

***Orientalmotor***

**NEW**  
PRODUCTS

**(RoHS)** RoHS-Compliant  
5 Phase Stepping Motor Unit  
**CRK Series**

Type with Built-In Controller  
24 VDC Microstep Drive



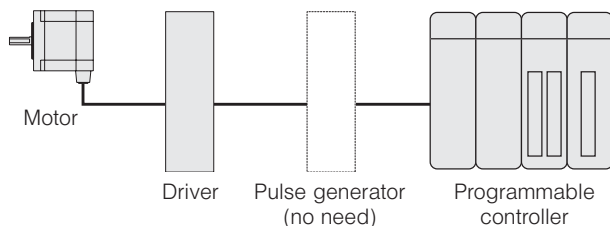
5 Phase Microstep Stepping Motor Unit with DC-Input and Integrated Controller. Two Control Methods Including I/O-Control can be selected.



## Features

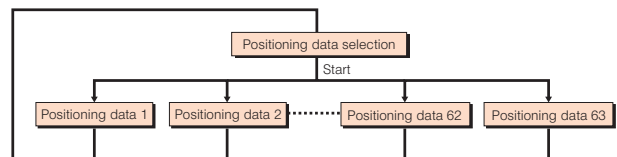
### ● Space-Saving, Less Wiring

The compact driver and the needlessness of a pulse generator make the device space-saving and the system simpler.



### ● Positioning Data of up to 63 Points

Up to 63 points of positioning data can be set in the driver. Each data can be set either in the incremental mode or in the absolute mode.



The positioning data can be set with the control module OPX-2A (sold separately) or via RS-485 connection.

## Three Operating Patterns

### ● Positioning Operation

The motor operation speed and movement distance are set in the positioning data and the operation is realized based on the selected positioning data. Continuous operation and sequential operation can be selected.

### ● Return to Home Operation

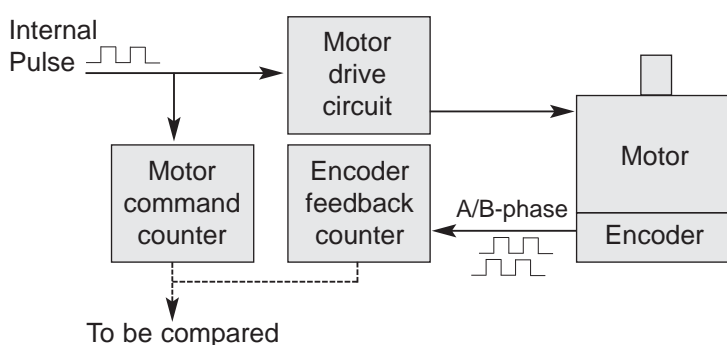
This function allows an easy return to home operation by using sensors.

### ● Speed Control Operation

With FWD signal input and RVS signal input the motor operates continuously. As the operation runs with the prior set positioning data, multi-speed operation can be realized by changing the data number.

## Useful Functions

### ● STEP-OUT Output Function



### ● PLS-OUT Output Function

### ● Multi-axes Operation Function

### ● Sensor Input Function

### ● Teaching Function

When a commanded position to the motor and a feedback position from the encoder are compared, and an abnormal deviation is detected, STEP-OUT (Misstep detection output) is turned on. Warning, or Alarm can be generated as well.

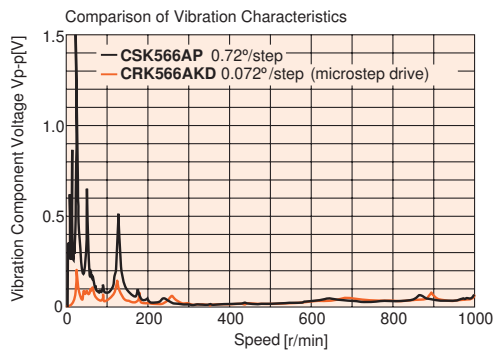
The motor resolution need not correspond with the encoder resolution because the resolution is matched by the internal encoder electronic gear function.



## Low Vibration, Low Noise

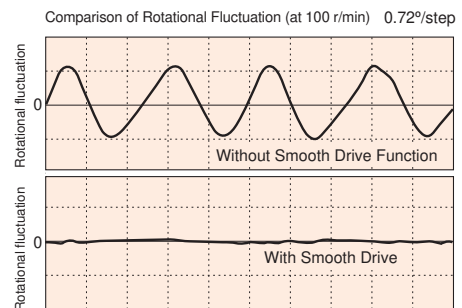
### ● Lower Vibration and Noise Achieved by Microstep Drive

The basic step angle of the motor can be divided into a maximum of 250 microstep angles without using any mechanical element such as a reduction gear. As a result, vibration and noise are further reduced.



### ● Smooth Drive Function for Enhanced Ease of Use

The Smooth Drive Function automatically controls operations via microstep drive, at the same travel distance and speed used in the full-step mode.



## Compact Driver for DIN Rail Mounting

### ● Compact DC-Input Driver with Mounting Case

The driver has a compact size of 35 mm (width) x 100 mm (height) x 70 mm (depth) and therefore contributes to a space-saving control box and device.



### ● DIN Rail Mounting Possible

The driver is made for direct DIN rail mounting, screws are not necessary.



## Lineup

The standard type and TH geared type are available with 42 mm and 60 mm frame size, in total 32 types are provided.

