP20				

*1 For round shaft types, install on a heat sink (material: aluminum) of one of the following sizes to maintain a motor case surface temperature of 90°C or less.

30 W type: 115×115 mm thickness 5 mm, 60 W type: 135×135 mm thickness 5 mm 120 W type: 165×165 mm thickness 5 mm, 200 W type: 200×200 mm thickness 5 mm 300 W type: 250×250 mm thickness 6 mm

*2 Install the driver to a location that has the same heat radiation capability as an aluminum metal plate. Installation of a stand-alone driver 200×200 mm thickness 2 mm Installation of multiple drivers 350×350 mm thickness 2 mm

 $30 \sim +40$ °C for installation of multiple drivers.

*4 The storage condition applies to short periods such as the period during transport.

*5 The IP display indicating watertight and dust-resistant performance is regulated by IEC 60529 and IEC 60034-5.

Note

• Do not measure insulation resistance or perform a dielectric strength test while the motor and driver are connected.

Motor Material and Surface Treatment

•Materials Case: Aluminum

Output Shaft: Stainless steel

Screws: Stainless steel (externally facing screws only; protective earth terminals excluded)

•Surface treatment Case: Paint (installation surface excluded)

Permissible Torque of Combination Types

Combination Type with a Parallel Shaft Gearhead

Combination	Combination Type with a Parallel Shaft Gearhead Unit: [Nm]								
Output Power [W]	Gear Ratio Motor Shaft Speed	5	10	15	20	30	50	100	200
	80~2500 r/min	0.54	1.1	1.6	2.2	3.1	5.2	6	6
30	3000 r/min	0.43	0.86	1.3	1.7	2.5	4.1	6	6
	4000 r/min	0.32	0.65	0.97	1.3	1.9	3.1	5.4	5.4
	80~2000 r/min	0.9	1.8	2.7	3.6	5.2	8.6	16	16
60	3000 r/min	0.86	1.7	2.6	3.4	4.9	8.2	16	16
	4000 r/min	0.65	1.3	1.9	2.6	3.7	6.2	12.4	14
	80~2000 r/min	2	4.1	6.1	8.1	11.6	19.4	30	30
120	3000 r/min	1.7	3.4	5.2	6.9	9.9	16.4	30	30
	4000 r/min	1.3	2.6	3.9	5.2	7.4	12.3	24.7	27
200	80~3000 r/min	2.9	5.7	8.6	11.5	16.4	27.4	51.6	70
200	4000 r/min	2.2	4.3	6.5	8.6	12.4	20.6	38.9	63
200	80~3000 r/min	4.3	8.6	12.9	17.2	24.6	41.1	70	-
300	4000 r/min	3.2	6.4	9.7	12.9	18.5	30.8	58	-

Unit: [r/min]

A colored background indicates gear shaft rotation in the same direction as the motor shaft. Others rotate in the opposite direction.

Output Shaft Speed of Combination Types

Gear Ratio Motor Shaft Speed	5	10	15	20	30	50	100	200
80 r/min	16	8	5.3	4	2.7	1.6	0.8	0.4
2000 r/min	400	200	133	100	66.7	40	20	10
2500 r/min	500	250	167	125	83.3	50	25	12.5
3000 r/min	600	300	200	150	100	60	30	15
4000 r/min	800	400	267	200	133	80	40	20

Permissible Inertia J of Combination Types

Combination Type with a Parallel Shaft Gearhead

Combination T	Combination Type with a Parallel Shaft Gearhead Unit: ×10 ⁻⁴ k						it: $ imes$ 10 ⁻⁴ kgm ²		
Output Power [W]	Gear Ratio	5	10	15	20	30	50	100	200
		12	50	110	200	370	920	2500	5000
30	When instantaneous stop or instantaneous bi- directional operation is performed*	1.55	6.2	14	24.8	55.8	155	155	155
		22	95	220	350	800	2200	6200	12000
60	When instantaneous stop or instantaneous bi- directional operation is performed*	5.5	22	49.5	88	198	550	550	550
		45	190	420	700	1600	4500	12000	25000
120	When instantaneous stop or instantaneous bi- directional operation is performed*	25	100	225	400	900	2500	2500	2500
		100	460	1000	1700	3900	9300	18000	37000
200	When instantaneous stop or instantaneous bi- directional operation is performed*	50	200	450	800	1800	5000	5000	5000
		100	460	1000	1700	3900	9300	18000	-
300	When instantaneous stop or instantaneous bi- directional operation is performed*	50	200	450	800	1800	5000	5000	-

*It is also applicable when digitally setting the deceleration time to below 0.1 seconds.