### ● Standard Type

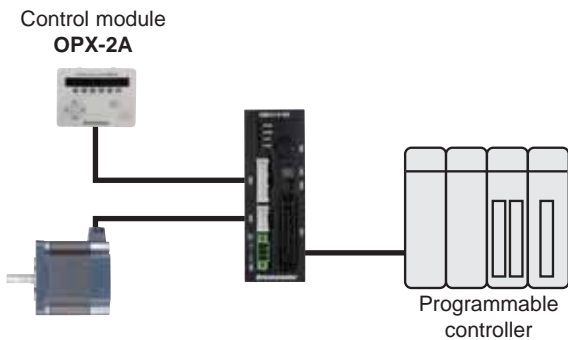


### ● TH Geared Type



# Two control methods

## I/O controlled system

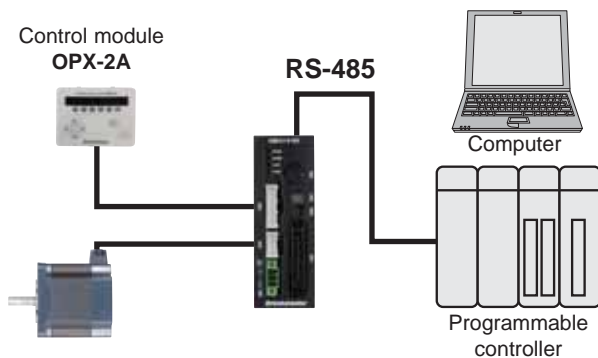


### I/O control

Setting and input method of operation command

Setting of operation command and parameter	Operation command (START, STOP, etc.)
Control module (OPX-2A)	I/O

## RS-485 controlled system



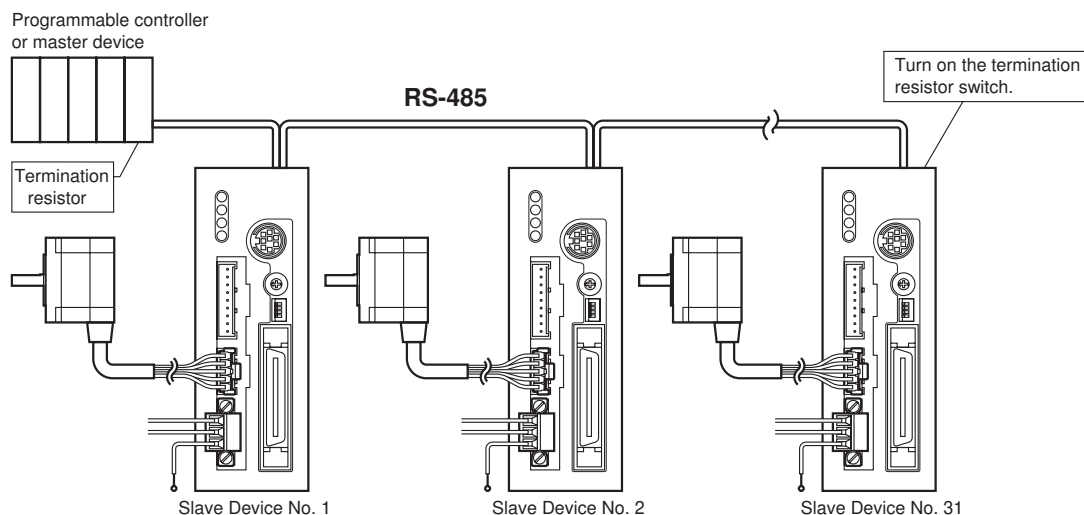
### RS-485 control

Setting and input method of operation command

Setting of operation command and parameter	Operation command (START, STOP, etc.)
Control module (OPX-2A) RS-485 communication	I/O RS-485 communication

# RS-485 communication - Example of system configuration

## Connection example



- Up to 31 units can be connected to a host master.
- Operation data and parameter can be set by the RS-485 communication and OPX-2A.
- Both the I/O and the RS-485 communication can be used for inputting the operation command.

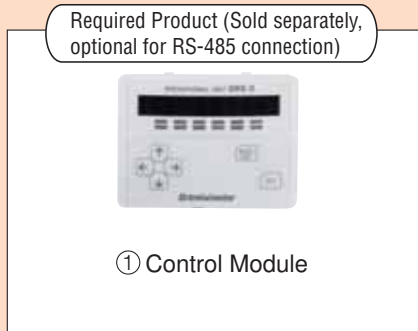
Example:

**STOP** input ⇨ I/O control

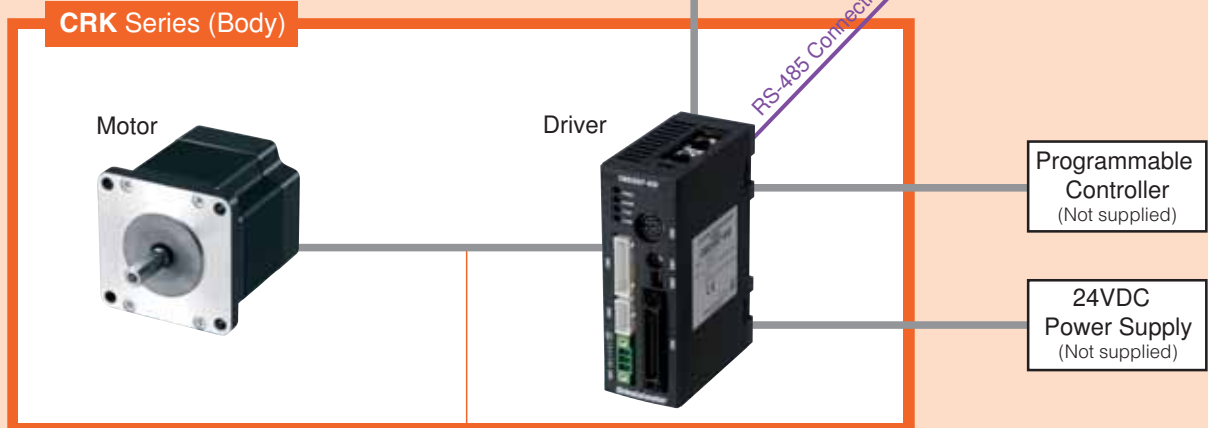
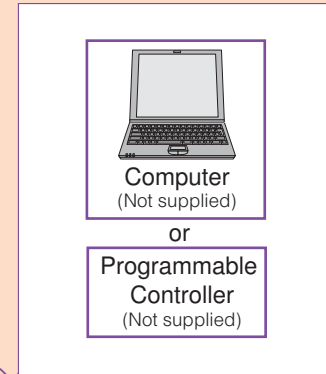
**START** input ⇨ RS-485 communication control

## System Configuration

### For I/O Control



### For RS-485 Connection



### Selectable Accessories and Peripheral Equipment (Sold separately)



No.	Product Name	Overview
①	Control Module	This Control Module lets you set various data (edit, monitor, operate) and comes with a communication cable (5 m).
②	Motor Mounting Brackets	Dedicated mounting bracket for the motor.
③	Flexible Couplings	Coupling that connects the motor shaft to the driven shaft.
④	Clean Dampers	Dedicated damper for suppressing stepping motor vibration.
⑤	Extension Cables	Cable for extending the wiring distance between the motor and driver (5 m, 10 m).
⑥	Lead Wire with Connector (For encoder connection)	Lead wire with Connector. Cable to connect the encoder with the driver (0.6 m).

### Example of System Configuration

#### For I/O Control:

CRK Series	Control Module	+	Extension Cable (5m)	Motor Mounting Bracket	Flexible Coupling	Clean Damper
CRK566BKD	OPX-2A		CC05PK5	PAL2P-5	MCS300808	D6CL-8.0F

#### For RS-485 Connection:

CRK Series	Control Module	+	Extension Cable (5m)	Motor Mounting Bracket	Flexible Coupling	Clean Damper
CRK566BKD	OPX-2A		CC05PK5	PAL2P-5	MCS300808	D6CL-8.0F

● The system configuration shown above is an example. Other combinations are available.

Product Number Code

**CRK 5 6 4 A K D - T 10**

① ② ③ ④ ⑤ ⑥ ⑦ ⑧ ⑨

①	Series	<b>CRK Series</b>
②	5: 5-phase	
③	Motor Frame Size	<b>4:</b> 42 mm <b>6:</b> 60 mm
④	Motor Case Length	
⑤	Motor Shaft Type	<b>A:</b> Single shaft <b>B:</b> Double shaft
⑥	Power Supply Input	<b>K:</b> DC24V
⑦	Driver Type	<b>D:</b> Stored data type
⑧	Gearhead Type	<b>None:</b> Standard type <b>T:</b> TH geared type
⑨	Gear Ratio	

**Standard Type** Motor Frame Size **42 mm, 60 mm**

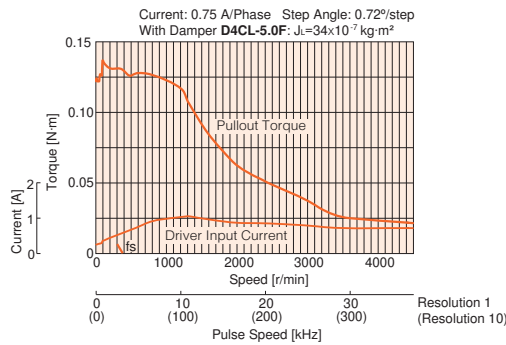
Specifications **(RoHS)**



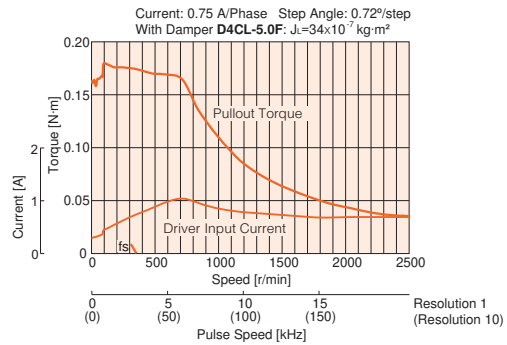
	Single Shaft Double Shaft	CRK543AKD	CRK544AKD	CRK545AKD	CRK564AKD	CRK566AKD	CRK569AKD
		CRK543BKD	CRK544BKD	CRK545BKD	CRK564BKD	CRK566BKD	CRK569BKD
Maximum Holding Torque	N·m	0.13	0.18	0.24	0.42	0.83	1.66
Rotor Inertia	J: kg·m <sup>2</sup>	35x10 <sup>-7</sup>	54x10 <sup>-7</sup>	68x10 <sup>-7</sup>	175x10 <sup>-7</sup>	280x10 <sup>-7</sup>	560x10 <sup>-7</sup>
Rated Current	A/Phase	0.75			1.4		
Basic Step Angle		0.72°					
Power Source		24 VDC±10% 1.4 A			24 VDC±10% 2.5 A		
Excitation Mode		Microstep					
Mass	Motor kg	0.25	0.3	0.4	0.6	0.8	1.3
	Driver kg	0.2					
Dimension No.	Motor	1			2		
	Driver	5					