Permissible Radial Load and Permissible Axial Load

Combination Type with a Parallel Shaft Gearhead

			Permissible	Radial Load		
Output Power IWI	Gea	r Ratio	10 mm from the end of the	20 mm from the end of the	Permissible Axial Load	
				output shaft		
			[N]	[N]	[N]	
	5	80~3000 r/min	100	150		
	5	4000 r/min	90	110		
30	10 15 20	80~3000 r/min	150	200	40	
50	10, 13, 20	4000 r/min	130	170	40	
	20 50 100 200	80~3000 r/min	200	300		
	30, 30, 100, 200	4000 r/min	180	230		
	E	80~3000 r/min	200	250		
	5	4000 r/min	180	220		
40	10 15 20	80~3000 r/min	300	350	100	
80	10, 15, 20	4000 r/min	270	330	100	
	30, 50, 100, 200	80~3000 r/min	450	550		
		4000 r/min	420	500		
	5	80~3000 r/min	300	400		
		4000 r/min	230	300		
100	10, 15, 20	80~3000 r/min	400	500	150	
120		4000 r/min	370	430	150	
	20 50 100 000	80~3000 r/min	500	650		
	30, 50, 100, 200	4000 r/min	450	550		
	5 10 15 20	80~3000 r/min	550	800	200	
	5, 10, 15, 20	4000 r/min	500	700	200	
200	20.50	80~3000 r/min	1000	1250	200	
200	30, 30	4000 r/min	900	1100	500	
	100 200	80~3000 r/min	1400	1700	400	
	100, 200	4000 r/min	1200	1400	400	
	5 10 15 20	80~3000 r/min	550	800	200	
	5, 10, 15, 20	4000 r/min	500	700	200	
200	20 50	80~3000 r/min	1000	1250	200	
300	30, 30	4000 r/min	900	1100	300	
	100	80~3000 r/min	1400	1700	400	
	100	4000 r/min	1200	1400	400	

Round Shaft Type

	Permissible	Radial Load	
Output [W]	10 mm from the end of the output shaft	20 mm from the end of the output shaft	Permissible Axial Load
	[N]	[N]	
30	80	100	
60	80	100	
120	150	170	Half of motor mass max.
200	150	170	
300	150	170	



Dimensions (Unit = mm)

• The motor dimensions in this catalogue are the dimensions when a separately sold connection cable (the _____ color in the diagrams) is attached.

Listed masses do not include the mass of the connection cable.

Refer to page 20 for the dimensions and masses of connection cables.

Installation screws" are included with the combination type. Dimensions for installation screws -> Page 20

 \blacksquare A number indicating the gear ratio is specified where the box \square is located in the product name.

Motor: 30 W

\diamondsuit Combination Type with a Parallel Shaft Gearhead

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass [kg]
			5~20	34	
BLM230HP-🗆S	BLM230HP-GFV	GFV2G⊡S	30~100	38	0.85
			200	43	1

•When connection cable is attached for pull-out on output shaft side



At the time of shipment, a key is fixed in the key slot of the gearhead shaft.

• When connection cable is attached for pull-out on rear of the motor

•For vertical pull-out



Mass: 0.35 kg





Motor: 60 W

\diamondsuit Combination Type with a Parallel Shaft Gearhead

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass [kg]
			5~20	41	
BLM460SHP-🗆S	BLM460SHP-GFV	GFV4G⊡S	30~100	46	1.6
			200	51	

•When connection cable is attached for pull-out on output shaft side





At the time of shipment, a key is fixed in the key slot of the gearhead shaft.