Speed - Torque Characteristics fs: Starting Frequency

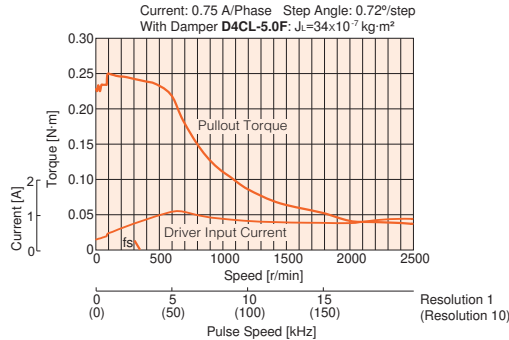
**CRK543AKD/CRK543BKD**



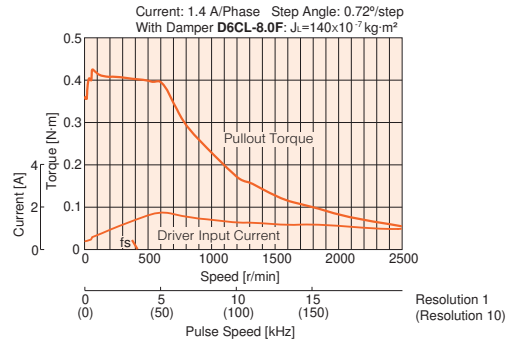
**CRK544AKD/CRK544BKD**



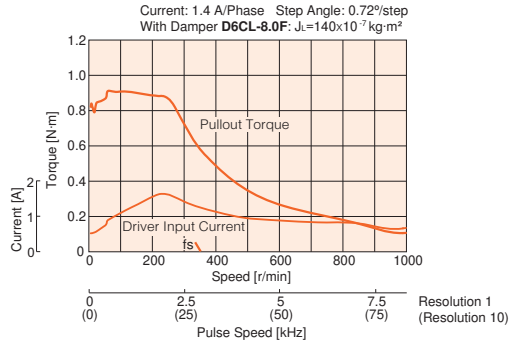
**CRK545AKD/CRK545BKD**



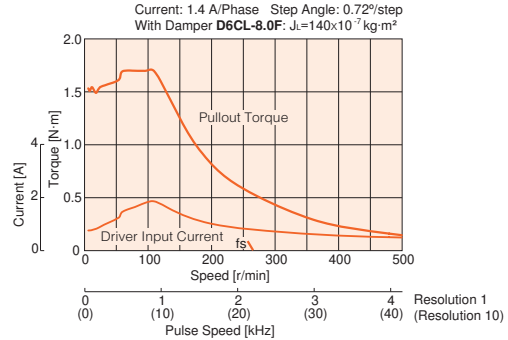
**CRK564AKD/CRK564BKD**



**CRK566AKD/CRK566BKD**



**CRK569AKD/CRK569BKD**



Notes:

- Pay attention to heat dissipation from motor as there will be a considerable amount of heat under certain conditions. Be sure to keep the temperature of the motor case under 100°C.
- The driver's automatic current cutback function at motor standstill reduces maximum holding torque by approximately 50 %.

# TH Geared Type Motor Frame Size 42 mm

● Specifications **RoHS**



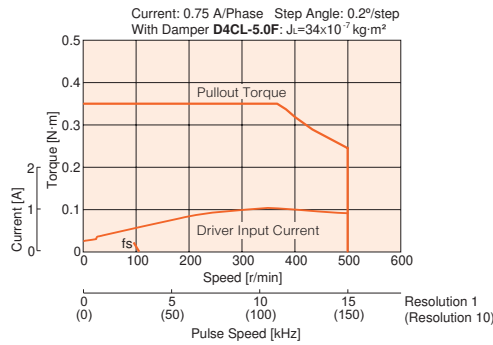
		Single Shaft	CRK543AKD-T3.6	CRK543AKD-T7.2	CRK543AKD-T10	CRK543AKD-T20	CRK543AKD-T30
		Double Shaft	CRK543BKD-T3.6	CRK543BKD-T7.2	CRK543BKD-T10	CRK543BKD-T20	CRK543BKD-T30
Maximum Holding Torque	N·m		0.35	0.7	1	1.5	
Rotor Inertia	J: g·m <sup>2</sup>		35×10 <sup>-7</sup>				
Rated Current	A/Phase		0.75				
Basic Step Angle			0.2°	0.1°	0.072°	0.036°	0.024°
Gear Ratio			1: 3.6	1: 7.2	1: 10	1: 20	1: 30
Permissible Torque	N·m		0.35	0.7	1	1.5	
Backlash	degrees		0.75°	0.417°		0.25°	
Permissible Speed Range	r/min		0~500	0~250	0~180	0~90	0~60
Power Source			24 VDC±10% 1.4 A				
Excitation Mode			Microstep				
Mass	Motor	kg	0.35				
	Driver	kg	0.2				
Dimension No.	Motor		3				
	Driver		5				

Notes:

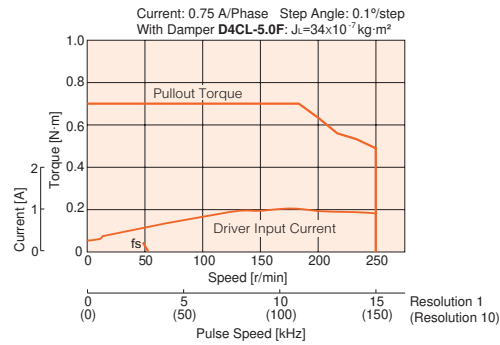
· Direction of rotation of the motor and that of the gear output shaft are the same for the gear ratios 1:3.6, 1:7.2 and 1:10. It is the opposite for 1:20 and 1:30 gear ratios.

## ● Speed - Torque Characteristics fs: Starting Frequency

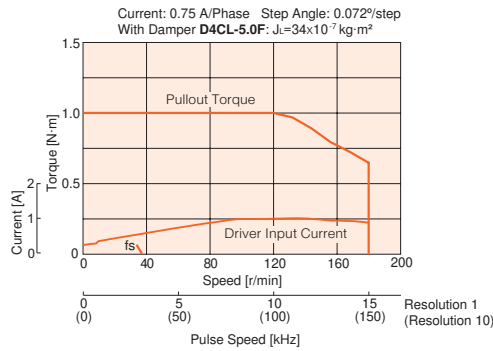
### CRK543AKD-T3.6/CRK543BKD-T3.6



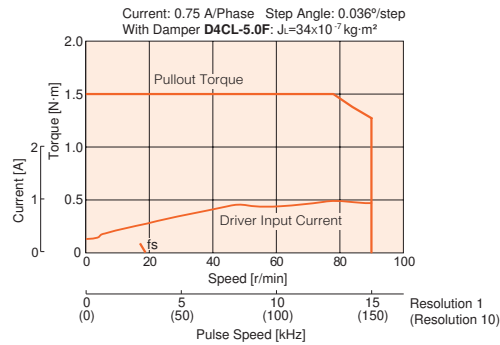
### CRK543AKD-T7.2/CRK543BKD-T7.2



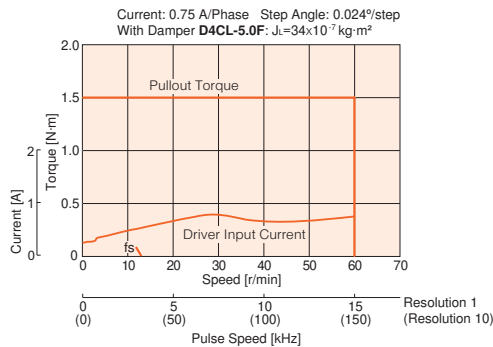
### CRK543AKD-T10/CRK543BKD-T10



### CRK543AKD-T20/CRK543BKD-T20



### CRK543AKD-T30/CRK543BKD-T30



Notes:

· Pay attention to heat dissipation from motor as there will be a considerable amount of heat under certain conditions. Be sure to keep the temperature of the motor case under 100°C.  
· The driver's automatic current cutback function at motor standstill reduces maximum holding torque by approximately 50 %.

# TH Geared Type Motor Frame Size 60 mm

● Specifications **RoHS**



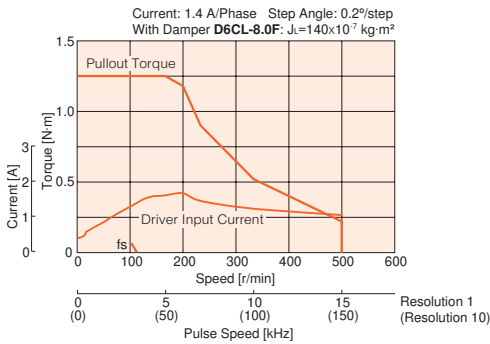
	Single Shaft	CRK564AKD-T3.6	CRK564AKD-T7.2	CRK564AKD-T10	CRK564AKD-T20	CRK564AKD-T30
	Double Shaft	CRK564BKD-T3.6	CRK564BKD-T7.2	CRK564BKD-T10	CRK564BKD-T20	CRK564BKD-T30
Maximum Holding Torque	N·m	1.25	2.5	3	3.5	4
Rotor Inertia	J: g·m <sup>2</sup>	175×10 <sup>-7</sup>				
Rated Current	A/Phase	1.4				
Basic Step Angle		0.2°	0.1°	0.072°	0.036°	0.024°
Gear Ratio		1: 3.6	1: 7.2	1: 10	1: 20	1: 30
Permissible Torque	N·m	1.25	2.5	3	3.5	4
Backlash	degrees	0.584°	0.25°		0.167°	
Permissible Speed Range	r/min	0~500	0~250	0~180	0~90	0~60
Power Source		24 VDC±10% 2.5 A				
Excitation Mode		Microstep				
Mass	Motor	kg				
	Driver	kg				
Dimension No.	Motor	4				
	Driver	5				

Notes:

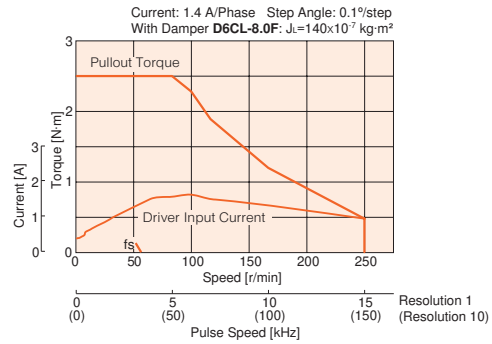
· Direction of rotation of the motor and that of the gear output shaft are the same for the gear ratios 1:3.6, 1:7.2 and 1:10. It is the opposite for 1:20 and 1:30 gear ratios.

## ● Speed - Torque Characteristics fs: Starting Frequency

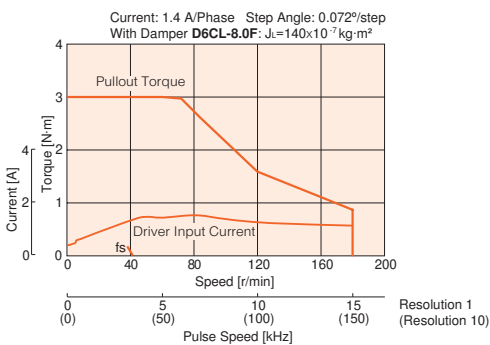
**CRK564AKD-T3.6/CRK564BKD-T3.6**



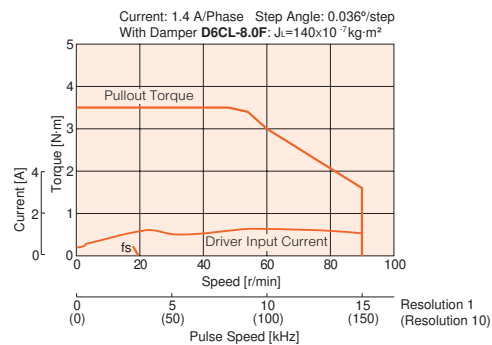
**CRK564AKD-T7.2/CRK564BKD-T7.2**



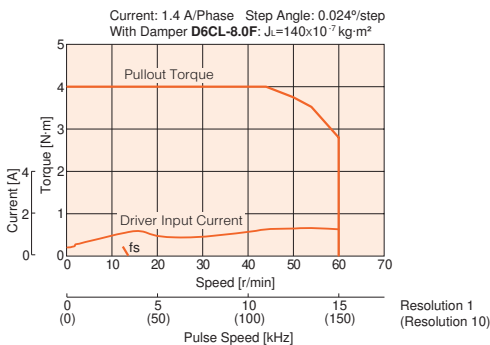
**CRK564AKD-T10/CRK564BKD-T10**



**CRK564AKD-T20/CRK564BKD-T20**



**CRK564AKD-T30/CRK564BKD-T30**



Notes:

· Pay attention to heat dissipation from motor as there will be a considerable amount of heat under certain conditions. Be sure to keep the temperature of the motor case under 100°C.  
 · The driver's automatic current cutback function at motor standstill reduces maximum holding torque by approximately 50 %.