•When connection cable is attached for pull-out on rear of the motor



For vertical pull-out

0



◇Round Shaft Type BLM260HP-AS Mass: 0.52 kg







(2/)

Motor: 120W

\bigcirc Combination Type with a Parallel Shaft Gearhead

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass [kg]
			5~20	45	
BLM5120HP-	BLM5120HP-GFV	GFV5G⊡S	30~100	58	2.6
			200	64	

•When connection cable is attached for pull-out on output shaft side





•For vertical pull-out

90

10ľ

(1)

20.5

14.5-0.1

Ø

6

(8)





Motor: 200W

◇Combination Type with a Parallel Shaft Gearhead

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass [kg]
			5~20	60	
BLM6200SHP-	BLM6200SHP-GFV	GFV6G⊡S	30 , 50	72	4.7
			100.200	86	

•When connection cable is attached for pull-out on output shaft side









•At the time of shipment, a key is fixed in the key slot of the gearhead shaft.

• When connection cable is attached for pull-out on rear of the motor





◇Round Shaft Type BLM5200HP-AS Mass: 1.6 kg







For vertical pull-out







Motor: 300W

\diamondsuit Combination Type with a Parallel Shaft Gearhead

Product Name	Motor Product Name	Gearhead Product Name	Gear Ratio	L	Mass [kg]
			5~20	60	
BLM6300SHP-	BLM6300SHP-GFV	GFV6G⊡S	30, 50	72	5.2
			100	86	

• When connection cable is attached for pull-out on output shaft side



•At the time of shipment, a key is fixed in the key slot of the gearhead shaft.

• When connection cable is attached for pull-out on rear of the motor



◇Round Shaft Type BLM5300HP-AS Mass: 2.1 kg

(17)



47.3

Protective Earth Terminal M4/



58.7

•For vertical pull-out





Driver BLE2D30-A, BLE2D30-C, BLE2D60-A, BLE2D60-C, BLE2D120-A, BLE2D120-C, BLE2D200-C, BLE2D300-C Mass: 0.8 kg



Connection Cable

Longth	Product Name				
Lengui L [m]	Pull-out on output shaft side	Pull-out on rear of the motor	Vertical direction	[kg]	
0.5	CC005KHBLF	CC005KHBLB	CC005KHBLV	0.08	
1	CC010KHBLF	CC010KHBLB	CC010KHBLV	0.12	
1.5	CC015KHBLF	CC015KHBLB	CC015KHBLV	0.2	
2	CC020KHBLF	CC020KHBLB	CC020KHBLV	0.25	
2.5	CC025KHBLF	CC025KHBLB	CC025KHBLV	0.32	
3	CC030KHBLF	CC030KHBLB	CC030KHBLV	0.38	
4	CC040KHBLF	CC040KHBLB	CC040KHBLV	0.49	
5	CC050KHBLF	CC050KHBLB	CC050KHBLV	0.62	
7	CC070KHBLF	CC070KHBLB	CC070KHBLV	0.86	
10	CC100KHBLF	CC100KHBLB	CC100KHBLV	1.2	
15	CC150KHBLF	CC150KHBLB	CC150KHBLV	1.9	
20	CC200KHBLF	CC200KHBLB	CC200KHBLV	2.5	

• Pull-out on output shaft side, Pul-out on rear of the motor



Installation Screw Dimensions

Included with a combination type with a parallel shaft gearhead.





Gearhead Product	Installati	on Screw	
Name	L1 [mm]	Screw Size	L2 [mm]
GFV2G5~20S	50		42
GFV2G30~1005	55	M4 P0.7	46
GFV2G200S	60		51
GFV4G5~20S	60		49
GFV4G30~1005	65	M6 P1.0	54
GFV4G200S	70		59
GFV5G5~205	70		55
GFV5G30~100S	85	M8 P1.25	68
GFV5G200S	90		74
GFV6G5~20S	85		70
GFV6G30~50S	100	M8 P1.25	82
GFV6G1005~2005	110	I	96

Installation Screws: Plain washer, spring washer included (4 each)

•The installation screw material is stainless steel.

Connection and Operation

Names and Functions	of Driver Parts	Name	Indication	Description
			-	Indicator: Displays monitor contents, setting screen, alarm, etc.
Control Panel - Display -	Setting Dial	Control Panel	MODE LOCAL RUN STOP	Operation Key: Switches operation modes and changes parameters Operates and stops the motor using RUN key and STOP key during local control operation
	ALARM LED (Red)	Setting Dial	PUSH-SET	Sets the speed and parameters
LOCAL LED (Gleen)	ALANIVI LED (NEU)			
1.1	Country Longe	LOCAL LED (Green)	LOCAL	Illuminates during local control operation
Sensor Connector (CN4)	1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	ALARM LED (Red)	ALARM	Blinks when an alarm occurs
CHARGE LED (Red)	USB Communication Connector	CHARGE LED (Red)	CHARGE	Illuminates when the main power supply is turned on Turns off after the main power supply is turned off and internal residual voltage is reduced to a stable level
Motor Connector (CN2)			-	Connects the main power supply
		Main Power Supply Input Terminals (CN1)	L, N, NC	Single-Phase 100-120 VAC: Connects 100-120 VAC to L and N. NC is not used.
Main Power Supply Input Terminals (CN1)			L1, L2, NC L1, L2, L3	Single-Phase 200-240 VAC: Connects 200-240 VAC to L1 and L2. NC is not used. Three-Phase 200-240 VAC: Connects three-phase 200-240 VAC to L1
	1 1000		21, 22, 20	L2, L3
	12 1		RG1, RG2	No connection
Protective E	arth Terminal	Motor Connector (CN2)	MOTOR	Connects a connection cable's power connector (white)
		Sensor Connector (CN4)	HALL-S	Connects a connection cable's sensor connector (black)
		USB Communication Connector	•	Connects a PC that has data setting software MEXEO2 installed
				Connects input signals
		I/O Signal Connector	1/0	Connects accessories such as external speed potentiometer (sold
		(CN5)	1/0	separately) and external DC power supply
				Connects output signals
		Protective Earth Terminal		Connects the protective earth terminal of a connection cable and a grounding conductor

\Diamond Operation Key

BLE2 Series has 4 operating modes.

	· -	
Operating Mode	Description	Setting Items
Monitoring Mode	This mode is displayed when the power is turned on.	Speed, load factor, operating data number, alarm, general information, I/O monitor
Data Mode	It sets a max. of 16 speeds of operating data.	Speed, torque limiting value, acceleration time, deceleration time, reset
Parameter Mode	It sets various parameters.	Basic setting parameter, speed and torque limiting adjustment parameter, alarm and general information setting parameter, operation setting parameter, I/O operation parameter, I/O function selection parameter, I/F function parameter, reset, configuration
Test Mode	It is used to check the connection status of the I/O signals.	

◇Main Power Supply Input Terminals (CN1)

Connects the main power supply. Connect a power supply that matches the power supply voltage to be used.



♦ USB Cable Connection

Please use a USB cable which meets the following specifications.

Specifications	USB 2.0 (Full speed)
Cablo	Length: 3 m max.
Cable	Configuration: A - mini-B

Operation Using the Control Panel

♦ Selection of the Operation Control

Pressing the "LOCAL key" will illuminate the LOCAL LED and the control panel can be used to operate.

♦ Selection of the Rotation Direction

The rotation direction of a motor will change every time the "MODE key" is pressed.

\bigcirc Starting and Stopping a Motor

Motor rotates when "RUN" is pressed. Motor stops when "STOP" is pressed.

♦ Speed Setting Method

The display will flash when "Setting Dial" is pressed, and the speed increases when it is turned clockwise. Turning it counterclockwise will decelerate. Pressing the "Setting Dial" will set the speed.

Control Panel



Operation by External Signals

◇I/O Signal Connector (CN5)

Pin No.	Signal Type	Signal Name	Function*	Description		$\frac{10}{11}$		
1		IN-COM0	IN-COM0	Input signal common (for external power supply)				
2		INO	FWD	The motor rotates when FWD input or REV input is turned ON.	0 wire input	$13 \boxed{0} \boxed{4}$		
3		IN1	REV	Turning it OFF decelerates the motor to a stop.	2-wire input	<u>14</u> <u>5</u>		
4		IN2	STOP-MODE	Selects the method for stopping the motor.	mealou			
5		IN3	MO	Selecte the operation data number through the selection of M0, M1 input ON/OF	E	16		
6		IN4	M1		г.	$\frac{17}{10}$		
7	Input	IN5	ALARM-RESET	Alarms are reset.	arms are reset.			
8	input	IN6	Not used	Assigns various functions.	• Applicable			
9		IN-COM1	IN-COM1	Input signal common (for internal power supply: 0 V)				
10		NC		No connection				
11		N.C.	-		AWG24 \sim 18			
12		VH		The second state of the second state of the Property of the second state of the second		$-(0.2 \sim 0.75 \text{ mm}^2)$		
13		VM	External Analog Setting	It is connected when speed and torque limiting value are set externally using an notentiometer or external DC voltage	external speed			
14		VL	input	potentionneter of external Do voltage.	potentionneter of external DC voltage.			
15		0UT0+		30 pulses are output with each rotation of the motor output shaft.		_		
16	Output	0UT0-	5F LLD-001					
17	υαίραι	0UT1+		Output when an alarm activates (Normally alaged)		-		
18]	OUT1-		oulput when an diarm activates. (wornally Closed)				