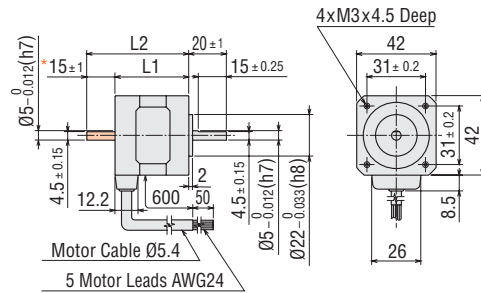
## ■ Dimensions (Unit = mm)

### ● Motor

#### Standard Type

##### 1 □ 42 mm

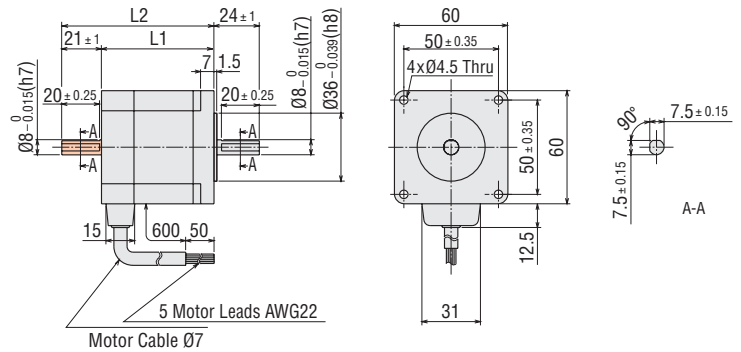
Model	Motor Model	L1	L2	Mass (kg)
<b>CRK543AKD</b>	PK543AW	33	-	0.25
<b>CRK543BKD</b>	PK543BW		48	
<b>CRK544AKD</b>	PK544AW	39	-	0.3
<b>CRK544BKD</b>	PK544BW		54	
<b>CRK545AKD</b>	PK545AW	47	-	0.4
<b>CRK545BKD</b>	PK545BW		62	



\* The length of machining on double shaft model is 15 ± 0.25 mm.

##### 2 □ 60 mm

Model	Motor Model	L1	L2	Mass (kg)
<b>CRK564AKD</b>	PK564AW	48.5	-	0.6
<b>CRK564BKD</b>	PK564BW		69.5	
<b>CRK566AKD</b>	PK566AW	59.5	-	0.8
<b>CRK566BKD</b>	PK566BW		80.5	
<b>CRK569AKD</b>	PK569AW	89	-	1.3
<b>CRK569BKD</b>	PK569BW		110	

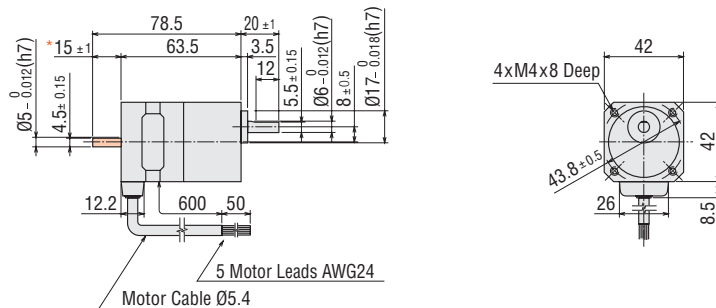


#### TH Geared Type

##### 3 □ 42 mm

Model	Motor Model	Gear Ratio	Mass (kg)
<b>CRK543AKD-T</b> □	PK543AW-T □	<b>3.6, 7.2, 10, 20, 30</b>	0.35
<b>CRK543BKD-T</b> □	PK543BW-T □		

· Enter the gear ratio in the box (□) within the model name.

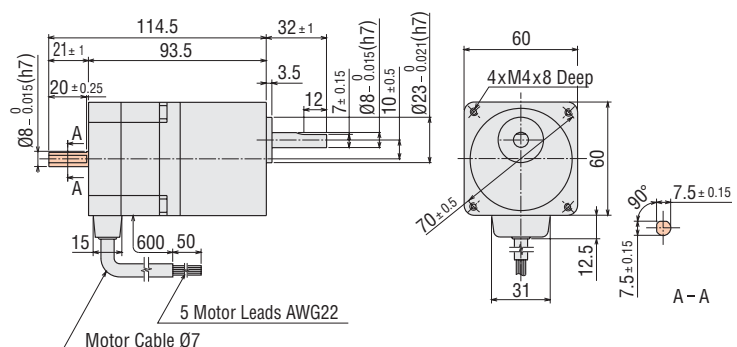


\* The length of machining on double shaft model is 15 ± 0.25 mm.

##### 4 □ 60 mm

Model	Motor Model	Gear Ratio	Mass (kg)
<b>CRK564AKD-T</b> □	PK564AW-T □	<b>3.6, 7.2, 10, 20, 30</b>	0.95
<b>CRK564BKD-T</b> □	PK564BW-T □		

· Enter the gear ratio in the box (□) within the model name.



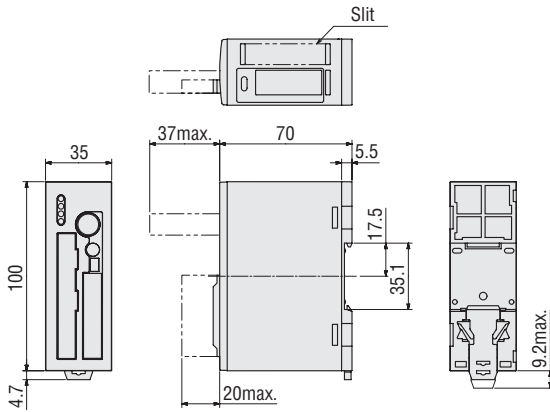
· These dimensions are for double shaft models. For single shaft models, ignore the orange areas.

## ■ Dimensions (Unit = mm)

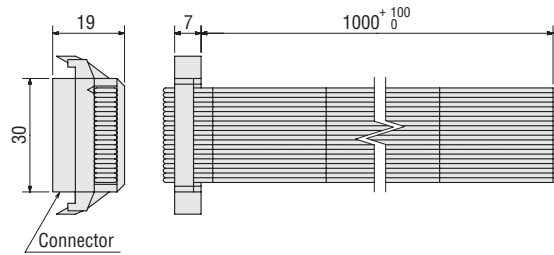
### ● Driver

⑤ Driver Model: CRD507-KD, CRD514-KD

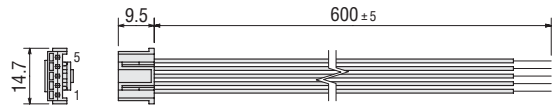
Mass: 0.2 kg



### ● Cable with Connector



### ● Lead Wire with Connector (For Motor Connection)



### Power Supply Connector (CN1)

- Connector: MC1,5/3-STF-3,5 (PHOENIX CONTACT)

### Cable with Connector (CN2, length: 1 m)

- Connector: FX2B-40SA-1.27R (HIROSE Electric)