*The text inside the ______ represents the factory default function assignment. Pin No. 2 - 8, 15 - 18 can change the assigned functions. Assignment points are 7 points for the 12 types of input signal and 2 points for the 7 types of output signal.

Assignment points are 7 points for the 12 types of input signal and 2 points for the

Signal Type	Function	Description			
	START/STOP	The motor rotates when the START/STOP input and RUN/BRAKE input are ON.			
	RUN/BRAKE	The motor decelerates to a stop when START/STOP input is turned OFF. The motor comes to an instantaneous stop when RUN/BRAKE input is turned OFF.	3-wire input method		
	CW/CCW	This signal switches the motor's rotation direction.			
11	M2	This signal selects the operating data number			
input	M3				
	H-FREE	The easy hold is cancelled when the H-FREE input is ON.			
	TL	This signal enables and disables torque limiting from the outside.			
	HMI	This signal limits the operation that uses a control panel or data setting software MEXEO2 .			
	EXT-ERROR	This signal forcefully stops the motor from the outside.			
	MOVE	This signal is output when the motor is rotating with the operation input turned ON.			
	INFO	This signal is output when general information is generated.			
Output Power	TLC	This signal is output when the motor's output torque has reached the torque limiting value.			
	VA	This signal is output when the motor's detection speed has reached the setting speed \pm VA detection width.			
	DIR	This signal outputs the motor's rotation direction.			

Connection Diagram

This is a connection example for single-phase 200-240 VAC when setting the speed from the outside. The I/O signal inside [] is the factory setting.

♦ Using Built-in Power Supply

Driver Driver Motor Connecti Motor Connection Main Circuit CN1 Main Circuit CN1 RG1 Motor C RG1 CN2 Moto CN2 Moto RG2 D RG2 Circuit Br NC Circuit B NC PE Power Supply Connection Power Supply ^L Connection _N N Ν Ν Ν NC NC Driver Ground PE Driver Ground ∉ PE ₫ CN4 Sensor Conne <. Control Circuit Speed setting with external speed potentiometer (accessory) or external DC voltage <u>CN5</u> USB Connection CN4 < Control Circuit +5 \ Speed setting with external speed USB Connection potentiometer (accessory) or external DC voltage CN5 +5 V 4 12 ٧M CN5 VM CNS 13 VH 12 N.C. VM 3 <u>®</u> 14 VM ov 🕹 Connection of In 20.4~28.8 VDC 13 Command Voltage 13 7 . VL e 10 V 14 14 CNS ov ₹ 100 mA min IN-COMO 6.6 kΩ +5 V \$ External DC ₽=⊂ Voltage 10 V max. INO [FWD] Connection of Input Signal 2 CN5 IN1 [REV] 6.6 kΩ IN-COM0 3 INO [FWD] ז≈ע IN2 2 OP-MODE IN1 [REV] 4 3 IN3 15]⊈=([M0] IN4 IN2 [STOP-MODE] <u></u> 5 16 4 IN4 [M1] IN5 [ALARM-RESET] 15 IN3 [M0] 17 ¥ 5 本 6 IN4 [M1] 16 6 IN5 [ALARM-RESET] 17 7 7 18 8 IN-COM1 9 ₹ov N.C. 10 Ψov ľ N.C. N.C. 11 10 N.C. 11 ----

♦ Using External Power Supply

Timing Chart (2-wire input method)



I/O Signal Circuits

Select the sink logic or source logic wiring according to the external control device that will be used.

◇Input Signals



◇Programmable Controller Connection Examples

Sink Logic



Source Logic



- FWD Input, REV Input
- When FWD input is ON, it rotates in CW direction (clockwise). Turning it OFF decelerates the motor to a stop.

When REV input is ON, it rotates in CCW direction (counterclockwise). Turning it OFF decelerates the motor to a stop.

STOP-MODE Input

It selects the method for stopping the motor when FWD input and REV input are turned OFF. When the STOP-MODE input is OFF, the motor decelerates to a stop according to the deceleration stop of the operating data number. When STOP-MODE is ON, it stops at the shortest

time (instantaneous stop).

⊘Output Circuit



♦ When an External Control Device with a Built-In Clamp Diode is Used

If an external control device with a built-in clamp diode is connected and the external control device is turned off when the driver power is on, current may flow in and rotate the motor. Because the current capacity of the driver and external control device is different, the motor may also rotate when their power supplies are turned ON or OFF simultaneously. To turn the power off, turn off the driver and then the external control device. To turn the power on, turn on the external control device and then the driver.

• Example of Sink Logic



♦ SPEED-OUT

Pulse signals of 30 pulses (pulse width: 0.2 ms) are output per each rotation of the motor output shaft in synchronization with the motor operation.

The speed output frequency can be measured and the approximate motor speed calculated.



Motor Shaft Speed [r/min] = $\frac{\text{SPEED-OUT Frequency [Hz]}}{30} \times 60$



◇ALARM-OUT

When any of the driver's protective functions is activated, the output turns OFF and the ALARM LED blinks. An alarm code will be displayed on the control panel and the motor will coast to a stop.

Speed Setting Methods

Speed can be set using the following 4 methods.

♦ Using the control panel



♦ Using the external speed potentiometer

Connect an external speed potentiometer to the I/O signal connector (CN5) of the driver.



Note

The speed in the graph represents the speed of the motor alone. The output gear shaft speed of the combination type is calculated by dividing the graph speed by the gear ratio.

♦ Set using external DC voltage

Connect external voltage to the I/O signal connector (CN5) of the driver.



· External DC Voltage — Speed Characteristics (Representative values) Example: 0~5 VDC 4000 Motor Shaft Speed (r/min) 3500 3000 2500 2000 1500 1000 500 0 2 3 Δ 5 External DC Voltage (V)

Note

●It can be set at 0~10 VDC.

The speed in the graph represents the speed of the motor alone. The output gear shaft speed of the combination type is calculated by dividing the graph speed by the gear ratio.

◇Using Data Setting Software (MEXEO2)

PC that has data setting software (MEXEO2) installed



• Multiple Speed-Change Operation (Max. 16 speeds) Operation data number is selected by combining the M0~M3 input

ON/OFF.				
Operating Data Number	M3	M2	M1	MO
0	0FF	0FF	0FF	OFF
1	OFF	OFF	OFF	ON
2	0FF	OFF	ON	OFF
3	0FF	OFF	ON	ON
4	0FF	ON	0FF	0FF
5	0FF	ON	OFF	ON
6	0FF	ON	ON	0FF
7	0FF	ON	ON	ON
8	ON	OFF	OFF	OFF
9	ON	OFF	0FF	ON
10	ON	OFF	ON	OFF
11	ON	OFF	ON	ON
12	ON	ON	OFF	OFF
13	ON	ON	OFF	ON
14	ON	ON	ON	0FF
15	ON	ON	ON	ON

Parallel-Motor Operation

Multiple motors can be operated at the same speed using 1 potentiometer or external DC voltage.

The figure below shows an example of the single-phase power supply specification. For a three-phase specification, change the power supply line to a three-phase power supply. The motor operation control unit is not illustrated in the figure.

♦ Using a Potentiometer

When using a potentiometer (VRx), operate with 20 units or less.

Resistance value when the number of drivers is n: VRx=20/n (k Ω), n/4 (W)

Example: When 2 drivers are connected

VRx = 20 k $\Omega/3$ = 6,67 k Ω ; P = 3/20 W = 0,15 W Selected potentiometer: 6,8 k Ω ; 0,25 W.



\bigcirc Using External DC Voltage

The power supply capacity of the external DC power supply is determined as follows.