### Lead Wire with Connector (for motor connection) (CN4, length: 0.6 m)

- Connector Housing: 51103-0500 (MOLEX)
- Contact: 50351-8100 (MOLEX)
- Hand Crimper: 57295-5000 (MOLEX)

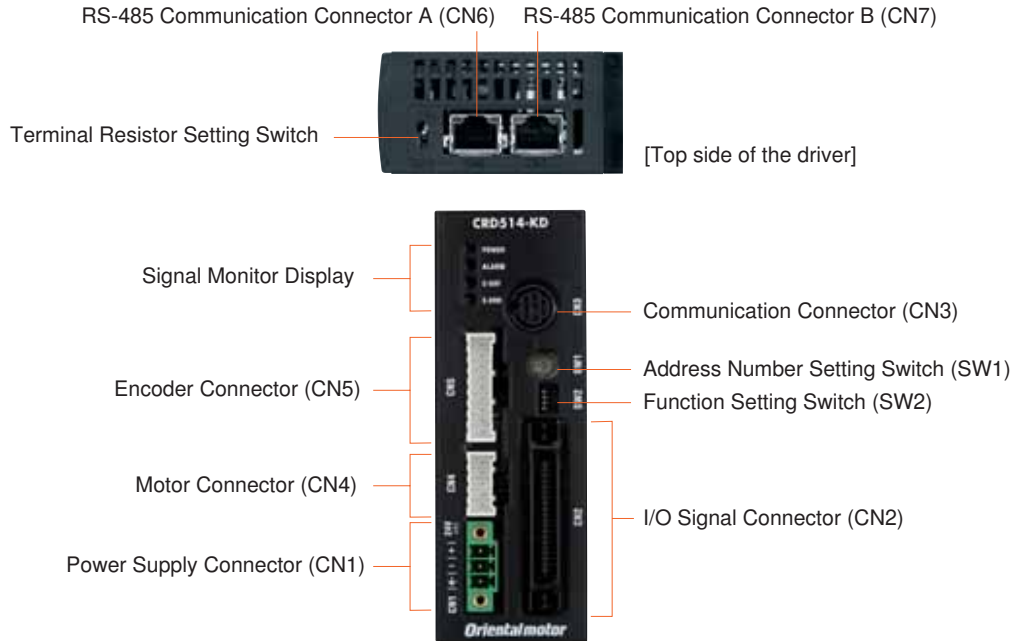
● In case of ordering only the driver for example for repair, the lead wire with connector, the cable with connector and the power supply connector are included.

## ■ Product Line

Type	Motor Frame Size	Model	Motor Model	Driver Model
Standard Type	□ 42 mm	CRK543AKD	PK543AW	CRD507-KD
		CRK543BKD	PK543BW	
		CRK544AKD	PK544AW	
		CRK544BKD	PK544BW	
		CRK545AKD	PK545AW	
	□ 60 mm	CRK545BKD	PK545BW	CRD514-KD
		CRK564AKD	PK564AW	
		CRK564BKD	PK564BW	
		CRK566AKD	PK566AW	
		CRK566BKD	PK566BW	
TH Geared Type	□ 42 mm	CRK543AKD-T3.6	PK543AW-T3.6	CRD507-KD
		CRK543BKD-T3.6	PK543BW-T3.6	
		CRK543AKD-T7.2	PK543AW-T7.2	
		CRK543BKD-T7.2	PK543BW-T7.2	
		CRK543AKD-T10	PK543AW-T10	
		CRK543BKD-T10	PK543BW-T10	
		CRK543AKD-T20	PK543AW-T20	
		CRK543BKD-T20	PK543BW-T20	
		CRK543AKD-T30	PK543AW-T30	
	CRK543BKD-T30	PK543BW-T30		
	□ 60 mm	CRK564AKD-T3.6	PK564AW-T3.6	CRD514-KD
		CRK564BKD-T3.6	PK564BW-T3.6	
		CRK564AKD-T7.2	PK564AW-T7.2	
		CRK564BKD-T7.2	PK564BW-T7.2	
		CRK564AKD-T10	PK564AW-T10	
		CRK564BKD-T10	PK564BW-T10	
		CRK564AKD-T20	PK564AW-T20	
		CRK564BKD-T20	PK564BW-T20	
CRK564AKD-T30		PK564AW-T30		
CRK564BKD-T30	PK564BW-T30			