Power supply capacity when the number of drivers is n: $I=1 \times n \text{ (mA)}$

Example: When 2 drivers are connected $I=1\times2=2$ (mA)

Power supply capacity is 2 mA min.



Accessories (Sold separately)

Cable System Configuration



1 Connection Cable (for relaying), Flexible Connection Cable (for relaying)

When extending the cable by adding connection cables (for relaying)/flexible connection cables (for relaying), ensure that the overall length of the cable is 20.5 m max (up to a total of 3 cables).

Product Line

♦ Connection (Cables
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Product Name	Length L [m]	List Price	
CC01BL2	1	25.00 €	٣ ()
CC02BL2	2	32.00€	
CC03BL2	3	40.00€	
CC05BL2	5	78.00€	
CC07BL2	7	102.00€	
CC10BL2	10	137.00€	

2 Power Supply Cable

These cables are used to connect the driver and the AC power supply. Cables are available with or without a power supply plug.



Plug Included

Product Line

Product Name	Power Supply Voltage	Length L [m]	List Price
CC01AC03N	Cingle Dhase 100, 100 VAO	1	11.00€
CC02AC03N	Single-Priase 100-120 VAC	2	17.00€
CC03AC03N	011gic-1 11d3c 200-240 VA0	3	22.00€
CC01AC04N		1	11.00€
CC02AC04N	Three-Phase 200-240 VAC	2	17.00€
CC03AC04N		3	22.00€

\bigcirc Flexible Connection Cables

Length L [m]	List Price	
1	60.00€	٣ ()
2	84.00 €	
3	107.00€	
5	156.00€	
7	203.00 €	
10	275.00 €	
	Length L [m] 1 2 3 5 7 10	Length L [m] List Price 1 60.00 € 2 84.00 € 3 107.00 € 5 156.00 € 7 203.00 € 10 275.00 €

3 General-Purpose Cables for I/O Signals

These cables connect the driver and programmable controller.



Product Line

Product Name	Length L [m]	Number of Lead Wire Cores	Outer Dimensions D [mm]	AWG	List Price
CC06D005B-1	0.5				13.00€
CC06D010B-1	1	6	45.4		15.00€
CC06D015B-1	1.5	0	φ3.4		17.00€
CC06D020B-1	2				17.00€
CC10D005B-1	0.5				15.00€
CC10D010B-1	1	10	ф6.7	- 24	17.00€
CC10D015B-1	1.5				18.00€
CC10D020B-1	2				21.00€
CC12D005B-1	0.5				17.00€
CC12D010B-1	1	10	175		18.00€
CC12D015B-1	1.5	12	φ7.5		22.00€
CC12D020B-1	2				24.00€
CC16D005B-1	0.5				18.00€
CC16D010B-1	1	16	175		20.00€
CC16D015B-1	1.5	10	φ7.5		23.00€
CC16D020B-1	2]			25.00€

Note

An external speed potentiometer (**PAVR2-20K**) and a general-purpose cable for I/O signals cannot be used together.

Flexible Coupling

This is a clamp type coupling for connecting the motor and gearhead shaft with a driven shaft.



Orientalmoto

It can be used on a round shaft type as well. Please select a coupling with an inner diameter that matches the motor shaft's diameter.

Product Line

Applicable Product	Load Type	Couplings Type	List Price	
PI M220	Uniform Load		39.00€	
BLM230	Impact Load	MCLSU Type		
	Uniform Load	MCL40 Type	60.00€	
BLM400	Impact Load	MCL55 Type	79.00€	
BI ME 1 20	Uniform Load		70.00 6	
BLM3120	Impact Load	MCL33 Type	79.00 E	
BLM6200,	Uniform Load		127.00 E	
BLM6300	Impact Load	MCLOS Type	127.00€	

External Speed Potentiometer

Features

A Potentiometer that can adjust speed and torque.

Easy Installation

Simply insert it into the installation hole without using any tools. It can also be removed easily.

Easy Wiring

It uses terminal blocks. It requires no soldering for connecting lead wires.

This improves the work efficiency of the wiring.



<Front Face>

Product Line				
Product Name	Applicable Product	List Price		
PAVR2-20K BLE2 Series, BXII Series, BLH Series, DSC Series 19.00 €				
The following items are included with each product				

The fellewing fellewine are included with each product.	
External Speed Potentiometer, Operating Manual	

Note

An external speed potentiometer (PAVR2-20K) and general-purpose cable for I/O signals cannot be used together.

Specifications

Resistance: 0~20 k Ω Rated Power: 0.05 W Resistor Variable Characteristics: B curve

Applicable Lead Wire Size*

AWG22~18 (0.3~0.75 mm²) *When combined with BLE2 Series

Motor and Gearhead Installation **Bracket**

These dedicated installation brackets are convenient for installing and fixing motors and gearheads.



2

Product Line

Product Name	Applicable Product	List Price
SOL2M4F	BLM230, BLM260 (Round shaft type)	26.00 €
SOL4M6F	BLM460 (Combination type)	29.00 €
SOL5M8F	BLM5120, BLM5200, BLM5300 (Round shaft type)	30.00 €
SOL6M8F	BLM6200, BLM6300 (Combination type)	32.00 €

Note

When fixing the mounting brackets and motors, ensure that the motor connector is facing upwards or sideways with respect to the installation surface.

Installing with the motor connector facing downwards is not recommended as this will interfere with the mounting brackets and installation surface.





DIN Rail Mounting Bracket

Use DIN rail mounting brackets to install a driver to a DIN rail.

	Pr	oc	luc	t l	Lin	e
-					_	

Jse DIN rail mounting brackets to install a driver to a DIN rail.			1 - m
Product Lin	e		3
Product Name	Applicable Product	List Price	
MADP02	BLE2 Series BXII Series BLH Series (100 W)	21.00€	-

Regeneration Unit

During vertical drive (gravitational operation) and when starting and stopping large inertia loads rapidly, external forces cause the motor to rotate and function as a power generator. When that occurs, if the regenerative power exceeds the capacity of the driver to absorb, failure may result. In such cases, the regeneration unit is connected to the driver and the regenerative power is released as heat energy.

Product Line

Product Name	List Price
RGB100	45.00 €

Specifications

Continuous Regenerative Power	70 W
Instantaneous Regenerative Power	720 W
Resistance Value	150 Ω
Thermal Protector Operating Temperature	Open: 150 ±7 °C Close: 145 ±12 °C (Normally closed))

Attach the regeneration unit to a location that has the same heat radiation capability as an aluminum heat radiation plate that is 350×350 mm and 3 mm thick.

For details, check the website or contact the customer support center. http://www.orientalmotor.eu

Motor Cover

This cover protects the motor. They are compatible with the degree of protection IP66 specification, and can be used in wet and dusty environments.

Product Line

Product Name	List Price
PCM5	33.00 €
PCM5-C	41.00 €

Replace the gasket approximately once a year.			S
Product Name	Set contents		List Price
PCMP5	Set of 2 gaskets		7.00€





With Brush Cap PCM5 With a Cable Gland PCM5-C

Applicable Product

Output Power [W]	Motor	Cable Pull-out Direction	
30, 60, 120	Parallel Shaft Combination Type*	Pull-out on output shaft side	
	Round Shaft Type	Pull-out on rear of the motor	
*In the case of a combination type, the cable with pull-out on rear of the motor cannot be used.			

Note

The cable with vertical pull-out cannot be used.

30

Introduction of Related Products

Brushless Motor and Driver Packages BMU Series



The BMU Series: Excellent ease of use with a setting dial for easy speed control, easy wiring, etc. There is also a new connector type that allows for direct connection between the motor and driver. The highest standard in speed control at an affordable price.

Features

- · Easy Speed Control by Turning and Pressing Dial
- · Easy Wiring, Easy Set Up
- · Compact, High Power and High Efficiency Motor
- Speed Control Range 80~4000 r/min
- Speed Regulation (Load) ±0.2%

- · Load Factor Indication and Alarm Indication are Possible
- · Multistep Speed-Change Operation up to 4 Speeds is Possible
- · Acceleration/Deceleration Time Can be Set
- · Output Shaft Holding when Stopped



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These products are manufactured at plants certified with the international standards **ISO 9001** (for quality assurance) and **ISO 14001** (for systems of environmental management).

Specifications are subject to change without notice. Published in August 2022

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