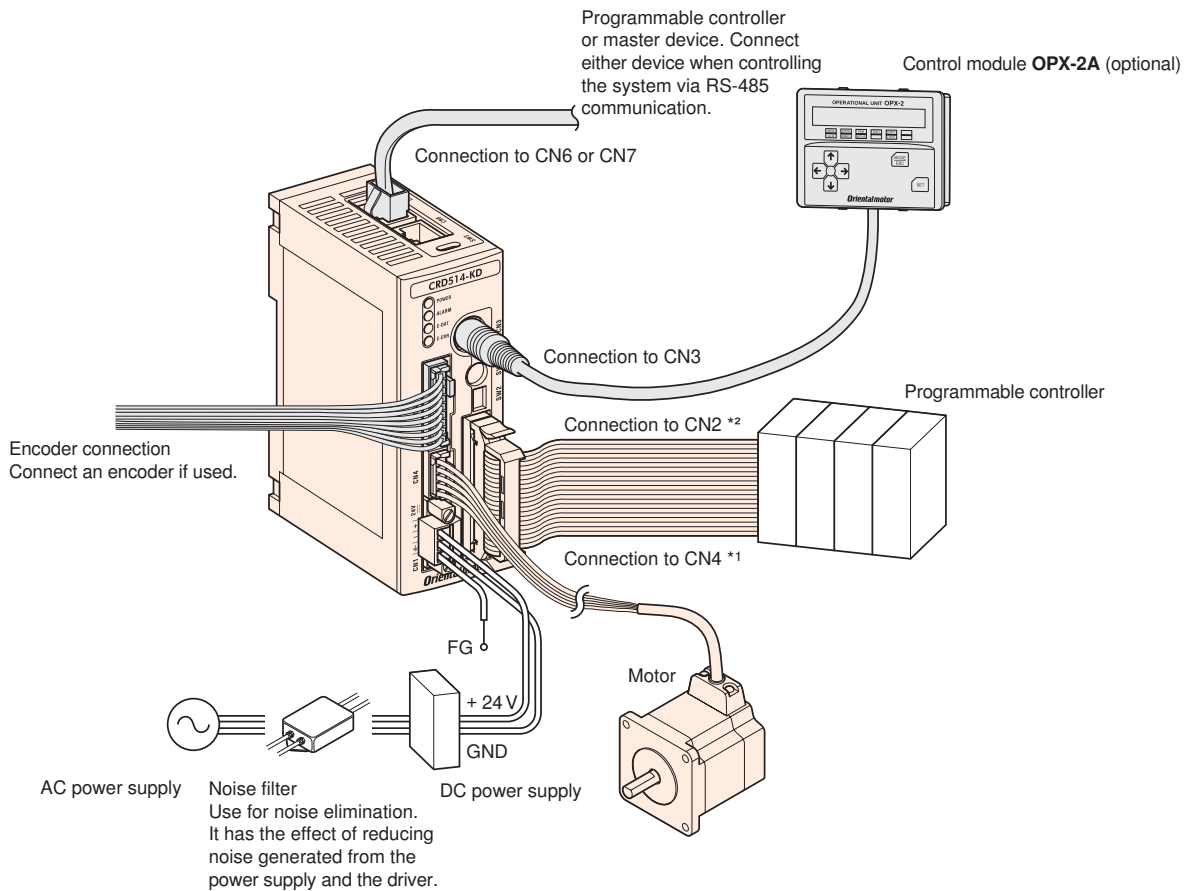
## Connection and Operation

### Names and Functions of Driver Parts



## Connection Diagrams

### Connection to Peripheral Equipment



\*1 When ordering the unit or only the driver the 0.6 m lead wire with connector is included.

\*2 When ordering the unit or only the driver the 1 m cable with connector is included.

## Accessories (Sold separately)

### Control Module (RoHS)

You can change the positioning data, various parameter and you can use it as a monitor.

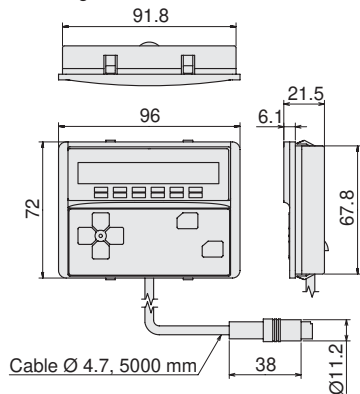
### Product Line

Model
<b>OPX-2A</b>

### Dimensions (Unit = mm)

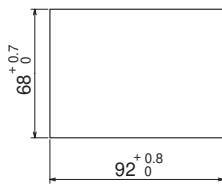
#### Control Module

Mass: 0.25 kg



#### Panel Cut-Out for Control

(Thickness of the mounting plate: 1-3 mm)



### Lead Wire with Connector

#### For Motor Connection

Crimped lead wire for the connection of motor and driver. When ordering a unit, a 0.6 m lead wire with connector is included.

#### For Encoder Connection

Crimped lead wire for the connection of encoder and driver.

#### Product Line

Model	Purpose	Length L (mm)	Conductor AWG
<b>LC5N06B</b>	For motor connection	600	22 (0.3 mm <sup>2</sup> )
<b>LC5N10B</b>		1000	
<b>LC09A-006</b>	For encoder connection	600	



For motor connection



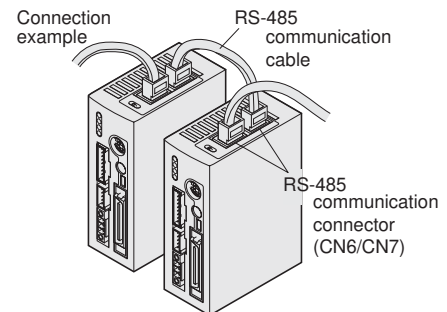
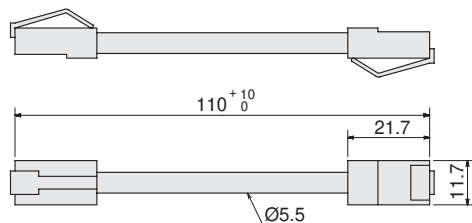
For encoder connection

### RS-485 Communication Cable

Cable to connect the drivers in case of multi-axes operation.

#### Product Line

Model	Length L (m)
<b>CC001-RS4</b>	0.1



· For more Accessories please check on page 5.

This product is manufactured at a plant certified with the international standards **ISO 9001** (for quality assurance) and **ISO 14001** (for systems of environmental management).

Specifications are subject to change without notice.

This catalogue was published in May, 2009.

# Orientalmotor

## ORIENTAL MOTOR (EUROPA) GmbH

www.orientalmotor.de

### European Headquarters and Düsseldorf Office

Schiessstraße 74  
40549 Düsseldorf, Germany  
Tel: 0211-5206700 Fax: 0211-52067099

## ORIENTAL MOTOR (FRANCE) SARL

www.orientalmotor.fr

### France Headquarters

32, Avenue de l'île Saint Martin  
92737 Nanterre Cedex, France  
Tel: 01 47 86 97 50 Fax: 01 47 82 45 16

## ORIENTAL MOTOR (UK) LTD.

www.oriental-motor.co.uk

Unit 5, Faraday Office Park,  
Rankine Road, Basingstoke,  
Hampshire RG24 8AH U.K.  
Tel: 01256-347090 Fax: 01256-347099

## ORIENTAL MOTOR CO., LTD.

www.orientalmotor.co.jp

### Headquarters

16-17, Ueno 6-chome  
Taito-ku, Tokyo 110-8536, Japan  
Tel: (03)3835-0684 Fax: (03)3835-1890

## ORIENTAL MOTOR ITALIA s.r.l.

www.orientalmotor.it

### Italy Headquarters

Via A. De Gasperi, 85  
20017 Mazzo di Rho (MI), Italy  
Tel: 02-93906346 Fax: 02-93906348